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asyncio/SeekAsync                                asyncio/SeekAsync

NAME
    SeekAsync -- set the current position for reading or writing within
                an async file.

SYNOPSIS
    oldPosition = SeekAsync(file, position, mode);

    LONG SeekAsync(struct AsyncFile *, LONG, BYTE);

FUNCTION
    SeekAsync() sets the read/write cursor for the file 'file' to the
    position 'position'. This position is used by the various read/write
    functions as the place to start reading or writing. The result is the
    current absolute position in the file, or -1 if an error occurs, in
    which case dos.library/IOErr() can be used to find more information.
    'mode' can be SEEK_START, SEEK_CURRENT or SEEK_END. It is used to
    specify the relative start position. For example, 20 from current
    is a position 20 bytes forward from current, -20 is 20 bytes back
    from current.

    To find out what the current position within a file is, simply seek
    zero from current.

INPUTS
    file - an opened async file, as obtained from OpenAsync()
    position - the place where to move the read/write cursor
    mode - the mode for the position, one of SEEK_START, SEEK_CURRENT,
          or SEEK_END.

RESULT
    oldPosition - the previous position of the read/write cursor, or -1
                  if an error occurs. In case of error, dos.library/IOErr()
                  can give more information.

SEE ALSO
    OpenAsync(), CloseAsync(), ReadAsync(), WriteAsync(),
    dos.library/Seek()
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ASyncIO.c

```
/* ASyncIO.c - Execute me to compile with SAS/C 5.10b
sc data=near nominc strmer streq nostchk saved ign=73 ASyncIO.c
;lc -cist -v -j73 asyncio.c
quit */

#include <exec/types.h>
#include <exec/memory.h>
#include <dos/dos.h>
#include <dos/dosextens.h>
#include <clib/exec_protos.h>
#include <clib/dos_protos.h>

#include <pragmas/exec_pragmas.h>
#include <pragmas/dos_pragmas.h>

#include "asyncio.h"

/*****

extern struct Library *DOSBase;
extern struct Library *SysBase;

/*****

/* this macro lets us long-align structures on the stack */
#define D_S(type,name) char a_##name[sizeof(type)+3]; \
                        type *name = (type *) ((LONG) (a_##name+3) & ~3);

/*****/
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/* send out an async packet to the file system. */
static VOID SendPacket(struct AsyncFile *file, APTR arg2)
{
    file->af_Packet.sp_Pkt.dp_Port = &file->af_PacketPort;
    file->af_Packet.sp_Pkt.dp_Arg2 = (LONG) arg2;
    PutMsg(file->af_Handler, &file->af_Packet.sp_Msg);
    file->af_PacketPending = TRUE;
}

/*****

/* this function waits for a packet to come back from the file system. If no
* packet is pending, state from the previous packet is returned. This ensures
* that once an error occurs, it state is maintained for the rest of the life
* of the file handle.
*
* This function also deals with IO errors, bringing up the needed DOS
* requesters to let the user retry an operation or cancel it.
*/
static LONG WaitPacket(struct AsyncFile *file)
{
    LONG bytes;

    if (file->af_PacketPending)
    {
        /* mark packet as no longer pending since we are going to get it */
        file->af_PacketPending = FALSE;

        while (TRUE)
        {
            /* This enables signalling when a packet comes back to the port */
            file->af_PacketPort.mp_Flags = PA_SIGNAL;

            /* Wait for the packet to come back, and remove it from the message
            * list. Since we know no other packets can come in to the port, we can
            * safely use Remove() instead of GetMsg(). If other packets could come in,
            * we would have to use GetMsg(), which correctly arbitrates access in such
            * a case
            */
            Remove((struct Node *)WaitPort(&file->af_PacketPort));

            /* set the port type back to PA_IGNORE so we won't be bothered with
            * spurious signals
            */
            file->af_PacketPort.mp_Flags = PA_IGNORE;

            bytes = file->af_Packet.sp_Pkt.dp_Res1;
            if (bytes >= 0)
            {
                /* packet didn't report an error, so bye... */
                return(bytes);
            }

            /* see if the user wants to try again... */
            if (ErrorReport(file->af_Packet.sp_Pkt.dp_Res2,
                           REPORT_STREAM,
                           file->af_File, NULL))
                return(-1);

            /* user wants to try again, resend the packet */
            SendPacket(file, file->af_Buffers[file->af_CurrentBuf]);
        }

        /* last packet's error code, or 0 if packet was never sent */
        SetIOErr(file->af_Packet.sp_Pkt.dp_Res2);

        return(file->af_Packet.sp_Pkt.dp_Res1);
    }
}

/*****

/* this function puts the packet back on the message list of our
* message port.
*/
static VOID RequeuePacket(struct AsyncFile *file)
{

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    AddHead(&file->af_PacketPort.mp_MsgList, &file->af_Packet.sp_Msg.mn_Node);
    file->af_PacketPending = TRUE;
}

/*****

/* this function records a failure from a synchronous DOS call into the
* packet so that it gets picked up by the other IO routines in this module
