Let us consider

an infinite, perfect field k, where, if $p := \operatorname{char}(k) \neq 0$, it is possible to extract pth roots,

the algebraic closure k of k,

the polynomial ring $\mathcal{P} := k[X_1, \ldots, X_n],$

its k-basis $\mathcal{T} := \{X_1^{a_1} \cdots X_n^{a_n} : (a_1, \dots, a_n) \in \mathbb{N}^n\};$

an ideal $\mathsf{I} := (F) := \mathbb{I}(F) := \{\sum_{i=1}^{u} h_i f_i : h_i \in \mathcal{P}\} \subset \mathcal{P}$ given by

a finite basis $F := \{f_1, \ldots, f_u\} \subset \mathcal{P},$

the algebraic affine variety $\mathcal{Z}(\mathsf{I}) := \{\mathsf{a} \in \mathsf{k}^n : f(\mathsf{a}) = 0, \text{ for each } f \in F\} \subset \mathsf{k}^n.$

Each polynomial $f \in k[X_1, \ldots, X_n]$ is therefore a unique linear combination

$$f = \sum_{t \in \mathcal{T}} c(f, t) t$$

of the terms $t \in \mathcal{T}$ with coefficients c(f, t) in k; the support

$$\operatorname{supp}(f) := \{t \in \mathcal{T} : c(f, t) \neq 0\}$$

of f being finite, once a term ordering < on T is fixed, f has a unique representation as an ordered linear combination of terms:

$$f = \sum_{i=1}^{s} c(f, t_i) t_i : c(f, t_i) \in k \setminus 0, t_i \in \mathcal{T}, t_1 > \dots > t_s;$$

the maximal term of f is $\mathbf{T}(f) := t_1$, its leading coefficient is $lc(f) := c(f, t_1)$ and its maximal monomial is $\mathbf{M}(f) := c(f, t_1)t_1$.

For any set $F \subset \mathcal{P}$ we denote

- $\mathbf{T}_{<}\{F\} := \{\mathbf{T}(f) : f \in F\};$
- $\mathbf{T}_{<}(F) := \{ \tau \mathbf{T}(f) : \tau \in \mathcal{T}, f \in F \};$
- $\mathbf{N}_{\leq}(F) := \mathcal{T} \setminus \mathbf{T}_{\leq}(F);$

•
$$k[\mathbf{N}_{\leq}(F)] := \operatorname{Span}_{k}(\mathbf{N}_{\leq}(F))$$

and we will usually omit the dependence on < if there is no ambiguity.

Let us fix any term-ordering < on \mathcal{T} and let us compute a Gröbner basis $G \subset I$ of I w.r.t. <. Then it holds

- $\bullet \ \mathcal{Z}(\mathsf{I}) = \emptyset \iff 1 \in \mathsf{I} \iff 1 \in G;$
- $\mathcal{Z}(I)$ is infinite iff $\mathbf{N}(I)$ is an infinite dimensional k-vector space iff there exists i such that for each $d \in \mathbb{N} : X_i^d \notin \mathbf{T}(G) = T(I);$
- $\mathcal{Z}(\mathsf{I})$ is finite iff $\mathbf{N}(\mathsf{I})$ is finite iff for each *i* there exists $d_i \in \mathbb{N} : X_i^{d_i} \in \mathbf{T}\{G\} \subset \mathbf{T}(\mathsf{I})$; moreover, in this case and under the assumption that I is radical, we have $\#\mathcal{Z}(\mathsf{I}) = \#\mathbf{N}(\mathsf{I})$.

Definition. Let $\mathcal{P} := k[X_1, \ldots, X_n]$ and let $\mathfrak{f} \subset \mathcal{P}$ be an ideal.

A subset $\{X_{i_1}, \ldots, X_{i_d}\}$ of d variables for which it holds

$$\mathfrak{f} \cap k[X_{i_1}, \dots, X_{i_d}] = (0)$$

is called a set of independent variables for \mathfrak{f} .

If, for each $j \notin \{i_1, \ldots, i_d\}$ it holds

$$\mathfrak{f} \cap k[X_{i_1}, \dots, X_{i_d}, X_j] \neq (0)$$

 $\{X_{i_1}, \ldots, X_{i_d}\}$ is called a maximal set of independent variables.

Lemma (Kredel–Weispfenning). Let

$$\mathfrak{f} \subset k[X_1,\ldots,X_n]$$

be an ideal, < be any termordering and $\mathbf{T}_{<}(\mathfrak{f})$ the corresponding monomial ideal. If $\{X_{i_1}, \ldots, X_{i_d}\}$ is a set of variables such that $\mathbf{T}_{<}(\mathfrak{f}) \cap k[X_{i_1}, \ldots, X_{i_d}] = \emptyset$ then $\mathfrak{f} \cap k[X_{i_1}, \ldots, X_{i_d}] = (0)$.

Proof. If exists $f \in \mathfrak{f} \cap k[X_{i_1}, \ldots, X_{i_d}], f \neq 0$, then $\mathbf{T}_{<}(f) \in \mathbf{T}_{<}(\mathfrak{f}) \cap k[X_{i_1}, \ldots, X_{i_d}]$.

