

**serial**

COLLABORATORS

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# Chapter 1

## serial

### 1.1 serial.doc

AbortIO()	CMD_FLUSH	CMD_WRITE
BeginIO()	CMD_READ	OpenDevice()
CloseDevice()	CMD_RESET	SDCMD_QUERY
CMD_BREAK	CMD_START	SDCMD_SETPARAMS
CMD_CLEAR	CMD_STOP	

### 1.2 serial.device/AbortIO

#### NAME

AbortIO(ioRequest) -- abort an I/O request  
A1

#### FUNCTION

This is an exec.library call.

This function attempts to aborts a specified read or write request. If the request is active, it is stopped immediately. If the request is queued, it is painlessly removed. The request will be returned in the same way any completed request it.

After AbortIO(), you must generally do a WaitIO().

#### INPUTS

ioRequest -- pointer to the IORequest Block that is to be aborted.

#### RESULTS

io\_Error -- if the Abort succeeded, then io\_Error will be #IOERR\_ABORTED

(-2) and the request will be flagged as aborted (bit 5 of io\_Flags is set). If the Abort failed, then the Error will be zero.

#### BUGS

Previous to version 34, the serial.device would often hang when aborting CTS/RTS handshake requests. This was the cause of the

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incorrect assumption that `AbortIO()` does not need to be followed by a wait for a reply (or a `WaitIO()`).

## 1.3 serial.device/BeginIO

### NAME

`BeginIO(ioRequest),deviceNode` -- start up an I/O process  
A1                    A6

### FUNCTION

This is a direct function call to the device. It is intended for more advanced programmers. See `exec's DoIO()` and `SendIO()` for the normal method of calling devices.

This function initiates a I/O request made to the serial device. Other than read or write, the functions are performed synchronously, and do not depend on any interrupt handling logic (or it's associated discontinuities), and hence should be performed as `IO_QUICK`.

With some exceptions, reads and writes are merely initiated by `BeginIO`, and thusly return to the caller as begun, not completed. Completion is signalled via the standard `ReplyMsg` routine.

Multiple requests are handled via FIFO queueing.

One exception to this non-`QUICK` handling of reads and writes is for `READS` when:

- `IO_QUICK` bit is set
- There are no pending read requests
- There is already enough data in the input buffer to satisfy this I/O Request immediately.

In this case, the `IO_QUICK` flag is not cleared, and the request is completed by the time it returns to the caller. There is no `ReplyMsg` or signal bit activity in this case.

### INPUTS

`ioRequest` -- pointer to an I/O Request Block of size `io_ExtSerSize` (see `serial.i` for size/definition), containing a valid command in `io_Command` to process, as well as the command's other required parameters.  
`deviceNode` -- pointer to the "serial.device", as found in the `IO_DEVICE` of the `ioRequest`.

### RESULTS

`io_Error` -- if the `BeginIO` succeeded, then Error will be null.  
If the `BeginIO` failed, then the Error will be non-zero.  
I/O errors won't be reported until the io completes.

### SEE ALSO

`devices/serial.h`

## 1.4 serial.device/CloseDevice

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## NAME

CloseDevice -- close the serial port

## SYNOPSIS

```
CloseDevice(deviceNode)
           A1
```

## FUNCTION

This is an exec call that terminates communication with the serial device. Upon closing, the device's input buffer is freed.

Note that all IORequests MUST be complete before closing.

If any are pending, your program must AbortIO() then WaitIO() to complete them.

## INPUTS

deviceNode - pointer to the device node, set by Open

## SEE ALSO

serial.device/OpenDevice

## 1.5 serial.device/CMD\_BREAK

## NAME

Break -- send a break signal over the serial line

## FUNCTION

This command sends a break signal (serial line held low for an extended period) out the serial port. This is accomplished by setting the UARTBRK bit of reg ADKCON. After a duration (user specifiable via setparams, default 250000 microseconds) the bit is reset and the signal discontinued. If the QUEUEDBRK bit of io\_SerFlags is set in the io\_Request block, the request is placed at the back of the write-request queue and executed in turn. If the QUEUEDBRK bit is not set, the break is started immediately, control returns to the caller, and the timer discontinues the signal after the duration is completed. Be aware that calling BREAK may affect other commands such as ABORT, FLUSH, STOP, START, etc...

