Soundness of object-oriented languages with coinductive big-step semantics*

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Abstract. It is well known that big-step operational semantics are not suitable to prove soundness of type systems, because of their inability of distinguishing stuck from non terminating computations. We show how this problem can be solved by interpreting coinductively the rules of a standard big-step operational semantics for a Java-like language, and making the claim of soundness very simple: whenever a program is well-typed, its coinductive operational semantics returns a value.

This is possible since coinduction allows assignments of values to non terminating computations; this is proved by showing that the set of proof trees defining the semantic judgment forms a complete metric space when equipped with a proper distance function.

In this way, we are able to prove soundness of a nominal type system w.r.t. the coinductive semantics. Since the coinductive semantics is sound w.r.t. the usual small-step operational semantics, the standard claim of soundness can be easily deduced.

1 Introduction

It is well known that standard big-step operational semantics are less amenable to prove soundness of type systems than small-step semantics; several important motivations for this statement can be found in the literature [14,15], but, basically, the main source of all problems is the inability of big-step operational semantics to distinguish stuck from non terminating computations.

Besides addressing this problem, our work seeks to find simpler and easily automatizable techniques for proving soundness of abstract compilation of object-oriented languages [8,4,7,6,5], a novel approach which aims to reconcile type analysis and symbolic execution, where programs are compiled into a constraint logic program (CLP), and type analysis corresponds to solving a certain goal w.r.t. the coinductive semantics of CLP.

The idea of using coinduction to allow big-step semantics to capture non terminating computations is not new (see the conclusion for a brief survey); Leroy and Grall [15] have investigated coinductive operational semantics in the

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context of functional programming, with the main aim of elaborating new easily automatizable techniques for proving the correctness of compilation. Among the several approaches considered by the authors, the simplest one consists in interpreting coinductively the standard rules for the big-step operational semantics of lambda-calculus, and then express the soundness claim in a very direct way: if an expression e has type τ , then the coinductive semantics of e yields a value v of type τ . Unfortunately, such a claim fails to hold, as shown by the authors themselves, since there exist well-typed non terminating expressions for which the coinductive semantics is not defined. This happens because only finite values are considered, whereas the values that should be returned by the coinductive semantics of such counter-example expressions correspond to necessarily infinite limits of sequences of finite (that is, inductively defined) values. More formally, if only finite values are considered, then it is not possible to define a complete metric space over the set of possibly infinite proof trees for the judgment of the coinductive semantics.

Interestingly enough, if the same approach is taken for a Java-like language, and, more importantly, infinite values are considered as well, then the claim of soundness holds when expressed in terms of a coinductive big-step semantics.

Figure 1 provides a road-map to the main defined judgments and proved claims in this paper. Symbols \vdash and \vdash denote judgments defined inductively

Sect. 5 Sect. 6 Sect. 4
$$\boxed{\Gamma \vdash e : \tau} \quad \Rightarrow \quad \boxed{\Gamma \Vdash e : \tau} \quad \Rightarrow \quad \boxed{\exists \, v \, \varPi \Vdash e \Rightarrow \, v} \quad \Rightarrow \quad \boxed{e \, \text{diverges or} \, \exists \, v \, e \stackrel{*}{\to} \, v}$$

Fig. 1. Relationship between the main judgments

and coinductively, respectively.

After having introduced the syntax and the standard small-step semantics (abbreviated with ISS) of the language (Section 2), and the mathematical background (Section 3) needed for the proofs, in Section 4 we define the coinductive big-step semantics (abbreviated with CBS) of the language, show, by means of examples, its behavior in case of non termination, and formalize its relationship with the ISS (rightmost implication in Figure 1): if the CBS of e yields a value v, then the ISS of e either returns a value v, or does not terminate; in other words, whenever the CBS of e yields a value, the ISS of e cannot get stuck, hence, the CBS is sound w.r.t. the ISS. Note the different nature of values (and hence the use of different meta-variables) in the CBS, where they can be infinite, and in the ISS, where they can only be finite.

In Section 5 a conventional inductive and nominal type system is defined (judgment $\Gamma \vdash e:\tau$), and a coinductive type system is derived from it (judgment $\Gamma \vdash e:\tau$): such a coinductive system is closer to the CBS, indeed it can be regarded as an abstraction of the CBS. Furthermore we prove that all judgments that

hold in the inductive type system can be derived in the coinductive one as well (leftmost implication in Figure 1).

The core and most difficult part of the formalization concerns the proof of the soundness of the coinductive type system w.r.t. the CBS (mid implication in Figure 1, proved in Section 6). The overview in Figure 1 clearly shows that, as expected, in the end we obtain the standard soundness result expressed in terms of the ISS.

Finally, in Section 7 we outline conclusions and related work.

This paper is an extension of a previous work by the same author [3], where the following contributions have been added: The definition of the coinductive type system and the corresponding proof of the leftmost implication in Figure 1 are new; the coinductive type system has been introduced to make the proof of soundness simpler and more modular; it also reveals how coinduction is related to the inductive type system.

While the justification for the introduction of infinite values in the CBS is only informally motivated in the previous work, here it has been made rigorous by means of the notion of complete metric space; in particular, the definition of the metric space of proof trees for the CBS judgment, and the proof of its properties, represent a non trivial task and an original contribution.

In Section 4 a new example has been added (case 2 (c)), showing that soundness does not hold if only infinite but regular values are considered.

All main proofs have been detailed. The details that have been removed for space reasons can be found in a companion technical report¹.

2 Definition of the language

In this section we present our simple Java-like language, which will be used as reference language throughout the paper, together with its standard call-by-value small-step operational semantics.

Syntax: The syntax of the language is defined in Figure 2.

The language is a modest variation of Featherweight Java (FJ) [13], where the main differences concern the introduction of conditional expressions and boolean values, and the omission of type casts.