Corollary (Kredel–Weispfenning). Let $\mathfrak{f} \subset k[X_1, \ldots, X_n]$ be an ideal, < be any termordering and $\mathbf{T}_{<}(\mathfrak{f})$ the corresponding monomial ideal.

Let $\{X_{i_1}, \ldots, X_{i_d}\}$ be a maximal set of independent variables for $\sqrt{\mathbf{T}_{\leq}(\mathfrak{f})}$; then

- $\dim(\mathfrak{f}) = d$,
- $\{X_{i_1}, \ldots, X_{i_d}\}$ is a maximal set of independent variables for f.

Proof. One has dim $(\sqrt{\mathbf{T}_{<}(\mathfrak{f})}) = \dim(\mathbf{T}_{<}(\mathfrak{f}))$ and $\{X_{i_1}, \ldots, X_{i_d}\}$ is a maximal set of independent variables for $\sqrt{\mathbf{T}_{<}(\mathfrak{f})}$ iff it is a maximal set of independent variables for $\mathbf{T}_{<}(\sqrt{\mathfrak{f}})$.

Then, by the lemma above, $\{X_{i_1}, \ldots, X_{i_d}\}$ is a set of independent variables for \mathfrak{f} , and it is also maximal because $\dim(\mathbf{T}_{<}(\mathfrak{f})) = \dim(\mathfrak{f})$ since they share the same Hilbert polynomial.

Then, we can re-enumerate and re-label the variables as

$$\{X_1, \dots, X_n\} = \{V_1, \dots, V_d, Z_1, \dots, Z_r\}, \quad \{X_{i_1}, \dots, X_{i_d}\} = \{V_1, \dots, V_d\},\$$

so that

$$\mathsf{I} \cap k[V_1, \dots, V_d] = (0)$$

and consider

the field $K := k(V_1, \ldots, V_d),$

its algebraic closure K

the polynomial ring $\mathcal{Q} := K[Z_1, \ldots, Z_r],$

its K-basis $\mathcal{W} := \{Z_1^{a_1} \cdots Z_r^{a_r} : (a_1, \dots, a_r) \in \mathbb{N}^r\};$

the zero-dimensional ideal $J := I^e := IK[Z_1, \dots, Z_r]$

and the unmixed ideal $\mathsf{J}^c := \mathsf{J} \cap \mathcal{P}$.

Then, if $I = \bigcap_{i=1}^{t} \mathfrak{q}_i$ denotes any irredundant primary representation in \mathcal{P} , and we wlog assume that the primaries are ordedered so that, for a suitable value $1 \leq r \leq t$,

 $\{X_{i_1},\ldots,X_{i_d}\}$ is a maximal set of independent variables for $\mathfrak{q}_i \iff i \leq \mathsf{r}$,

then

$$\mathsf{J} := \mathsf{I}^e = \bigcap_{i=1}^{\mathsf{r}} \mathfrak{q}_i^e = \bigcap_{i=1}^{\mathsf{r}} \mathfrak{q}_i \mathcal{Q}$$

is an irredundant primary representation in \mathcal{Q} and

$$\mathsf{J}\cap\mathcal{P}=:\mathsf{J}^c=\mathsf{I}^{ec}=igcap_{i=1}^\mathsf{r}\mathfrak{q}_i\subset\mathcal{P}$$

is an irredundant primary representation.

Moreover, the (GTZ, ARGH, CCC)-schemes allow to compute unmixed ideals $\mathfrak{a}_i \subset \mathcal{P}$ giving a decomposition

$$\sqrt{\mathsf{I}} = \sqrt{\mathsf{J}^c} \bigcap \left(\bigcap_j \sqrt{\mathfrak{a}_j}\right).$$

Thus solving the ideal $I \subset \mathcal{P}$ is reduced, via Gröbner technique, to solving each unmixed (GTZ, ARGH, CCC)component and solving each such component is reduced to solving the related zero-dimensional extension ideal.

Trinks' Algorithm

Thus we are reduced to consider a zero-dimensional ideal

$$\mathsf{J} \subset \mathcal{Q} := K[Z_1, \ldots, Z_r]$$

which we assume to be given via a Gröbner basis G_{\prec} w.r.t. the lexicographical ordering \prec induced on \mathcal{W} by $Z_1 \prec Z_2 \prec \cdots \prec Z_r$:

$$Z_1^{a_1} \dots Z_r^{a_r} \prec Z_1^{b_1} \dots Z_r^{b_r} \iff \text{ exists } j: a_j < b_j \text{ and } a_i = b_i \text{ for } i > j_i$$

Corollary. If $I \subset k[X_1, \ldots, X_n]$ is an ideal and G is a Gröbner basis of I w.r.t. the lexicographical ordering \prec then for each $i, 1 \leq i \leq n$, $G_i := G \cap k[X_1, \ldots, X_i]$ is a Gröbner basis of $I \cap k[X_1, \ldots, X_i]$.