*/
VOID RecordSyncFailure(struct AsyncFile *file)
{
    file->af_Packet.sp_Pkt.dp_Res1 = -1;
    file->af_Packet.sp_Pkt.dp_Res2 = IOErr();
}

/*****

struct AsyncFile *OpenAsync(const STRPTR fileName, UBYTE accessMode, LONG bufferSize)
{
    struct AsyncFile *file;
    struct FileHandle *fh;
    BPTR handle;
    BPTR lock;
    LONG blockSize;
    D_S(struct InfoData, infoData);

    handle = NULL;
    file = NULL;
    lock = NULL;

    if (accessMode == MODE_READ)
    {
        if (handle = Open(fileName, MODE_OLDFILE))
            lock = DupLockFromFH(handle);
    }
    else
    {
        if (accessMode == MODE_WRITE)
        {
            handle = Open(fileName, MODE_NEWFILE);
        }
        else if (accessMode == MODE_APPEND)
        {
            /* in append mode, we open for writing, and then seek to the
            * end of the file. That way, the initial write will happen at
            * the end of the file, thus extending it
            */

            if (handle = Open(fileName, MODE_READWRITE))
            {
                if (Seek(handle, 0, OFFSET_END) < 0)
                {
                    Close(handle);
                    handle = NULL;
                }
            }

            /* we want a lock on the same device as where the file is. We can't
            * use DupLockFromFH() for a write-mode file though. So we get sneaky
            * and get a lock on the parent of the file
            */
            if (handle)
                lock = ParentOfFH(handle);
        }
    }

    if (handle)
    {
        /* if it was possible to obtain a lock on the same device as the
        * file we're working on, get the block size of that device and
        * round up our buffer size to be a multiple of the block size.
        * This maximizes DMA efficiency.
        */

        blockSize = 512;
        if (lock)
        {

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    if (Info(lock, infoData))
    {
        blockSize = infoData->id_BytesPerBlock;
        bufferSize =
            ((bufferSize + blockSize - 1) / blockSize) * blockSize * 2;
    }
    UnLock(lock);
}

/* now allocate the ASyncFile structure, as well as the read buffers.
* Add 15 bytes to the total size in order to allow for later
* quad-longword alignment of the buffers
*/

if (file = AllocVec(sizeof(struct AsyncFile) + bufferSize + 15, MEMF_ANY))
{
    file->af_File = handle;
    file->af_ReadMode = (accessMode == MODE_READ);
    file->af_BlockSize = blockSize;

    /* initialize the ASyncFile structure. We do as much as we can here,
    * in order to avoid doing it in more critical sections
    *
    * Note how the two buffers used are quad-longword aligned. This
    * helps performance on 68040 systems with copyback cache. Aligning
    * the data avoids a nasty side-effect of the 040 caches on DMA.
    * Not aligning the data causes the device driver to have to do
    * some magic to avoid the cache problem. This magic will generally
    * involve flushing the CPU caches. This is very costly on an 040.
    * Aligning things avoids the need for magic, at the cost of at
    * most 15 bytes of ram.
    */

    fh = BADDR(file->af_File);
    file->af_Handler = fh->fh_Type;
    file->af_BufferSize = bufferSize / 2;
    file->af_Buffers[0]
        = (APTR) (((ULONG) file + sizeof(struct AsyncFile) + 15) & 0xfffffff0);
    file->af_Buffers[1]
        = (APTR) ((ULONG) file->af_Buffers[0] + file->af_BufferSize);
    file->af_Offset = file->af_Buffers[0];
    file->af_CurrentBuf = 0;
    file->af_SeekOffset = 0;
    file->af_PacketPending = FALSE;

    /* this is the port used to get the packets we send out back.
    * It is initialized to PA_IGNORE, which means that no signal is
    * generated when a message comes in to the port. The signal bit
    * number is initialized to SIGB_SINGLE, which is the special bit
    * that can be used for one-shot signalling. The signal will never
    * be set, since the port is of type PA_IGNORE. We'll change the
    * type of the port later on to PA_SIGNAL whenever we need to wait
    * for a message to come in.
    *
    * The trick used here avoids the need to allocate an extra signal
    * bit for the port. It is quite efficient.
    */

    file->af_PacketPort.mp_MsgList.lh_Head
        = (struct Node *) &file->af_PacketPort.mp_MsgList.lh_Tail;
    file->af_PacketPort.mp_MsgList.lh_Tail = NULL;
    file->af_PacketPort.mp_MsgList.lh_TailPred
        = (struct Node *) &file->af_PacketPort.mp_MsgList.lh_Head;
    file->af_PacketPort.mp_Node.ln_Type = NT_MSGPORT;
    file->af_PacketPort.mp_Flags = PA_IGNORE;
    file->af_PacketPort.mp_SigBit = SIGB_SINGLE;
    file->af_PacketPort.mp_SigTask = FindTask(NULL);

    file->af_Packet.sp_Pkt.dp_Link = &file->af_Packet.sp_Msg;
    file->af_Packet.sp_Pkt.dp_Arg1 = fh->fh_Arg1;
    file->af_Packet.sp_Pkt.dp_Arg3 = file->af_BufferSize;
    file->af_Packet.sp_Pkt.dp_Res1 = 0;
    file->af_Packet.sp_Pkt.dp_Res2 = 0;
    file->af_Packet.sp_Msg.mn_Node.ln_Name = (STRPTR) &file->af_Packet.sp_Pkt;
    file->af_Packet.sp_Msg.mn_Node.ln_Type = NT_MESSAGE;
    file->af_Packet.sp_Msg.mn_Length = sizeof(struct StandardPacket);

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        if (accessMode == MODE_READ)