Standard syntactic restrictions are implicitly imposed in the figure. Bars denote sequences of n items, where n is the superscript of the bar and the first index is 1. Sometimes this notation is abused, as in $\overline{f}^h = \overline{e'}^h$; which is a shorthand for $f_1 = e'_1; \dots f_h = e'_h$;.

A program consists of a sequence of class declarations and a main expression. Types can only be class names and the primitive type **bool**; we assume that the

Available at ftp://ftp.disi.unige.it/person/AnconaD/ecoop12long.pdf.

```
\begin{array}{l} p ::= \overline{cd}^n \ e \\ cd ::= \mathbf{class} \ c_1 \ \mathbf{extends} \ c_2 \ \{ \ \overline{fd}^n \ \overline{md}^k \ \} \quad (c_1 \neq \mathtt{Object}) \\ fd ::= \tau \ f; \\ md ::= \tau_0 \ m(\overline{\tau} \ \overline{x}^n) \ \{e\} \quad x_i \neq \mathtt{this} \ \forall i = 1..n \\ \tau ::= c \mid \mathbf{bool} \\ e ::= \mathbf{new} \ c(\overline{e}^n) \mid x \mid e.f \mid e_0.m(\overline{e}^n) \mid \mathbf{if} \ (e) \ e_1 \ \mathbf{else} \ e_2 \\ \mid \mathbf{false} \mid \mathbf{true} \end{array}
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Assumptions: $n, k \geq 0$, inheritance is acyclic, names of declared classes in a program, methods and fields in a class, and parameters in a method are distinct.

Fig. 2. Syntax of the language

language supports boxing conversions, hence bool is a subtype² of the predefined class Object, which is the top type.

A class declaration contains field and method declarations; in contrast with FJ, constructors are not declared, but every class is equipped with an implicit constructor with parameters corresponding to all fields, in the same order as they are inherited and declared. For instance, the classes defined below