Then, if we denote, for $i, 1 \leq i < r$,

 $\mathsf{J}_i := \mathsf{J} \cap K[Z_1, \ldots, Z_i],$

 $\pi_i: \mathsf{K}^r \to \mathsf{K}^i$ the canonical projection $\pi_i(a_1, \ldots, a_r) = (a_1, \ldots, a_i),$

 $G_i := G_{\prec} \cap K[Z_1, \dots, Z_i],$

we have, for each i

- 1. $\mathcal{Z}(\mathsf{J}_i) = \pi_i(\mathcal{Z}(\mathsf{J})) = \{(a_1, \dots, a_i) : (a_1, \dots, a_r) \in \mathcal{Z}(\mathsf{J})\},\$
- 2. G_i is the reduced lexicographical Gröbner basis of J_i .

In particular, there is a unique polynomial $f(Z_1) \in K[Z_1]$, such that

 $J_1 = (f) \text{ and } \{f\} = G_{\prec} \cap K[Z_1].$

For each $\alpha := (a_1, \ldots, a_{i-1}) \in \mathsf{K}^{i-1}$, denote $\Phi_\alpha : K[Z_1, \ldots, Z_i] \to \mathsf{K}[T]$ the projection defined by

 $\Phi_{\alpha}(f) = f(a_1, \dots, a_{i-1}, T) \text{ for each } f \in K[Z_1, \dots, Z_i].$

Theorem (Trinks). Let $\alpha := (a_1, \ldots, a_{i-1}) \in \mathcal{Z}(\mathsf{J}_{i-1})$ and let $f \in \mathsf{K}[T]$ be a generator of the principal ideal $\Phi_{\alpha}(\mathsf{J}_i) \subset \mathsf{K}[T]$. Then, for each $b \in \mathsf{K}$

 $(a_1,\ldots,a_{i-1},b) \in \mathcal{Z}(\mathsf{J}_i) \iff f(b) = 0.$

Proof. Let $h(Z_1, \ldots, Z_i) \in \mathsf{J}_i$ be any polynomial such that

$$f(T) = \Phi_{\alpha}(h) = h(a_1, \dots, a_{i-1}, T).$$

Then

$$(a_1,\ldots,a_{i-1},b)\in \mathcal{Z}(\mathsf{J}_i)\implies f(b)=h(a_1,\ldots,a_{i-1},b)=0.$$

Conversely for any $g(Z_1, \ldots, Z_i) \in \mathsf{J}_i, \ \Phi_\alpha(g) \in \Phi_\alpha(\mathsf{J}_i)$, so that

$$g(a_1,\ldots,a_{i-1},b) = \Phi_{\alpha}(g)(b) = 0$$
 for each $g \in \mathsf{J}_i$

and $(a_1, \ldots, a_{i-1}, b) \in \mathcal{Z}(\mathsf{J}_i)$.

Figure 1: Trinks' Algorithm

Z := Solve(F, L)

where

 $F := (f_1, \dots, f_u) \subset \mathcal{Q} := K[Z_1, \dots, Z_r],$ $L \supset K \text{ is a field extension of } K,$ $\mathsf{J} \subset \mathcal{Q} \text{ is the zero-dimensional ideal generated by } F,$

$$\mathsf{Z} := \{\alpha_1, \ldots, \alpha_{\mathsf{s}}\} = \mathcal{Z}(\mathsf{J}) \cap L^r.$$

Compute the reduced lexicographical Gröbner basis G of (f_1, \ldots, f_u) .

Let $p(Z_1)$ be the unique element in $G \cap K[Z_1]$,

$$\mathsf{Z}_1 := \{ a \in L : p(a) = 0 \}.$$

For
$$i = 2..r$$
 do

$$Z_{i} := \emptyset;$$
For each $(a_{1}, \dots, a_{i-1}) \in Z_{i-1}$ do

$$H := \{g(a_{1}, \dots, a_{i-1}, Z_{i}) : g \in G_{i} \setminus G_{i-1}\},$$

$$p := \gcd(H),$$

$$Z := \{a \in L : p(a) = 0\},$$

$$Z_{i} := Z_{i} \cup \{(a_{1}, \dots, a_{i-1}, a) : a \in Z\}.$$

$$Z := Z_r$$

Gianni–Kalkbrener Algorithm

Remarking that each polynomial $f \in K[Z_1, \ldots, Z_i]$ can be uniquely expressed as

$$f = \sum_{j=0}^{D} h_j(Z_1, \dots, Z_{i-1}) Z_i^j, h_D \neq 0,$$

we recall that the degree of f in the variable Z_i is denoted $\deg_{Z_i}(f) := \deg_i(f) := D$, and that $\operatorname{Lp}(f) := h_d$ is named the *leading polynomial* of f, while $Tp(f) = h_0$ the trailing polynomial of f. Observe that, for the lexicographical ordering \prec , we have $\mathbf{T}(f) = \mathbf{T}(\operatorname{Lp}(f))Z_i^{\deg_i(f)}$.