        {
            /* if we are in read mode, send out the first read packet to
             * the file system. While the application is getting ready to
             * read data, the file system will happily fill in this buffer
             * with DMA transfers, so that by the time the application
             * needs the data, it will be in the buffer waiting
             */

            file->af_Packet.sp_Pkt.dp_Type = ACTION_READ;
            file->af_BytesLeft = 0;
            if (file->af_Handler)
                SendPacket(file, file->af_Buffers[0]);
        }
        else
        {
            file->af_Packet.sp_Pkt.dp_Type = ACTION_WRITE;
            file->af_BytesLeft = file->af_BufferSize;
        }
    }
    else
    {
        Close(handle);
    }
}

return(file);
}

/*****
LONG CloseAsync(struct AsyncFile *file)
{
    LONG result;

    if (file)
    {
        result = WaitPacket(file);
        if (result >= 0)
        {
            if (!file->af_ReadMode)
            {
                /* this will flush out any pending data in the write buffer */
                result = Write(file->af_File,
                             file->af_Buffers[file->af_CurrentBuf],
                             file->af_BufferSize - file->af_BytesLeft);
            }

            Close(file->af_File);
            FreeVec(file);
        }
        else
        {
            SetIoErr(ERROR_INVALID_LOCK);
            result = -1;
        }
    }

    return(result);
}

/*****
LONG ReadAsync(struct AsyncFile *file, APTR buffer, LONG numBytes)
{
    LONG totalBytes;
    LONG bytesArrived;

    totalBytes = 0;

    /* if we need more bytes than there are in the current buffer, enter the
     * read loop
     */

    while (numBytes > file->af_BytesLeft)
    {
        /* drain buffer */
        CopyMem(file->af_Offset, buffer, file->af_BytesLeft);

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        numBytes -= file->af_BytesLeft;
        buffer = (APTR)((ULONG)buffer + file->af_BytesLeft);
        totalBytes += file->af_BytesLeft;
        file->af_BytesLeft = 0;

        bytesArrived = WaitPacket(file);
        if (bytesArrived <= 0)
        {
            if (bytesArrived == 0)
                return(totalBytes);

            return(-1);
        }

        /* ask that the buffer be filled */
        SendPacket(file, file->af_Buffers[1-file->af_CurrentBuf]);

        if (file->af_SeekOffset > bytesArrived)
            file->af_SeekOffset = bytesArrived;

        file->af_Offset = (APTR)((ULONG)file->af_Buffers[file->af_CurrentBuf]
                                + file->af_SeekOffset);
        file->af_CurrentBuf = 1 - file->af_CurrentBuf;
        file->af_BytesLeft = bytesArrived - file->af_SeekOffset;
        file->af_SeekOffset = 0;
    }

    CopyMem(file->af_Offset, buffer, numBytes);
    file->af_BytesLeft -= numBytes;
    file->af_Offset = (APTR)((ULONG)file->af_Offset + numBytes);

    return (totalBytes + numBytes);
}

/*****
LONG ReadCharAsync(struct AsyncFile *file)
{
    unsigned char ch;

    if (file->af_BytesLeft)
    {
        /* if there is at least a byte left in the current buffer, get it
         * directly. Also update all counters
         */

        ch = *(char *)file->af_Offset;
        file->af_BytesLeft--;
        file->af_Offset = (APTR)((ULONG)file->af_Offset + 1);

        return((LONG)ch);
    }

    /* there were no characters in the current buffer, so call the main read
     * routine. This has the effect of sending a request to the file system to
     * have the current buffer refilled. After that request is done, the
     * character is extracted for the alternate buffer, which at that point
     * becomes the "current" buffer
     */

    if (ReadAsync(file, &ch, 1) > 0)
        return((LONG)ch);

    /* We couldn't read above, so fail */

    return(-1);
}

/*****
LONG WriteAsync(struct AsyncFile *file, APTR buffer, LONG numBytes)
{
    LONG totalBytes;

    totalBytes = 0;

    while (numBytes > file->af_BytesLeft)
    {

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        /* this takes care of NIL: */
        if (!file->af_Handler)
        {
            file->af_Offset = file->af_Buffers[0];
            file->af_BytesLeft = file->af_BufferSize;
            return(numBytes);
        }

        if (file->af_BytesLeft)
        {
            CopyMem(buffer, file->af_Offset, file->af_BytesLeft);

            numBytes -= file->af_BytesLeft;
            buffer = (APTR)((ULONG)buffer + file->af_BytesLeft);
            totalBytes += file->af_BytesLeft;
        }

        if (WaitPacket(file) < 0)
            return(-1);

        /* send the current buffer out to disk */
        SendPacket(file, file->af_Buffers[file->af_CurrentBuf]);

        file->af_CurrentBuf = 1 - file->af_CurrentBuf;
        file->af_Offset = file->af_Buffers[file->af_CurrentBuf];
        file->af_BytesLeft = file->af_BufferSize;
    }

    CopyMem(buffer, file->af_Offset, numBytes);
    file->af_BytesLeft -= numBytes;
    file->af_Offset = (APTR)((ULONG)file->af_Offset + numBytes);

    return (totalBytes + numBytes);
}

/*****
LONG WriteCharAsync(struct AsyncFile *file, UBYTE ch)
{
    if (file->af_BytesLeft)
    {
        /* if there's any room left in the current buffer, directly write