```
class P extends Object {bool b; P p;}
class C extends P {C c;}
have the following implicit constructors:
P(bool b,P p) {super(); this.b=b; this.p=p;}
C(bool b,P p,C c) {super(b,p); this.c=c;}
```

Method declarations are standard; in the body, the target object can be accessed via the implicit parameter this, therefore all explicitly declared formal parameters must be different from this. Expressions include instance creation, variables, field selection, method invocation, conditional expressions, and boolean literals.

Small-step operational semantics The definition of the conventional small-step operational semantics of the language can be found in Figure 3. We follow the approach of FJ, even though for simplicity we have preferred to restrict the semantics to the deterministic call-by-value evaluation strategy.

Values are either the literals **false** or **true**, or object expressions in normal form having shape **new** $c(\overline{v}^n)$. As happens for FJ, the semantics of object creation is more liberal than the expected one; indeed, **new** $c(\overline{v}^n)$ is always a correct expression which reduces to itself in zero steps, even when class c is not declared, or the number of arguments does not match the number of fields of c. As we will see, the big-step semantics follows a less liberal semantics, more in accordance with the standard semantics of mainstream object-oriented languages.

² This assumption ensures the existence of the join operator (least upper bound) between types, without introducing union types. This allows a simpler typing rule for conditional expressions in the type system defined in Section 5.

As usual, the reduction relation \rightarrow should be indexed over the collection of all class declarations contained in the program (conventionally called class table), however for brevity we leave implicit such an index in all judgments defined in the paper. The reflexive and transitive closure of \rightarrow is denoted by $\stackrel{*}{\rightarrow}$.

The standard auxiliary functions fields and meth are defined in Figure 10 in Appendix A. For compactness, such functions provide semantic and type information at once, since they are instrumental for the definition of both the semantics and the type system of the language. Function fields returns the list of all fields which are either inherited or declared in the class, in the standard order and with the corresponding declared types. In the case of the predefined class Object the returned list is empty (ϵ) ; field hiding is not supported, hence fields is not defined if a class declares a field with the same name of an inherited one. Function meth performs standard method look-up: if $meth(c, m) = \overline{\tau}^n \ \overline{x}^n.e:\tau$, then look-up of method m starting from class c returns the corresponding declaration where $\overline{\tau}^n \ \overline{x}^n$ are the formal parameters with their declared types, and e and τ are the body and the declared returned type, respectively. If meth(c, m) is undefined, then it means that look-up of m from c fails.

In rule (fld), if f_i is a field of the class, then the expression reduces to the corresponding value passed to the implicit constructor. If the selected field is not in such a list, then the evaluation of the expression gets stuck.

In rule (inv), if method look-up succeeds starting from the class of the target object, then the corresponding body is executed, where the implicit parameter this and the formal parameters are substituted with the target object and the argument values, respectively. The notation $e_i[\overline{x}^n \mapsto \overline{v}^n]$ denotes parallel substitution of the distinct variables \overline{x}^n with values \overline{v}^n in the expression e.

Rules for conditional expressions (ift) and (iff), and for context closure (ctx) are straightforward. Contexts are the standard ones corresponding to left-to-right, call-by-value strategy.

$$\begin{array}{l} v ::= \mathbf{new} \ c(\overline{v}^n) \mid \mathbf{false} \mid \mathbf{true} \\ \mathcal{C}[\] ::= \square \mid \mathbf{new} \ c(\overline{v}^n, \square, \overline{e}^k) \mid \square.f \mid \square.m(\overline{e}^n) \mid v.m(\overline{v}^n, \square, \overline{e}^k) \mid \mathbf{if} \ (\square) \ e_1 \ \mathbf{else} \ e_2 \\ \\ (\mathrm{fid}) \frac{\mathit{fields}(c) = \overline{\tau}^n \ \overline{f}^n, \quad 1 \leq i \leq n}{\mathbf{new} \ c(\overline{v}^n).f_i \rightarrow v_i} \\ \\ (\mathrm{inv}) \frac{\mathit{meth}(c, m) = \overline{\tau}^n \ \overline{x}^n.e:\tau}{\mathbf{new} \ c(\overline{v}^k).m(\overline{v'}^n) \rightarrow e[\mathtt{this} \mapsto \mathbf{new} \ c(\overline{v}^k), \overline{x}^n \mapsto \overline{v'}^n]} \\ \\ (\mathrm{ift}) \frac{\mathrm{iff} \ (\mathbf{true}) \ e_1 \ \mathbf{else} \ e_2 \rightarrow e_1}{\mathbf{iff} \ (\mathbf{false}) \ e_1 \ \mathbf{else} \ e_2 \rightarrow e_2} \end{array} \qquad \begin{array}{c} e \rightarrow e' \\ \hline \mathcal{C}[e] \rightarrow \mathcal{C}[e'] \end{array}$$

Fig. 3. Call-by-value inductive small-step operational semantics

3 Background

In the following, with the term tree over a set S we will mean a finitely branching tree with nodes in S that is allowed to contain infinite paths. If t is a tree, we denote with root(t) the root of t.

More rigorously, a tree with infinite paths can be defined in terms of partial functions over finite paths of natural numbers (denoted by \mathbb{N}^*) [11,9].

Definition 1. A tree over a set S is a partial function $t : \mathbb{N}^* \to S$ satisfying the following properties:

- 1. its domain is not empty: $dom(t) \neq \emptyset$;
- 2. its domain is prefix-closed: $p \cdot n \in dom(t)$ implies $p \in dom(t)$, for all $p \in \mathbb{N}^*$, and $n \in \mathbb{N}$;
- 3. if $p \cdot n \in dom(t)$ and $k \leq n$, then $p \cdot k \in dom(t)$ for all $p \in \mathbb{N}^*$ and $n, k \in \mathbb{N}$;
- 4. there exists $n \in \mathbb{N}$ s.t. $p \cdot n \notin dom(t)$, for all $p \in \mathbb{N}^*$.

Every path $p \in dom(t)$ identifies a unique subtree t' of t whose roots is t(p): $dom(t') = \{p' \in \mathbb{N}^* \mid p \cdot p' \in dom(t)\}$, and $t'(p') = t(p \cdot p')$ for all $p' \in dom(t')$.

Definition 2. A regular (a.k.a. rational) tree is a tree whose set of subtrees is finite.

Trivially, every finite tree (that is, tree with only finite paths) is regular, but there exist also infinite trees that are regular.

Definition 3. A metric space (S,d) is a set S equipped with a function $d:S \times S \to \mathbb{R}$, called metric or distance, satisfying the following properties, for all x, y, and z in S:

- (identity) d(x,y) = 0 iff x = y;
- (symmetry) d(x,y) = d(y,x);
- (triangle inequality) $d(x, z) \le d(x, y) + d(y, z)$.

Definition 4. Let (S, d) be a metric space.

- A sequence $(x_i)_{i\in\mathbb{N}}$ has limit l iff for all $\epsilon > 0$ there exists $k \in \mathbb{N}$ s.t. $d(x_n, l) < \epsilon$, for all n > k.
- A Cauchy sequence $(x_i)_{i\in\mathbb{N}}$ is a sequence s.t. for all $\epsilon > 0$ there exists $k \in \mathbb{N}$ s.t. $d(x_n, x_m) < \epsilon$ for all n, m > k.
- A metric space is complete iff all Cauchy sequences have a limit.

Proposition 1. Let T_S be the set of all trees over S. Then, T_S is a complete metric space [10,2] with the following metric:

$$d_T(t_1, t_2) = 2^{-c}$$

where $c = shtp(t_1, t_2) = \min\{n \in \mathbb{N} \mid p \in \mathbb{N}^n, t_1(p) \neq_{\perp} t_2(p)\}, \min \emptyset = \infty, 2^{-\infty} = 0, t_1(p) =_{\perp} t_2(p) \text{ iff either } p \notin dom(t_1) \text{ and } p \notin dom(t_2), \text{ or } p \in dom(t_1) \cap dom(t_2) \text{ and } t_1(p) = t_2(p). \text{ That is, } c \text{ is the length of a shortest path that distinguishes } t_1 \text{ from } t_2, \text{ if } t_1 \neq t_2, \text{ or } c = \infty \text{ if } t_1 = t_2.$

By definition, for all pairs of trees t_1 and t_2 , $d_T(t_1, t_2) \in \{0\} \cup \{2^{-c} \mid c \in \mathbb{N}\}$, that is, $0 \leq d_T(t_1, t_2) \leq 1$. It can be proved that the set of finitely branching trees with infinite paths, with the metric defined above, is the (unique up to isometries) completion of the set of finitely branching trees with finite paths with the same metric.

Definition 5. Let us consider a judgment where all possible instantiations range over the set \mathcal{J} .

A proof tree ∇ for an instantiation $j \in \mathcal{J}$ of the judgment is a tree ∇ over \mathcal{J} s.t. $root(\nabla) = j$.

A valid proof tree for an instantiation $j \in \mathcal{J}$ of the judgment is a proof tree ∇ s.t. for any node j in ∇ , if j_1, \ldots, j_k are the children of j, then $\frac{j_1, \ldots, j_k}{j}$ is a correct instantiation of one of the meta-rules defining this kind of judgment.

We simply write that ∇ is a (valid) proof tree for the judgment, when we are not interested in specifying the particular instantiation $j \in \mathcal{J}$ which is the root of the tree.

We write $ok(R)(\nabla)$ to indicate that the root of ∇ together with its children are a correct instantiation of the meta-rule labeled by R. Hence, a valid proof tree ∇ is a proof tree s.t. for all subtrees ∇' of ∇ (including ∇), there exists a meta-rule R s.t. $ok(R)(\nabla')$.

Definition 6. A complete lattice is a partially ordered set (L, \leq) s.t. any subset S of L has a supremum (a.k.a. least upper bound) denoted with $\sup S$.

Since, by definition of inf and sup, inf $S = \sup\{x \in L | \forall y \in S \ x \leq y\}$, sup \emptyset is the least element \bot of L, and inf \emptyset is the greatest element \top of L, then every subset of a complete lattice has an infimum (greatest lower bound) and every complete lattice is bounded.

Definition 7. Let (L, \leq) be a complete lattice. A (total) function $f: L \to L$ is continuous iff preserves the supremum of every subset of L: for all $S \subseteq L$, $f(\sup S) = \sup\{f(x) | x \in S\}$.

It is easy to prove that a complete function is monotone and preserves infima as well.

Definition 8. Let (L, \leq) be a partially ordered set, f a (total) function from L to L, and x an element of L.

- x is a pre-fixed point of f (a.k.a. f-closed) iff $f(x) \leq x$;
- x is a post-fixed point of f (a.k.a. f-dense or f-justified or f-consistent) iff $x \leq f(x)$.

Trivially, x is a fixed-point of f iff x is both a pre-fixed and a post-fixed point of f.

Theorem 1 (Tarski-Knaster). Let (L, \leq) be a complete lattice, and $f: L \to L$ a monotone function. Then