We also denote, for each $i, 1 \leq i \leq r, \delta \in \mathbb{N}$,

$$G_i := \{g \in G, g \in K[Z_1, \dots, Z_i]\}$$

$$G_{i\delta} := \{g \in G, g \in K[Z_1, \dots, Z_i], \deg_i(g) \le \delta\}$$

and remark that each $G_{i\delta}$ is a section of both $G_{i\delta+1}$ and G_i and that hold the obvious inclusions

$$G_{11} \subseteq G_{12} \subseteq \ldots \subseteq G_1 \subseteq \ldots \subseteq G_{i-1} \subseteq \ldots \subseteq G_{i\delta} \subseteq G_{i\delta+1} \subseteq \ldots \subseteq G_i \subseteq \ldots$$

For each $i, 1 \leq i \leq r, \delta \in \mathbb{N}$, and each $F \subset \mathcal{Q}$, we denote

$$\operatorname{Lp}_{i\delta}(F) := \{\operatorname{Lp}(g), g \in F \cap K[Z_1, \dots, Z_i], \deg_i(g) \le \delta\}.$$

Theorem (Gianni–Kalkbrener). Let $J \subset Q$ be an ideal, \prec be the lexicographical ordering induced by $Z_1 \prec \cdots \prec Z_r$. Let $G := \{g_1, \ldots, g_v\}$ be a Gröbner basis of J w.r.t. \prec , enumerated in such a way that

$$\mathbf{T}(g_1) \prec \mathbf{T}(g_2) \prec \ldots \prec \mathbf{T}(g_{v-1}) \prec \mathbf{T}(g_v).$$

Then with the notation above:

- 1. for each $i, i \leq r$, G_i is a Gröbner basis of J_i ;
- 2. for each $i, 1 \leq i \leq r, \delta \in \mathbb{N}$, $\operatorname{Lp}_{i\delta}(G)$ is a Gröbner basis of $\operatorname{Lp}_{i\delta}(\mathsf{J})$;
- 3. for each $i, 1 \leq i \leq r$ and each $\alpha := (b_1, \ldots, b_{i-1}) \in \mathcal{Z}(\mathsf{J}_{i-1})$, denoting

 $\Phi_{\alpha}: \mathcal{Q} \to K[Z_i, \dots, Z_n] \quad f(Z) \to f(\alpha, Z_i, \dots, Z_n).$

- σ the minimal value such that $\Phi_{\alpha}(\operatorname{Lp}(g_{\sigma})) \neq 0$ and
- j, δ the value such that $g_{\sigma} \in G_{j\delta}$ so that

$$g_{\sigma} = \operatorname{Lp}(g_{\sigma})Z_{j}^{\delta+1} + \dots \in K[Z_{1}, \dots, Z_{j}] \setminus K[Z_{1}, \dots, Z_{j-1}]$$

it holds

(a)
$$j = i$$
,
(b) for each $g \in G_{i-1}, \Phi_{\alpha}(g) = 0$,
(c) for each $g \in G_{i\delta}, \Phi_{\alpha}(g) = 0$,
(d) $\Phi_{\alpha}(g_{\sigma}) = \gcd(\Phi_{\alpha}(g) : g \in G_i) \in \mathsf{K}[Z_i]$,
(e) for each $b \in \mathsf{K}$,
 $(b_1, \dots, b_{i-1}, b) \in \mathcal{Z}(\mathsf{J}_i) \iff \Phi_{\alpha}(g_{\sigma})(b) = 0$.

Z := Solve(F, L)

where

 $F := (f_1, \dots, f_u) \subset \mathcal{Q} := K[Z_1, \dots, Z_r],$ $L \supset K \text{ is a field extension of } K,$

 $J \subset \mathcal{Q}$ is the zero-dimensional ideal generated by F,

 $\mathsf{Z} := \{\alpha_1, \dots, \alpha_{\mathsf{s}}\} = \mathcal{Z}(\mathsf{J}) \cap L^r.$

Compute the reduced lexicographical Gröbner basis G of (f_1, \ldots, f_u) .

Sort $G := \{g_1, \ldots, g_v\}$ by increasing maximal terms.

$$\mathsf{Z}_1 := \{ a \in L : g_1(a) = 0 \},\$$

%% g_1 is the unique element in $G \cap K[Z_1]$.

For
$$i = 2..r$$
 do

$$Z_{i} := \emptyset;$$

$$g := \min(g \in G_{i} \setminus G_{i-1}).$$

For each $(a_{1}, \dots, a_{i-1}) \in Z_{i-1}$ do

$$h := g,$$

While $Lp(h)(a_{1}, \dots, a_{i-1}) = 0$ do $h := Next(h, G),$

$$p := h(a_{1}, \dots, a_{i-1}, Z_{i}),$$

 $\%\% p = gcd(H)$ for $H := \{g(a_{1}, \dots, a_{i-1}, Z_{i}) : g \in G_{i} \setminus G_{i-1}\},$

$$Z := \{a \in L : p(a) = 0\},$$

$$Z_{i} := Z_{i} \cup \{(a_{1}, \dots, a_{i-1}, a) : a \in Z\}.$$

$$Z := Z_{r}$$

Endomorphisms of an Algebra

Let $\mathcal{Q} := K[Z_1, \ldots, Z_r]$, \mathcal{W} its monomial K-basis and K the algebraic closure of K. In order to simplify the notation let us wlog assume K = K to be algebraically closed.