         * the byte into it, updating counters and stuff.
         */

        *(UBYTE *)file->af_Offset = ch;
        file->af_BytesLeft--;
        file->af_Offset = (APTR)((ULONG)file->af_Offset + 1);

        /* one byte written */
        return(1);
    }

    /* there was no room in the current buffer, so call the main write
     * routine. This will effectively send the current buffer out to disk,
     * wait for the other buffer to come back, and then put the byte into
     * it.
     */

    return(WriteAsync(file, &ch, 1));
}

/*****
LONG SeekAsync(struct AsyncFile *file, LONG position, BYTE mode)
{
    LONG current, target;
    LONG minBuf, maxBuf;
    LONG bytesArrived;
    LONG diff;
    LONG filePos;
    LONG roundTarget;
    D_S(struct FileInfoBlock, fib);

    bytesArrived = WaitPacket(file);

    if (bytesArrived < 0)
        return(-1);
}

/*****

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if (file->af_ReadMode)
{
    /* figure out what the actual file position is */
    filePos = Seek(file->af_File, OFFSET_CURRENT, 0);
    if (filePos < 0)
    {
        RecordSyncFailure(file);
        return(-1);
    }

    /* figure out what the caller's file position is */
    current = filePos - (file->af_BytesLeft+bytesArrived);

    /* figure out the absolute offset within the file where we must seek to */
    if (mode == MODE_CURRENT)
    {
        target = current + position;
    }
    else if (mode == MODE_START)
    {
        target = position;
    }
    else /* if (mode == MODE_END) */
    {
        if (!ExamineFH(file->af_File, fib))
        {
            RecordSyncFailure(file);
            return(-1);
        }

        target = fib->fib_Size + position;
    }

    /* figure out what range of the file is currently in our buffers */
    minBuf = current - (LONG)((ULONG)file->af_Offset -
                               (ULONG)file->af_Buffers[1 - file->af_CurrentBuf]);
    maxBuf = current + file->af_BytesLeft
              + bytesArrived; /* WARNING: this is one too big */

    diff = target - current;

    if ((target < minBuf) || (target >= maxBuf))
    {
        /* the target seek location isn't currently in our buffers, so
         * move the actual file pointer to the desired location, and then
         * restart the async read thing...
         */

        /* this is to keep our file reading block-aligned on the device.
         * block-aligned reads are generally quite a bit faster, so it is
         * worth the trouble to keep things aligned
         */
        roundTarget = (target / file->af_BlockSize) * file->af_BlockSize;

        if (Seek(file->af_File, roundTarget-filePos, OFFSET_CURRENT) < 0)
        {
            RecordSyncFailure(file);
            return(-1);
        }

        SendPacket(file, file->af_Buffers[0]);

        file->af_SeekOffset = target-roundTarget;
        file->af_BytesLeft = 0;
        file->af_CurrentBuf = 0;
    }
    else if ((target < current) || (diff <= file->af_BytesLeft))
    {
        /* one of the two following things is true:
         *
         * 1. The target seek location is within the current read buffer,
         *    but before the current location within the buffer. Move back
         *    within the buffer and pretend we never got the pending packet,
         *    just to make life easier, and faster, in the read routine.
         *
         * 2. The target seek location is ahead within the current
         *    read buffer. Advance to that location. As above, pretend to

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        * have never received the pending packet.
        */

    RequeuePacket(file);

    file->af_BytesLeft -= diff;
    file->af_Offset = (APTR)((ULONG)file->af_Offset + diff);
}
else
{
    /* at this point, we know the target seek location is within
     * the buffer filled in by the packet that we just received
     * at the start of this function. Throw away all the bytes in the
     * current buffer, send a packet out to get the async thing going
     * again, readjust buffer pointers to the seek location, and return
     * with a grin on your face... :-)
     */

    diff -= file->af_BytesLeft;

    SendPacket(file, file->af_Buffers[1-file->af_CurrentBuf]);

    file->af_Offset
        = (APTR)((ULONG)file->af_Buffers[file->af_CurrentBuf] + diff);
    file->af_CurrentBuf = 1 - file->af_CurrentBuf;
    file->af_BytesLeft = bytesArrived - diff;
}
}
else
{
    if (Write(file->af_File,
              file->af_Buffers[file->af_CurrentBuf],
              file->af_BufferSize - file->af_BytesLeft) < 0)
    {
        RecordSyncFailure(file);
        return(-1);
    }

    /* this will unfortunately generally result in non block-aligned file
     * access. We could be sneaky and try to resync our file pos at a
     * later time, but we won't bother. Seeking in write-only files is
     * relatively rare (except when writing IFF files with unknown chunk
     * sizes, where the chunk size has to be written after the chunk data)
     */

    current = Seek(file->af_File, position, mode);

    if (current < 0)
    {
        RecordSyncFailure(file);
        return(-1);
    }

    file->af_BytesLeft = file->af_BufferSize;
    file->af_CurrentBuf = 0;
}

return(current);
}