```
1. f(\inf\{x \in L | x \text{ pre-fixed point of } f\}) = \inf\{x \in L | x \text{ pre-fixed point of } f\};
2. f(\sup\{x \in L | x \text{ post-fixed point of } f\}) = \sup\{x \in L | x \text{ pre-fixed point of } f\}.
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From Theorem 1 one can trivially deduce that a monotone function defined on a complete lattice has always a least fixed-point (which is also the least pre-fixed point), and a greatest fixed point (which is also the greatest post-fixed point).

Given a judgment defined by a set of meta-rules, with instantiations ranging over \mathcal{J} , it is possible to define the one step inference function \mathcal{F} over the power-set of \mathcal{J} as follows: for any subset J of \mathcal{J} , $\mathcal{F}(J)$ is the subset J' of \mathcal{J} s.t. for any $j \in J'$, there exists a correct instantiation $\frac{j_1, \dots, j_k}{j}$ of a meta-rule with $\{j_1, \dots, j_k\} \subseteq J$.

Such a function is always trivially monotone, and it can be proved [8,5,15,19] that its least fixed point is the set of $j \in \mathcal{J}$ s.t. there exists a finite valid proof tree for j, whereas its greatest fixed point is the set of $j \in \mathcal{J}$ s.t. there exists a valid proof tree for j.

We denote with $f^n(x)$ n iterated applications of f to x (with $n \in \mathbb{N}$, $f^0(x) = x$).

Theorem 2 (Kleene). Let (L, \leq) be a complete lattice, and $f: L \to L$ a continuous function. Then

```
1. \sup\{f^n(\bot)|n\in\mathbb{N}\}\ is the least fixed point of f; 2. \inf\{f^n(\top)|n\in\mathbb{N}\}\ is the greatest fixed point of f.
```

Since f is monotone, we have that $f^0(\bot) \leq f^1(\bot) \leq \dots f^n(\bot) \leq f^{n+1}(\bot) \leq \dots$ is an ascending chain, and dually, $f^0(\top) \geq f^1(\top) \geq \dots f^n(\top) \geq f^{n+1}(\top) \geq \dots$ is a descending chain. Note that the two claims of Theorem 2 hold also under the weaker assumption that f is a monotone function preserving suprema of ascending chains (claim 1), or infima of descending chains (claim 2).

4 A coinductive semantics

In this section we define a call-by-value coinductive big-step operational semantics for our language.

Such a semantics is obtained by simply interpreting coinductively the definition of values and the rules of a pretty standard inductive big-step operational semantics (with no rules for error handling).

Definition of the semantics The CBS judgment uses value environments (see below), just for uniformity with the type judgment defined in Section 5. Value environments are not strictly necessary, since the rule for method invocation can be equivalently defined with parallel substitution as in ISS. Values are separated from expressions since they are infinite, while expressions are always finite. Such a separation is further stressed by the fact that values belong to a different syntactic category, that is, even finite values are different from expressions.

$$v, u := obj(c, [\overline{f}^n \mapsto \overline{v}^n]) \mid false \mid true \quad (coinductive def.)$$

We recall that **false** and **true** are expressions of our language, and values (denoted by the meta-variable v) in the ISS, whereas *false* and *true* are not expressions, but just the corresponding values (denoted by the meta-variable v) in the CBS. Similarly, **new** $c(\mathbf{true})$ is both an expression and a value in ISS, whereas $obj(c, [f \mapsto true])$ is the corresponding value in CBS (assuming that the only field of c is f), and is not an expression.

As an example of infinite value, let us consider the object value v defined by the equation

$$v = obj(List, [hd \mapsto obj(Elem, []), tl \mapsto v])$$

which represents an infinite list; in our language, such a value can only be returned by an infinite computation. Of course in a lazy or imperative language, this value could be returned also by a terminating computation; however, the important point here is that type correct expressions which do not terminate must always return a value in the CBS: as explained in case 2 in the second part of this section, without infinite values the claim of soundness proved in Section 5 would not hold.

The CBS is defined in Figure 4. Thicker lines manifest that rules are interpreted coinductively. A value environment Π is a finite sequence $\overline{x_i}^n \mapsto \overline{v}^n$, where all variables $\overline{x_i}^n$ are distinct, denoting a finite partial function mapping variables to values (\emptyset denotes the empty environment, $dom(\Pi)$ the domain of Π). Environments model stack frames of method invocations.

