STR = mecha.str

[Physics] [/Physics]

[Forces_computation]

[/Forces computation]

[PFD] [/PFD]

[Collisions]

```
; elasticity of collisions car / background, between 0 and 1 elasticity = 0.2
```

```
; solid friction = solid_friction_const + <shock normal impulse> *
solid_friction_coeff
solid_friction_coeff = 0.1
solid_friction_const = 10
```

```
; height of the collision lower plane (0 = the plane is the bounding box lower
plane)
lower_plane_height = 0.0
```

[/Collisions]

; the surfaces must be in the order of their property index (T_Type member of the polygons)

[Surface]

[Surface:tarmac]
grip_coeff = 1.0
[/Surface:tarmac]

[Surface:dusty_tarmac]
[/Surface:dusty_tarmac]

```
[Surface:wet_tarmac]
[/Surface:wet_tarmac]
```

```
[Surface:soaking_tarmac]
[/Surface:soaking_tarmac]
```

[Surface:not smoothed tarmac]

```
grip_coeff = 1.0
[/Surface:not_smoothed_tarmac]
```

[Surface:lightly_snowy_tarmac]
[/Surface:lightly_snowy_tarmac]

[Surface:very_snowy_tarmac]
[/Surface:very_snowy_tarmac]

[Surface:grass] [/Surface:grass]

[Surface:scrubland] [/Surface:scrubland]

[Surface:soil]
[/Surface:soil]

[Surface:bushy] [/Surface:bushy]

[Surface:shoulder] [/Surface:shoulder]

[Surface:snow]
[/Surface:snow]

[Surface:ice] [/Surface:ice] [/Surface]