Let $J \subset Q$ be a zero-dimensional ideal, $\deg(J) = s$, and A := Q/J the corresponding quotient algebra, which satisfies $\dim_K(A) = s$.

For any $f \in \mathcal{Q}$, we will denote $[f] \in A$ its residue class modulo J and Φ_f the endomorphism $\Phi_f : A \to A$ defined by

$$\Phi_f([g]) = [fg]$$
 for each $[g] \in \mathsf{A}$.

Clearly $\Phi_f = \Phi_h$ iff [f] = [h].

Definition.

- 1. A Gröbner representation of J is the assignment of
 - a K-basis $\mathbf{b} = \{[b_1], \dots, [b_s]\} \subset \mathsf{A}$ and
 - the square matrices $A_h := \left(a_{ij}^{(h)}\right) = M([Z_h], \mathbf{b})$ for each $h, 1 \le h \le s$,

[

2. For each $g \in Q$ the Gröbner description of g in terms of a Gröbner representation $(\mathbf{b}, \{A_k\})$ is the unique (row) vector

$$\mathbf{Rep}(g,\mathbf{b}) := (\gamma(g,b_1,\mathbf{b}),\ldots,\gamma(g,b_s,\mathbf{b})) \in K^s$$

which satisfies

$$[g] = \sum_j \gamma(g, b_j, \mathbf{b})[b_j]$$

If we fix any K-basis $\mathbf{b} = \{[b_1], \dots, [b_s]\}$ of A so that $\mathbf{A} = \operatorname{Span}_K(\mathbf{b})$, then for each $g \in \mathcal{Q}$, there is a unique (row) vector, the Gröbner description of g,

$$\mathbf{Rep}(g, \mathbf{b}) := (\gamma(g, b_1, \mathbf{b}), \dots, \gamma(g, b_s, \mathbf{b})) \in K^s$$

which satisfies

$$[g] = \sum_{j} \gamma(g, b_j, \mathbf{b})[b_j]$$

and the endomorphism Φ_f is naturally represented by the square matrix

$$M([f], \mathbf{b}) = (\gamma(fb_i, b_j, \mathbf{b})) : \Phi_f(b_i) = [fb_i] = \sum_j \gamma(fb_i, b_j, \mathbf{b})[b_j].$$

An alternative way of representing a zero-dimensional ideal $J \subset Q$ and the related quotient algebra A is via its dual space (Section 28.1)

$$\mathfrak{L}(\mathsf{J}) := \{\ell \in \mathcal{Q}^* : \ell(g) = 0 \text{ for each } g \in \mathsf{J}\} \subset \mathcal{Q}'$$

where $\mathcal{Q}^* := \operatorname{Hom}_K(\mathcal{Q}, K)$ is the K-vectorspace consisting of all K-linear functionals $\ell : \mathcal{Q} \to K$. Clearly we have $\dim_K(\mathfrak{L}(J)) = s$ and to each K-basis $\mathbb{L} := \{\lambda_1, \dots, \lambda_s\}$ of $\mathfrak{L}(J)$ is associated a Lagrange K-basis

 $\mathbf{q} = \{[q_1], \dots, [q_s]\} \text{ which is biorthogonal to } \mathbb{L} \text{ id est } \lambda_i(q_j) = \delta_{ij} = \begin{cases} 1 & i = j \\ 0 & i \neq j. \end{cases}$

In particular, since, for each i, j, h,

$$\lambda_j(Z_h q_i) = \lambda_j\left(\sum_l a_{il}^{(h)} q_l\right) = \sum_l a_{il}^{(h)} \lambda_j(q_l) = a_{ij}^{(h)},$$

to each basis $\mathbb{L} := \{\lambda_1, \cdots, \lambda_s\}$ of $\mathfrak{L}(\mathsf{J})$ is associated the Gröbner representation

- $\mathbf{q} = \{[q_1], \dots, [q_s]\} \subset \mathsf{A} : \lambda_i(q_j) = \delta_{ij} \text{ for each } i, j,$
- $Q_h := (\lambda_j(Z_h q_i))_{ij}.$

Between the two bases \mathbf{b} and \mathbf{q} there are the basis transformations

$$M_{bq} := (\gamma(b_i, q_j, \mathbf{q})) \text{ and } M_{qb} := (\gamma(q_i, b_j, \mathbf{b}))$$

so that, for each i,

$$[b_i] = \sum_j \gamma(b_i, q_j, \mathbf{q})[q_j] \text{ and } [q_i] = \sum_j \gamma(q_i, b_j, \mathbf{b})[b_j];$$

naturally, we have $M_{bq} = M_{qb}^{-1}$, and

$$M([f], \mathbf{b}) = M_{bq} M([f], \mathbf{q}) M_{qb} = M_{bq} M([f], \mathbf{q}) M_{bq}^{-1}$$

so that $M([f], \mathbf{q})$ and $M([f], \mathbf{b})$ are similar and share the same eigenvalues and Jordan normal form.