## IO REQUEST

io_Message	mn_ReplyPort initialized
io_Device	set by OpenDevice
io_Unit	set by OpenDevice
io_Command	SDCMD_BREAK
io_Flags	set/reset IO_QUICK per above description

## RESULTS

Error -- if the Break succeeded, then Error will be null.

If the Break failed, then the Error will be non-zero.

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## 1.6 serial.device/CMD\_CLEAR

### NAME

Clear -- clear the serial port buffers

### FUNCTION

This command resets the serial port's read buffer pointers.

### IO REQUEST

io_Message	mn_ReplyPort initialized
io_Device	set by OpenDevice
io_Unit	set by OpenDevice
io_Command	CMD_CLEAR

### RESULTS

Error -- If the Clear succeeded, then io\_Error will be null.  
If the Clear failed, then the io\_Error will be non-zero.

## 1.7 serial.device/CMD\_FLUSH

### NAME

Flush -- clear all queued I/O requests for the serial port

### FUNCTION

This command purges the read and write request queues for the serial device. Flush will not affect active requests.

### IO REQUEST

io_Message	mn_ReplyPort initialized
io_Device	set by OpenDevice
io_Unit	set by OpenDevice
io_Command	CMD_FLUSH

### RESULTS

Error -- if the Flush succeeded, then io\_Error will be null.  
If the Flush failed, then the io\_Error will be non-zero.

## 1.8 serial.device/CMD\_READ

### NAME

Read -- read input from serial port

### FUNCTION

This command causes a stream of characters to be read in from the serial port buffer. The number of characters is specified in io\_Length.

The Query function can be used to check how many characters are currently waiting in the serial port buffer. If more characters are requested than are currently available, the ioRequest will be queued until it can be satisfied.

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The best way to handle reads is to first Query to get the number of characters currently in the buffer. Then post a read request for that number of characters (or the maximum size of your buffer).

If zero characters are in the buffer, post a request for 1 character. When at least one is ready, the device will return it. Now start over with another Query.

Before the program exits, it must be sure to AbortIO() then WaitIO() any outstanding ioRequests.

#### IO REQUEST

io_Message	A mn_ReplyPort is required
io_Device	set by OpenDevice
io_Unit	set by OpenDevice
io_Command	CMD_READ
io_Flags	If the IOB_QUICK bit is set, read will try to complete the IO quickly
io_Length	number of characters to receive.
io_Data	pointer to buffer

#### RESULTS

Error -- if the Read succeeded, then io\_Error will be null.  
If the Read failed, then io\_Error will be non-zero.  
io\_Error will indicate problems such as parity mismatch, break, and buffer overrun.

#### SEE ALSO

serial.device/CMD\_QUERY  
serial.device/SDCMD\_SETPARAMS

#### BUGS

Having multiple outstanding read IORequests at any one time will probably fail.

Old documentation mentioned a mode where io\_Length was set to -1. If you want a NULL terminated read, use the io\_TermArray instead.

## 1.9 serial.device/CMD\_RESET

#### NAME

Reset -- reinitializes the serial port

#### FUNCTION

This command resets the serial port to its freshly initialized condition. It aborts all I/O requests both queued and current, relinquishes the current buffer, obtains a new default sized buffer, and sets the port's flags and parameters to their boot-up time default values. The functions places the reset parameter values in the ioRequest block.

#### IO REQUEST

io_Message	mn_ReplyPort initialized
io_Device	set by OpenDevice



io_Unit	set by OpenDevice
io_Command	CMD_RESET

**RESULTS**

Error -- if the Reset succeeded, then Error will be null.  
If the Reset failed, then the Error will be non-zero.

## 1.10 serial.device/CMD\_START

**NAME**

Start -- restart paused I/O over the serial port

**FUNCTION**

This function restarts all current I/O on the serial port by sending an xON to the "other side", and submitting a "logical xON" to "our side", if/when appropriate to current activity.

**IO REQUEST**

io_Message	mn_ReplyPort initialized
io_Device	set by OpenDevice
io_Unit	set by OpenDevice
io_Command	CMD_START

**RESULTS****SEE ALSO**

serial.device/CMD\_STOP

## 1.11 serial.device/CMD\_STOP

**NAME**

Stop -- pause all current I/O over the serial port

**FUNCTION**

This command halts all current I/O on the serial port by sending an xOFF to the "other side", and submitting a "logical xOFF" to "our side", if/when appropriate to current activity.