```

ASyncIO.h

```

#ifndef ASYNCIO_H
#define ASYNCIO_H

/*****

#ifndef EXEC_TYPES_H
#include <exec/types.h>
#endif

#ifndef EXEC_PORTS_H
#include <exec/ports.h>
#endif

#ifndef DOS_DOS_H
#include <dōs/dōs.h>
#endif

/*****

/* This structure is public only by necessity, don't muck with it yourself, or
 * you're looking for trouble
 */
struct AsyncFile
{
    BPTR                af_File;
    ULONG               af_BlockSize;
    struct MsgPort      *af_Handler;
    APTR                af_Offset;
    LONG               af_BytesLeft;
    ULONG               af_BufferSize;
    APTR                af_Buffers[2];
    struct StandardPacket af_Packet;
    struct MsgPort      af_PacketPort;
    ULONG               af_CurrentBuf;
    ULONG               af_SeekOffset;
    UBYTE               af_PacketPending;
    UBYTE               af_ReadMode;
};

/*****

#define MODE_READ    0 /* read an existing file */
#define MODE_WRITE   1 /* create a new file, delete existing file if needed */
#define MODE_APPEND  2 /* append to end of existing file, or create new */

#define MODE_START   -1 /* relative to start of file */
#define MODE_CURRENT  0 /* relative to current file position */
#define MODE_END      1 /* relative to end of file */

/*****

struct AsyncFile *OpenAsync(const STRPTR fileName, UBYTE accessMode, LONG bufferSize);
LONG CloseAsync(struct AsyncFile *file);
LONG ReadAsync(struct AsyncFile *file, APTR buffer, LONG numBytes);
LONG ReadCharAsync(struct AsyncFile *file);
LONG WriteAsync(struct AsyncFile *file, APTR buffer, LONG numBytes);
LONG WriteCharAsync(struct AsyncFile *file, UBYTE ch);
LONG SeekAsync(struct AsyncFile *file, LONG position, BYTE mode);

/*****

#endif /* ASYNCIO_H */

```