Toward Auzinger–Stetter's Theorem

With the same notation as in the previous section let us fix

• a Gröbner representation

$$\mathbf{b} = \{[b_1], \dots, [b_s]\} \subset \mathsf{A}, A_h := \left(a_{ij}^{(h)}\right) = M([Z_h], \mathbf{b}), 1 \le h \le r;$$

- a basis $\mathbb{L} := \{\lambda_1, \cdots, \lambda_s\}$ of $\mathfrak{L}(\mathsf{J})$;
- the conjugate Gröbner representation

$$\mathbf{q} = \{[q_1], \dots, [q_s]\} \subset \mathsf{A}, Q_h := (\lambda_j(Z_h q_i))_{ij}$$

where **q** is the Lagrange basis satisfying $\lambda_i(q_j) = \delta_{ij}$ for each i, j,

and let us denote

- $M_{bq} := (\gamma(b_i, q_j, \mathbf{q}))$ and $M_{qb} := (\gamma(q_i, b_j, \mathbf{b}))$ the basis transformation matrices;
- J_h the Jordan normal form matrix for A_h ;
- for each $f \in \mathcal{Q}/\mathsf{J} = \mathsf{A}$

$$A_{f} := M([f], \mathbf{b}) = (\gamma(fb_{i}, b_{j}, \mathbf{b})) : \Phi_{f}(b_{i}) = [fb_{i}] = \sum_{j} \gamma(fb_{i}, b_{j}, \mathbf{b})[b_{j}]$$

• J_f the Jordan normal form matrix for A_f .

Let us also consider the set

$$\mathcal{Z}(\mathsf{J}) := \{ \alpha \in K^r : f(\alpha) = 0 \text{ for each } f \in \mathsf{J} \}$$

Lemma (Auzinger–Stetter). With the present notation it holds

$$\gamma(b_i, q_j, \mathbf{q}) = \lambda_j(b_i), 1 \le i, j \le s.$$

Proof. For each $f \in A$, $\sum_{j} \gamma(f, q_j, \mathbf{q})[q_j] = f = \sum_{j} \lambda_j(f)[q_j]$. The first equality follows from the definition of γ , the second from the property of the Lagrange basis. The claim then follows by the linear independency of \mathbf{q} . \square

Corollary. Each i^{th} row of M_{bq} is the vector $(\lambda_1(b_i), \ldots, \lambda_s(b_i))$ of the evaluation of the basis element b_i at the functional basis \mathbb{L} .

Each j^{th} column of M_{ba} is the vector $(\lambda_i(b_1), \ldots, \lambda_i(b_s))^T$ of the evaluation of the basis **b** at the functional λ_i . \Box

Lemma (Auzinger–Stetter). For each $\alpha \in \mathcal{Z}(J)$ the vector

$$(b_1(\alpha),\ldots,b_s(\alpha))^T$$

is an eigenvector of the matrix A_f for the eigenvalue $f(\alpha)$.

Proof. For each $i, 1 \leq i \leq s$, we have $[fb_i] = \Phi_f([b_i]) = \sum_j \gamma(fb_i, b_j, \mathbf{b})[b_j]$ so that $f(\alpha)b_i(\alpha) = \sum_j \gamma(fb_i, b_j, \mathbf{b})b_j(\alpha)$. Thus the claim follows trivially.

Definition. A matrix is called non-derogatory if, equivalently,

all its eigenspaces have dimension 1;

its Jordan form has a single Jordan block associated with each eigenvalue.

Theorem (Auzinger–Stetter). The set $\{f(\alpha) : \alpha \in \mathcal{Z}(\mathsf{J})\}$ is the set of eigenvalues of A_f . If A_f is non-derogatory, each eigenspace of A_f for $f(\alpha)$ is spanned by $(b_1(\alpha), \ldots, b_s(\alpha))^T$.

Proof. A direct consequence of the Lemmata above.

Auzinger–Stetter: The Radical case

The relevant aspect of Auzinger–Stetter's Theorem is that while both eigenvalues and eigenvectors of A_f intrinsecally depend on the roots of J their actual values are precise functions of the choice of the matrix A_f and of the basis **b**; one can therefore expects that for a proper choice of f and **b** an eigenvalue computation can allow to deduce the roots of J.

Let us assume that J is radical and see whether the remark above leads to something.

The radicality assumption implies that J has $s = \deg(J)$ different roots in K^r :

$$\mathcal{Z}(\mathsf{J}) = \{\alpha_1, \dots, \alpha_s\} \subset K^r, \quad \alpha_j = (a_1^{(j)}, \dots, a_r^{(j)}).$$

Thus we can wlog identify each functional λ_i with the evaluation at the root α_i :

$$\lambda_j : \mathcal{Q} \to K, p(Z_1, \dots, Z_r) \mapsto \lambda_j(p) = p(a_1^{(j)}, \dots, a_r^{(j)})$$

and \mathbf{q} is the corresponding Lagrange basis.