Rules (VAR), (FAL), and (TRU) are straightforward. Evaluation of instance creation (NEW) succeeds only if fields(c) is defined (that is, if c and its ancestors are declared in the program and no field is hidden), and returns a list of fields whose length must coincide with the number of arguments; then all arguments are evaluated and the obtained values are associated with the corresponding fields in the object value. For field selection (FLD) the target expression is evaluated; then evaluation succeeds only if an object value is returned, and the selected field is present in the object value; in this case the corresponding associated value is returned. For method invocation (INV) all expressions denoting the target object and the arguments are evaluated. If the value corresponding to the target is an object of class c, method look-up starting from c succeeds and returns a method declaration with a number of formal parameters coinciding with the number of passed arguments, then the method body is evaluated in the environment where this and the formal parameters are associated with their corresponding values. If such an evaluation succeeds, then the returned value is the value of the method invocation. Finally, rules (IFT) and (IFF) deal with the straightforward evaluation of conditional expressions.

Note that in the CBS of object creation is less liberal than in the ISS: as an example, **new** c() is a value in the ISS, whereas the same expression may not evaluate to a value in the CBS; this happens if either c is not declared in the program, or if c contains at least one field.

Coinductive semantics of non terminating expressions We have already observed that if the definition of values and the evaluation rules are interpreted

$$\begin{array}{c} \Pi(x) = \mathbf{v} \\ \hline \Pi \Vdash x \Rightarrow \mathbf{v} \\ \hline \Pi \Vdash \mathbf{false} \Rightarrow \mathit{false} \\ \hline \\ \forall i = 1..n \ \Pi \Vdash e_i \Rightarrow \mathbf{v}_i \quad \mathit{fields}(c) = \overline{\tau}^n \ \overline{f}^n \\ \hline \\ \Pi \Vdash \mathbf{new} \ c(\overline{e}^n) \Rightarrow \mathit{obj}(c, [\overline{f}^n \mapsto \overline{\mathbf{v}}^n]) \\ \hline \\ \Pi \Vdash e \Rightarrow \mathit{false} \quad \Pi \Vdash e_2 \Rightarrow \mathbf{v} \\ \hline \\ \Pi \Vdash \mathbf{if} \ (e) \ e_1 \ \mathbf{else} \ e_2 \Rightarrow \mathbf{v} \\ \hline \\ \Pi \vdash \mathbf{if} \ (e) \ e_1 \ \mathbf{else} \ e_2 \Rightarrow \mathbf{v} \\ \hline \\ \Pi \vdash e \Rightarrow \mathit{obj}(c, [\overline{f}^n \mapsto \overline{\mathbf{v}}^n]) \\ \hline \\ \Pi \vdash e \Rightarrow \mathit{false} \quad \Pi \vdash e_3 \Rightarrow \mathbf{v} \\ \hline \\ \Pi \vdash e \Rightarrow \mathit{obj}(c, [\overline{f}^n \mapsto \overline{\mathbf{v}}^n]) \\ \hline \\ \Pi \vdash e \Rightarrow \mathit{false} \\ \hline \\ \Pi \vdash e$$

Fig. 4. Call-by-value coinductive big-step operational semantics

inductively, then we obtain a standard inductive big-step operational semantics. Obviously, if an expression evaluates to a value in the inductive semantics, then the same value is obtained in the coinductive one; however, this case concerns terminating expressions, whereas what we do really care about here is the behavior of the CBS for non terminating expressions. We show that three different cases may occur. All expressions e considered in the examples below are well-typed and do not terminate in the ISS, that is, there exists no normal form e' s.t. $e \stackrel{*}{\longrightarrow} e'$.

Case 1: There exist many values \forall s.t. $\emptyset \vdash e \Rightarrow \forall$

Let us consider the expression e = new C().m(), where C is the only class declared in the program:

Then $\emptyset \Vdash e \Rightarrow v$ for all values v, as shown in the valid proof tree of Figure 5. Ellipsis means that such a tree is infinite (hence, it cannot be a valid proof for an inductive system), although regular, that is, it can be folded into a finite graph, because of the repeated finite pattern originated from the judgment $\Pi \Vdash \text{this.m}() \Rightarrow v$. Such non-determinism is naturally reflected in the conven-

$$\begin{array}{cccc} & & & \vdots & & & \vdots & & & \\ \hline \varPi \Vdash \mathtt{this} \Rightarrow \mathbb{U} & & \varPi \vdash \mathtt{this}.\mathtt{m()} \Rightarrow \mathbb{v} & & & \\ \hline \emptyset \vdash \mathtt{new} \ \mathtt{C()} \Rightarrow \mathbb{U} & & & & & \\ \hline \end{pmatrix} \\ \hline \emptyset \vdash \mathtt{new} \ \mathtt{C()}.\mathtt{m()} \Rightarrow \mathbb{v} & & & & \\ \hline \end{array}$$

Fig. 5. Proof tree for $\emptyset \Vdash e \Rightarrow v$, where u = obj(C, []), $\Pi = \text{this} \mapsto u$

tional nominal type system (see Section 5) where the return type **bool** can in fact be correctly replaced by any other type defined in the program.