**IO REQUEST**

io_Message	mn_ReplyPort initialized
io_Device	set by OpenDevice
io_Unit	set by OpenDevice
io_Command	CMD_STOP

**RESULTS****SEE ALSO**

serial.device/CMD\_START

## 1.12 serial.device/CMD\_WRITE

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## NAME

Write -- send output to serial port

## FUNCTION

This command causes a stream of characters to be written out the serial port. The number of characters is specified in `io_Length`, unless `-1` is used, in which case output is sent until a null(0x00) is encountered.

## IO REQUEST

<code>io_Message</code>	must have <code>mn_ReplyPort</code> initialized
<code>io_Device</code>	set by <code>OpenDevice</code>
<code>io_Unit</code>	set by <code>OpenDevice</code>
<code>io_Command</code>	<code>CMD_WRITE</code>
<code>io_Flags</code>	Set <code>IOF_QUICK</code> to try quick I/O
<code>io_Length</code>	number of characters to transmit, or if set to <code>-1</code> transmit until null encountered in buffer
<code>io_Data</code>	pointer to block of data to transmit

## RESULTS

Error -- if the Write succeeded, then `io_Error` will be null.  
If the Write failed, then the `io_Error` will be non-zero.

## SEE ALSO

`serial.device/SDCMD_SETPARAMS`

## 1.13 serial.device/OpenDevice

## NAME

`OpenDevice` -- Request an opening of the serial device.

## SYNOPSIS

```
error = OpenDevice(SERIALNAME, unit, ioRequest, flags)
D0          A0          D0      A1          D0
```

## FUNCTION

This is an exec call. Exec will search for the `serial.device`, and if found, will pass this call on to the device.

Unless the shared-access bit (bit 5 of `io_SerFlags`) is set, exclusive use is granted and no other access to that unit is allowed until the owner closes it. All the serial-specific fields in the `ioRequest` are initialized to their most recent values (or the Preferences default, for the first time open).

If support of 7-wire handshaking (i.e. RS232-C CTS/RTS protocol) is required, set the `7WIRE` bit in `io_SerFlags` before opening the serial device.

## INPUTS

<code>SERIALNAME</code>	- pointer to literal string "serial.device"
<code>unit</code>	- Must be zero, or a user setable unit number. (This field is used by multiple port controllers) Zero specifies the built-in serial port.

ioRequest - pointer to an ioRequest block of size io\_ExtSerSize to be initialized by the serial.device.  
 (see devices/serial.h for the definition)  
 NOTE use of io\_SerFlags (see FUNCTION above)  
 IMPORTANT: The ioRequest block MUST be of size io\_ExtSerSize !  
 flags - Must be zero for future compatibility

#### RESULTS

D0 - same as io\_Error  
 io\_Error - If the Open succeeded, then io\_Error will be null.  
 If the Open failed, then io\_Error will be non-zero.  
 io\_Device - A pointer to whatever device will handle the calls for this unit. This pointer may be different depending on what unit is requested.

#### BUGS

If 7-wire handshaking is specified, this enables a timeout "feature".  
 If the device holds off the computer for more than about 30-60 seconds, the device will return the write request with the error SerErr\_TimerErr. Don't depend on this, however. If you want a timeout, set up the timer.device and wait for either timer, or serial IO to complete.

On open, the serial.device allocates the misc.resource for the serial port. It does not return it until the serial.device is expunged from memory. It should return it when no more openers exist.

#### SEE ALSO

serial.device/CloseDevice  
 devices/serial.h

## 1.14 serial.device/SDCMD\_QUERY

#### NAME

Query -- query serial port/line status

#### FUNCTION

This command return the status of the serial port lines and registers. The number of unread bytes in the serial device's read buffer is shown in io\_Actual.

The break send & received flags are cleared by a query, and whenever a read IORequest is returned with a error in io\_Error.

#### IO REQUEST

io\_Message mn\_ReplyPort initialized  
 io\_Device preset by OpenDevice  
 io\_Unit preset by OpenDevice  
 io\_Command SDCMD\_QUERY

#### RESULTS

io\_Status BIT ACTIVE FUNCTION

LSB	0	---	reserved
	1	---	reserved
	2	high	parallel "sel" on the A1000 On the A500 & A2000, "sel" is also connected to the serial port's "Ring Indicator". Be cautious when making cables.
	3	low	Data Set Ready
	4	low	Clear To Send
	5	low	Carrier Detect
	6	low	Ready To Send
MSB	7	low	Data Terminal Ready
	8	high	hardware overrun
	9	high	break sent (most recent output)
	10	high	break received (as latest input)
	11	high	transmit x-OFFed
	12	high	receive x-OFFed
	13-15	---	reserved

`io_Actual`            set to count of unread input characters

`io_Error` -- Query will always succeeded.