A matrix A_f is non-derogratory if and only if $f(\alpha_i) \neq f(\alpha_j)$ for each $i \neq j$. Clearly for a generic linear form $Y = \sum_{h} c_h Z_h$, A_Y is non-derogatory. Thus if we choose a linear form which separates $\mathcal{Z}(\mathsf{J})$ id est it satisfies the condition

(AS.1) $Y = \sum_h c_h Z_h$ is such that $\beta_i := \sum_h c_h a_h^{(i)} \neq \sum_h c_h a_h^{(j)} =: \beta_j$ for each $i \neq j$

then A_Y is non-derogatory and have s distinct eigenvalues

$$\beta_j := \sum_h c_h a_h^{(j)}, 1 \le j \le s$$

whose associated eigenspaces are generated by

$$(b_1(\alpha_j),\ldots,b_s(\alpha_j))^T.$$

In order to deduce the α_i s from these eigenvectors, the trick consists in a clever choice of the basis **b**. The efficient choice is the original one proposed by Auzinger–Stetter: let us denote V the K-vectorspace

$$V := \text{Span}_{K}\{[1], [Z_1], \dots [Z_r]\}$$

and let $\delta := \dim_K(V) \leq s$; then, up to reenumerating the variables, we can wlog assume that

- $V = \operatorname{Span}_{K}\{[1], [Z_1], \dots [Z_{\delta-1}]\}$
- $\{[1], [Z_1], \dots, [Z_{\delta-1}]\}$ is a *K*-basis of *V*,
- there are $c_{il} \in K, 0 \le l < \delta \le i \le r$ such that $[Z_i] = c_{i0} + \sum_{l=1}^{\delta-1} c_{il}[Z_l]$.

Moreover, the knowledge of the matrices A_h allows to deduce, by easy linear algebra, both δ and the c_{il} s. We can therefore choose a basis **b** which satisfies the condition

(AS.2) $\mathbf{b} = ([b_1], \dots, [b_s])$ is such that

$$b_1 = 1, b_i = Z_{i-1}, 1 < i \le \delta = \dim_K(V)$$

so that

$$V := \operatorname{Span}_{K}\{[1], [Z_{1}], \dots [Z_{r}]\} = \operatorname{Span}_{K}\{[1], [Z_{1}], \dots [Z_{\delta-1}]\} \\ = \operatorname{Span}_{K}\{[b_{1}], \dots, [b_{\delta}]\};$$

thus the eigenvectors corresponding to $\alpha_j = (a_1^{(j)}, \ldots, a_r^{(j)})$ are

$$(1, a_1^{(j)}, \dots, a_{\delta-1}^{(j)}, b_{\delta+1}(\alpha_j), \dots, b_s(\alpha_j))^T$$

and the other coordinates of α_j can be deduced from $a_i^{(j)} = c_{i0} + \sum_{l=1}^{\delta-1} c_{il} a_l^{(j)}$. In conclusion

Theorem (Auzinger–Stetter). With the present notation and under the assumption that J is radical, then it holds

- 1. each j^{th} column $(b_1(\alpha_j), \ldots, b_s(\alpha_j))^T$ of M_{bq} is an eigenvector of each $A_f, f \in \mathcal{Q}$, for the eigenvalue $f(\alpha_j)$;
- 2. for each $f \in Q$, it holds
 - (a) the eigenvalues of A_f and A_f^T are $\{f(\alpha_j) : 1 \le j \le s\};$
 - (b) the eigenspace of A_f for $\lambda \in K$ is

$$\operatorname{Span}_{K}\{(b_{1}(\alpha_{j}),\ldots,b_{s}(\alpha_{j}))^{T}:f(\alpha_{j})=\lambda\}\}$$

If, moreover, $Y = \sum_{h} c_h Z_h$ satisfies condition (AS.1) then:

3. the jth column $(b_1(\alpha_j), \ldots, b_s(\alpha_j))^T$ of M_{bq} is the eigenvector for $\beta_j := \sum_h c_h a_h^{(j)}$ of A_Y ;

If further $\mathbf{b} = \{[1], [Z_1], \dots, [Z_{\delta-1}], [b_{\delta+1}], \dots, b_s]\}$ satisfies condition (AS.2) then:

4. denoting $\{(d_{j1}, \ldots, d_{js})^T, 1 \leq j \leq s\}$ the eigenvectors of A_Y and

$$\alpha_j := \left(d_{j1}^{-1} d_{j2}, \dots, d_{j1}^{-1} d_{j\delta}, c_{\delta 0} + \sum_{l=1}^{\delta - 1} c_{\delta l} d_{j1}^{-1} d_{jl}, \dots, c_{n0} + \sum_{l=1}^{\delta - 1} c_{nl} d_{j1}^{-1} d_{jl} \right)$$

for each j, then $\mathcal{Z}(\mathsf{J}) = \{\alpha_j, 1 \leq j \leq s\}.$

Stetter Algorithm via Grobnerian Technology

A linear form

$$Y := \sum_{h=1}^{r} c_h Z_h$$

is said an all gemeine coordinate for the zero-dimensional ideal $\mathsf{J}=\cap_{i=1}^{\mathsf{s}}\mathfrak{q}_i$ iff