There are also cases where finitely many values are returned. For instance,

```
\emptyset \Vdash \text{if (new C().m())} true else false \Rightarrow true \emptyset \Vdash \text{if (new C().m())} true else false \Rightarrow false
```

and no other values can be returned.

```
Case 2 (a), (b) and (c): There exists a unique value v s.t. \emptyset \vdash e \Rightarrow v
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We consider three possible cases (a), (b), and (c), where the returned value is finite (a), or infinite but regular (b), or infinite and non regular (c). For case (a), if C is the class of case 1, then the expression if (new C().m()) true else true trivially evaluates to the unique value *true* (although with two different valid proof trees). For case (b), let us consider a program with the following declarations (where M, L, and n are abbreviations for Main, List, and next, respectively):

```
class M extends Object {L m(){new L(this.m())}}
class L extends Object {L n;}
```

The main expression **new** M().m() evaluates to a unique value which is a infinite but regular object of class L; Figure 5 shows the unique valid proof tree for $\emptyset \Vdash \mathbf{new} \ M() .m() \Rightarrow obj(L, [n \mapsto v])$; such a tree is infinite, but regular. The proof tree is valid if and only if the following proposition holds:

```
\Pi \Vdash \mathbf{new} \ \mathsf{L}(\mathsf{this.m()}) \Rightarrow \mathsf{v} \ \mathrm{iff} \ \Pi \Vdash \mathbf{new} \ \mathsf{L}(\mathsf{this.m()}) \Rightarrow \mathit{obj}(\mathsf{L}, [\mathsf{n} \mapsto \mathsf{v}])
```

with $\Pi = \mathtt{this} \mapsto obj(\mathtt{M},[])$. Such a proposition cannot be satisfied by finite values, but holds for the unique infinite regular value \mathtt{v} s.t. $\mathtt{v} = obj(\mathtt{L}, [\mathtt{n} \mapsto \mathtt{v}])$.

In the conventional nominal type system the return type τ of method m in M must verify $L \leq \tau$, since the body of the method returns a new instance of class L, but also $\tau \leq L$, since the formal parameter of the implicit constructor of L has the same type as field n; therefore, similarly to what happens in the CBS, there exists only one possible return type: L. This example shows that if rules are interpreted coinductively, but values can only be finite, then the soundness claim proved in Section 5, (that is, any well-typed expression evaluates to a value) does not hold.

Finally, for case (c), let us consider the following class declarations:

```
class Nat extends Object { }
class Z extends Nat { }
class NZ extends Nat {Nat p;}
class M extends Object {L m(Nat e){new L(e,this.m(new NZ(e)))}}
class L extends Object {Nat e; L n;}
```

Then, the expression \mathbf{new} M().m(\mathbf{new} Z()) is well-typed and evaluates to the unique infinite and non regular value \mathbf{v}_0 where

```
\mathbf{v}_i = obj(\mathbf{L}, [\mathbf{e} \mapsto \mathbf{u}_i, \mathbf{n} \mapsto \mathbf{v}_{i+1}]) \text{ for all } i \in \mathbb{N}

\mathbf{u}_0 = obj(\mathbf{Z}, [\ ])