## 1.15 serial.device/SDCMD\_SETPARAMS

### NAME

`SetParams` -- change parameters for the serial port

### FUNCTION

This command allows the caller to change parameters for the serial device. Except for xON-xOFF enable/disable, it will reject a setparams call if any reads or writes are active or pending.

Note specifically:

1. Valid input for `io_Baud` is between 112 and 292000 baud inclusive; asynchronous i/o above 32KB (especially on a busy system) may be ambitious.
2. The EOFMODE and QUEUEDBRK bits of `io_SerFlags` can be set/reset in the `io_Rqst` block without a call to `SetParams`. The SHARED and 7WIRE bits of `io_SerFlags` can be used in `OpenDevice` calls. ALL OTHER PARAMETERS CAN ONLY BE CHANGED BY THE `SetParams` COMMAND.
3. `RBufLen` must be at least 64.
4. If not used, `io_ExtFlags` MUST be set to zero.
5. xON-xOFF is by default enabled. The XDISABLED bit is the only parameter that can be changed via a `SetParams` call while the device is active. Note that this will return the value `SerErr_DevBusy` in the `io_Error` field.

xON/xOFF handshaking is inappropriate for certain binary transfer protocols, such as Xmodem. The binary data might contain the xON (ASCII 17) and xOFF (ASCII 19) characters.

6. If trying to run MIDI, you should set the RAD\_BOOGIE bit of io\_SerFlags to eliminate unneeded overhead. Specifically, this skips checks for parity, x-OFF handling, character lengths other than 8 bits, and testing for a break signal. Setting RAD\_BOOGIE will also set the XDISABLED bit.

Note that writing data (that's already in MIDI format) at MIDI rates is easily accomplished. Using this driver alone for MIDI reads may, however, may not be reliable, due to MIDI timestamping requirements, and possibility of overruns in a busy multitasking and/or display intensive environment.

7. If you select mark or space parity (see io\_ExtFlags in serial.h), this will cause the SERB\_PARTY\_ON bit to be set, and the setting of SERB\_PARTY\_ODD to be ignored.

8. For best results, set the RAD\_BOOGIE flag whenever possible. See #6 for details.

9. Note that at this time parity is \*not\* calculated for the xON-xOFF characters. If you have a system that is picky about the parity of these, you must set your own xON-xOFF characters in io\_CtlChar.

#### IO REQUEST

io_Message	mn_ReplyPort initialized
io_Device	preset by OpenDevice
io_Unit	preset by OpenDevice
io_Command	SDCMD_SETPARAMS (0x0B)
	NOTE that the following fields are filled in by Open to reflect the serial device's current configuration.
io_CtlChar	a longword containing byte values for the xON,xOFF,INQ,ACK fields (respectively) (INQ/ACK not used at this time)
io_RBufLen	length in bytes of input buffer
	NOTE that any change in buffer size causes the current buffer to be deallocated and a new, correctly sized one to be allocated. Thusly, the CONTENTS OF THE OLD BUFFER ARE LOST.
io_ExtFlags	additional serial flags (bitdefs in devices/serial.h) mark & space parity may be specified here.
io_Baud	baud rate for reads AND writes. (See 1 above)
io_BrkTime	duration of break signal in MICROseconds
io_TermArray	ASCII descending-ordered 8-byte array of termination characters. If less than 8 chars used, fill out array w/lowest valid value. Terminators are checked only if EOFMODE bit of io_Serflags is set. (e.g. x512F040303030303 )
io_ReadLen	number of bits in read word (1-8) not including parity
io_WriteLen	number of bits in write word (1-8) " " "
io_StopBits	number of stop bits (0, 1 or 2)
io_SerFlags	see devices/serial.h for bit equates, NOTE that x00 yields exclusive access, xON/OFF-enabled, no parity checking, 3-wire protocol and TermArray inactive.

#### RESULTS

Error -- if the SetParams succeeded, then Error will be null.  
If the SetParams failed, then the Error will be non-zero.

#### SEE ALSO

exec/OpenDevice

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