(a). there are polynomials $g_i \in K[Y], 0 \le i \le n, g_0$ monic, $\deg(g_i) < \deg(g_0)$, such that

$$G := (g_0(Y), Z_1 - g_1(Y), Z_2 - g_2(Y), \dots, Z_r - g_r(Y))$$

is the reduced Gröbner basis of the ideal

$$\mathsf{J}^+ := \mathsf{J} + \left(Y - \sum_h c_h Z_h\right) \subset K[Y, Z_1, \dots, Z_r]$$

w.r.t. the lex ordering induced by $Y < Z_1 < \ldots < Z_r$

and that this condition implies, under the assumption that J is radical, that

- (b). $\mathcal{Q}/\mathsf{J} \cong K[Y]/g_0(Y)$
- (c). for each $i, 1 \leq i \leq s$, $\beta_i := \sum_{h=1}^r c_h a_h^{(i)}$ is a root of g_0
- (d). $g_0(Y) = \prod_{i=1}^r (Y \beta_i);$
- (e). there are polynomials $h_1(Y), \ldots, h_r(Y) \in K[Y], \deg(h_i) < \deg(g_0)$, such that

$$^{+} = \mathbb{I}(g_0(Y), g'_0(Y)Z_1 - h_1(Y), \dots, g'_0(Y)Z_r - h_r(Y)) \subset K[Y, Z_1, \dots, Z_r].$$
(1)

(f). for each $\iota, 1 \leq \iota \leq r$, we have

$$h_{\iota}(Y) = \sum_{i=1}^{s} a_{\iota}^{(i)} \prod_{j \neq i} (Y - \beta_j).$$
⁽²⁾

- (g). $a_j^{(i)} = g_j(\beta_i) = \frac{g_0'(\beta_i)}{g_0'(\beta_i)}$ for each $i, 1 \le i \le s$, and each $j, 1 \le j \le r$,
- (h). For each $f \in \mathcal{Q}$, $g_f(Y) := \mathbf{Rem}(f(g_1(Y), \dots, g_r(Y)), g_0(Y))$ is s.t.

 $f \equiv g_f \mod \mathsf{J}^+, \deg(g_f) < \deg(g_0).$

(i). For each $f \in Q$, $h_f(Y) := \mathbf{Rem}(f(h_1(Y), \dots, h_r(Y)), g_0(Y)) \in K[Y]$ is s.t.

$$g'_0(Y)f(Z_1,\ldots,Z_r) \equiv g_f \mod \mathsf{J}^+, \deg(h_f) < \deg(g_0).$$

Moreover, there is a Zarisky open set $\mathbf{U} \subset K^n$ such that $Y := \sum_{h=1}^r c_h Z_h$ is an allgemeine coordinate for J iff $(c_1, \ldots, c_r) \in \mathbf{U}$.

Since Stetter Algorithm is improved if J is radical and the matrix A_Y is given wrt a linear form Y satisfying condition (AS.1), these results can be efficiently — $\mathcal{O}(n^2s^3)$ — granted by giving an FGLM-like linear algebra version of Gianni's Proposition obtained merging the algorithms by Alonso–Raimondo and Traverso.

We describe here the algorithm under the (useless but simplifer) assumption that J is radical:

1. $\ell := \sum_i a_i Z_i$

2. by linear algebra on the Gröbner descriptions of

$$[1], [\ell], [\ell^2], \dots, [\ell^s]$$

compute the minimal polynomial $g_0[Y] \in K[Y]$ such that

$$g_0(Y) \in \mathsf{J}^+ := \mathsf{J} + \left(Y - \sum_i a_i Z_i\right);$$

3. set i = r and

- (a) verify, by linear algebra on the Gröbner descriptions of $[g'_0(\ell)Z_j], [1], [\ell], [\ell^2], \ldots, [\ell^{d-1}]$, whether exists a relation $g'_0(Y)Z_i h_j(Y) \in \mathsf{J}^+$, $\deg(h_i) < d$;
- (b) if such a relation exists and i > 1, set i := i 1 and go to (3.a);
- (c) if such relation does not exist (this necessarily happens iff $d := \deg(g_0) < \deg(\mathsf{J})$ and in this case we have i > 1); then

• set
$$\ell := \ell + cZ_i, a_i := a_i + c$$
 and go to (2)

4. if
$$\deg(g_0) = \deg(\mathsf{J})$$
, then

- $\ell := \sum_{i} a_i Z_i$ is a separating linear form thus satisfyings condition (AS.1)
- $[g'_0(\ell)Z_i] = [h_i(\ell)]$ for i = 1..., r.