\mathbf{u}_i = obj(\mathbb{NZ}, [\mathbf{p} \mapsto \mathbf{u}_{i-1}]) \text{ for all } i \in \mathbb{N} \setminus \{0\}
```

Fig. 6. Proof of $\emptyset \vdash \mathbf{new} \ \mathtt{M().m()} \Rightarrow obj(\mathtt{L}, [\mathtt{n} \mapsto \mathtt{v}]), \ \mathrm{with} \ \mathtt{v} = obj(\mathtt{L}, [\mathtt{n} \mapsto \mathtt{v}]), \ \Pi = \mathsf{this} \mapsto obj(\mathtt{M}, [\])$

Figure 7 shows the non regular valid proof tree for the judgment, defined in terms of a countably infinite set of equations whose solutions are valid proof trees ∇_i , for all $i \in \mathbb{N}$. This example shows that if rules are interpreted coinductively, but values can only be regular, then the soundness claim proved in Section 5, (that is, any well-typed expression evaluates to a value) does not hold.

Fig. 7. Proof of $\emptyset \Vdash$ **new** M().m(new Z()) $\Rightarrow v_0$, with $\Pi_i =$ this $\mapsto obj(M,[]), e \mapsto u_i$ for all $i \in \mathbb{N}$

Case 3: There exist no values v s.t. $\emptyset \Vdash e \Rightarrow v$

If C is as in case 1 (that is, new C().m() does not terminate), then the expression if (new C().m()) true.m() else true.m() does not evaluate to any value; this is a direct consequence of the fact that no rules are applicable for the expression true.m() since true does not evaluate to an object value. The main difference with the previous two cases is that here the expression to be evaluated cannot be typed in any type system insensitive to non termination. Indeed, in the conventional nominal type system defined in Section 5 all previous examples except for the last one are well-typed. This example shows the main difference between the ISS and the CBS: in the former, there exist ill-typed expressions

whose evaluation does not terminate (that is, does not get stuck), whereas in the latter all ill-typed expressions do not evaluate to a value.

Soundness of CBS w.r.t. ISS We prove now that the CBS is sound w.r.t.the ISS. More precisely, if $\emptyset \Vdash e \Rightarrow v$, then in the ISS either e diverges (that is, e does not reduce to a normal form), or e reduces in zero or more steps to a value v s.t. $\emptyset \Vdash v \Rightarrow v$. In other words, we are guaranteed that the evaluation of an expression will never get stuck in the ISS whenever it returns a value in the CBS. Under this point of view the CBS plays a role similar to that of a type system; indeed, to prove this property we use the standard proof technique based on the progress and subject reduction properties. Such a property tells us an important fact: type soundness of a type system can be equivalently proved in terms of the CBS, instead of the ISS. If soundness holds in terms of the CBS, then it holds in terms of the ISS as well, by virtue of the soundness property of the CBS w.r.t. the ISS we are going to prove.

The progress and subject reduction properties can be proved routinely (see Appendix B), the former by induction on e, the latter by induction on the rules defining ISS. Proof by coinduction is only needed for the substitution lemma.

Theorem 3 (Progress). If $\emptyset \Vdash e \Rightarrow v$, then either e is a value, or there exists e' s.t. $e \rightarrow e'$.

Subject reduction relies on the following restricted form of substitution lemma which suffices for proving Theorem 4.

Lemma 1 (Substitution). If $\overline{x}^n \mapsto \overline{v}^n \Vdash e \Rightarrow v$, and for all $i = 1..n \emptyset \Vdash v_i \Rightarrow v_i$, then $\emptyset \Vdash e[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow v$.

Theorem 4 (Subject reduction). *If* $\emptyset \Vdash e \Rightarrow v$, and $e \rightarrow e'$, then $\emptyset \Vdash e' \Rightarrow v$.

Corollary 1. If $\emptyset \Vdash e \Rightarrow v$, $e \stackrel{*}{\rightarrow} e'$, and e' is a normal form, then e' is a value, and $\emptyset \Vdash e' \Rightarrow v$.

Proof. By induction on the number n of steps needed to reduce e to e'. If n=0, then e=e', and trivially $\emptyset \Vdash e' \Rightarrow v$; furthermore, since e' is a normal form, by progress (Theorem 3) e' is a value. If n>0, then there exists e'' s.t. $e\to e''$, and e'' reduces to e' in n-1 steps. By subject reduction (Theorem 4) $\emptyset \Vdash e'' \Rightarrow v$, then we conclude by inductive hypothesis.

5 Type systems

To make the proof of soundness simpler and more modular, we first define a standard inductive nominal type system for our reference language, and then we derive from it a coinductive nominal type system, and prove that if an expression is well-typed in the inductive type system, than it is assigned the same type in the coinductive one. In other words, the inductive type system is sound w.r.t. the

coinductive one; we conjecture that in fact the two systems are equivalent (hence, the coinductive system is sound w.r.t. the inductive one as well), but here we prove only the only implication we are interested in. In this way, soundness of the inductive type system in terms of the CBS can be directly derived from soundness of the coinductive type system in terms of the CBS (prove in Section 6).

Auxiliary definitions Besides functions fields and meth, already used for defining both the ISS and the CBS, the typing rules are based on the following auxiliary functions/operators, whose definition can be found in Figure 11 in Appendix A. The standard subtyping relation \leq between nominal types; the override predicate s.t. override $(c, m, \overline{\tau}^n, \tau)$ holds iff meth(c', m) is undefined or $meth(c', m) = \overline{\tau'}^n \ \overline{x}^n.e:\tau', \ \overline{\tau'}^n \leq \overline{\tau}^n$, and $\tau \leq \tau'$, with c' direct superclass of c; the join operator \vee which computes the least upper bound $\vee(\tau_1, \tau_2)$ of two types τ_1 and τ_2 (this is always defined since inheritance is single, and bool is a subtype of the top type Object).

Typing rules The typing rules, which can be found in Figure 8, are quite standard. A type environment Γ is a finite sequence $\overline{x_i}^n:\overline{\tau}^n$, where all variables $\overline{x_i}^n$ are distinct, denoting a finite function mapping variables to types (\emptyset denotes the empty type environment, $dom(\Gamma)$ the domain of Γ). Rules (pro), (cla), and (met) define well-typed programs, classes, and methods, respectively. The other rules define well-typed expressions w.r.t. a given type environment. Let us recall that, similarly to what happens for the operational semantics, all typing judgments are implicitly indexed over a class table containing all needed information on the classes declared in the program.

$$(pro) \frac{\forall i = 1..n \vdash cd_i : \diamond \quad \emptyset \vdash e : \tau}{\vdash cd^n} \qquad (cla) \frac{\forall i = 1..k \ c \vdash md_i : \diamond \quad fields(c) \ defined}{\vdash \mathbf{class} \ c \ extends} \ c' \ \left\{ \ \overline{fd^n \ md^k} \ \right\} : \diamond}$$

$$(met) \frac{\mathbf{this} : c, \overline{x}^n : \overline{\tau}^n \vdash e : \tau \quad \tau \leq \tau_0 \quad override(c, m, \overline{\tau}^n, \tau_0)}{c \vdash \tau_0 \ m(\overline{\tau}^n \ \overline{x}^n) \ \left\{ e \right\} : \diamond}$$

$$(var) \frac{\Gamma(x) = \tau}{\Gamma \vdash x : \tau} \qquad (fal) \frac{\Gamma}{\Gamma} \vdash \mathbf{false} : bool \qquad (tru) \frac{\Gamma(ru)}{\Gamma} \vdash \mathbf{true} : bool$$

$$(new) \frac{\forall i = 1..n \ \Gamma \vdash e_i : \tau_i \quad fields(c) = \overline{\tau'}^n \ \overline{f}^n \quad \forall i = 1..n \ \tau_i \leq \tau'_i}{\Gamma \vdash \mathbf{new} \ c(\overline{e}^n) : c}$$

$$(fld) \frac{\Gamma \vdash e : c \quad fields(c) = \overline{\tau}^n \ \overline{f}^n \quad 1 \leq i \leq n}{\Gamma \vdash e : f_i : \tau_i} \qquad (if) \frac{\Gamma \vdash e : bool \quad \Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash \mathbf{if} \ (e) \ e_1 \ \mathbf{else} \ e_2 : \vee (\tau_1, \tau_2)}$$

$$(inv) \frac{\forall i = 0..n \ \Gamma \vdash e_i : \tau_i \quad meth(\tau_0, m) = \overline{\tau'}^n \ \overline{x}^n . e : \tau \quad \forall i = 1..n \ \tau_i \leq \tau'_i}{\Gamma \vdash e_0 .m(\overline{e}^n) : \tau}$$

 ${\bf Fig.\,8.}$ Nominal type system

Membership relation To prove soundness of the type system w.r.t. the CBS, we first define a relation $v \in \tau$ between the CBS values and nominal types: intuitively, such a relation defines the intended semantics of types as set of values [6,7]. Such a relation is coinductively defined by the following rules:

$$(\text{\tiny TOP}) \frac{\mathbf{v} \in \text{Object}}{\mathbf{v} \in \text{Object}} \frac{\mathbf{v} = false \text{ or } \mathbf{v} = true}{\mathbf{v} \in bool}$$

$$\frac{\forall \, i = 1..n \, \mathbf{v}_i \in \tau_i \quad c \leq c' \quad fields(c) = \overline{\tau}^n \, \overline{f}^n}{obj(c, [\overline{f}^n \mapsto \overline{\mathbf{v}}^n]) \in c'}$$

The membership relation is easily extended to environments and type environments:

$$\Pi \in \Gamma \Leftrightarrow dom(\Gamma) \subseteq dom(\Pi) \text{ and } \forall x \in dom(\Gamma) \Pi(x) \in \Gamma(x).$$

Coinductive type system The coinductive type system is derived from the inductive one defined in Figure 8 as follows:

- all rules for typing expressions are interpreted coinductively (rules for well-typed programs, classes, and methods can be indifferently interpreted inductively or coinductively, since they are not recursive);
- all rules are unchanged, except for rule (inv) which is modified in (co-inv):

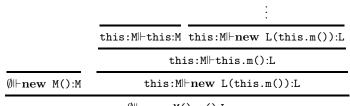
$$\begin{split} \forall \, i = 0..n \; \varGamma \Vdash e_i : \tau_i & \; \text{this} : \tau_0, \overline{x}^n : \overline{\tau}^n \Vdash e : \tau' \\ meth(\tau_0, m) &= \overline{\tau'}^n \; \overline{x}^n . e : \tau \quad \forall \, i = 1..n \; \tau_i \leq \tau'_i, \tau' \leq \tau \\ (\textit{co-inv}) & & & & & & \\ \hline \varGamma \Vdash e_0 . m(\overline{e}^n) : \tau & & & & \end{split}$$

Rule (co-inv) is clearly not compositional: instead of type checking a method once for all, and using subtyping and type safe overriding (as happens in the inductive system), the coinductive type system checks a method body, not only when it is declared (rule (cla)), but also whenever it is called. However, from a more theoretical point of view, the coinductive type system is a step closer to the CBS. Of course the type system must be interpreted coinductively, otherwise typechecking of recursive methods would always fail. Consider for instance case 2 (b) presented in Section 4. The judgment $\emptyset \Vdash \mathbf{new} \ M() .m() : L$ can be derived only with an infinite proof tree, as depicted in Figure 9. Note that the proof tree is isomorphic to the proof tree for $\emptyset \Vdash \mathbf{new} \ M() .m() \Rightarrow obj(L, [n \mapsto v])$ shown in Figure 6.

We can now prove soundness of the inductive type system w.r.t. the coinductive one.

The following lemmas are instrumental to the proof of the theorem 5 that follows; in the claims of all lemmas we implicitly assume that judgments refer to a well-typed program. All omitted proofs can be found in Appendix B.

Lemma 2. If
$$\tau'_1 \leq \tau_1$$
 and $\tau'_2 \leq \tau_2$ then $\leq \vee (\tau'_1, \tau'_2) \leq \vee (\tau_1, \tau_2)$.



 $\emptyset \vdash \mathbf{new} \ \texttt{M().m():L}$

Fig. 9. Proof for ∅⊩new M().m():L

Lemma 3. If $fields(c) = \overline{\tau}^n \overline{f}^n$, and $c' \leq c$, then $fields(c') = \overline{\tau}^m \overline{f}^m$ with $n \leq m$.

Lemma 4. If $meth(c, m) = \overline{\tau}^n \ \overline{x}^n.e:\tau$, then there exists c', τ' s.t. $c \leq c'$, $\tau \leq \tau$ and $this: c', \overline{x}^n:\overline{\tau}^n \vdash e:\tau'$.

Lemma 5. If $\overline{x}^n:\overline{\tau}^n \vdash e:\tau$ and for all i=1..n $\tau_i' \leq \tau_i$, then there exists τ' s.t. $\tau' \leq \tau$, and $\overline{x}^n:\overline{\tau'}^n \vdash e:\tau'$.

Theorem 5. Let \overline{cd}^n be well-typed class declarations. If $\Gamma \vdash e:\tau$ in \overline{cd}^n , then $\Gamma \Vdash e:\tau$ in \overline{cd}^n .

Proof. By coinduction on the rules defining the judgment $\bot\vdash$:.., and case analysis on e. The only interesting case is when e is a method invocation $e_0.m(\overline{e}^n)$, since for all other cases the rules of the two type systems coincide. If $\Gamma \vdash e:\tau$, then by definition of rule (inv) we have $\forall i = 0..n$ $\Gamma \vdash e_i:\tau_i$, $meth(\tau_0, m) = \overline{\tau'}^n \overline{x}^n.e:\tau$, and $\forall i = 1..n$ $\tau_i \leq \tau'_i$. By lemma 4 there exists τ'_0, τ' s.t. $\tau_0 \leq \tau'_0, \tau' \leq \tau$, and this: $\tau'_0, \overline{x}^n:\overline{\tau'}^n \vdash e:\tau'$; therefore, by lemma 5 there exists τ'' s.t. $\tau'' \leq \tau'$, and hence by transitivity (lemma 8) $\tau'' \leq \tau$, and this: $\tau_0, \overline{x}^n:\overline{\tau}^n \vdash e:\tau''$. We conclude by coinductive hypothesis and by definition of rule (co-inv).

6 Proof of soundness

In this section we prove the mid implication shown in Figure 1, which is the core of our result: soundness of the coinductive type system in terms of the CBS. Finally, by virtue of the soundness of the inductive type system w.r.t. the coinductive one (proved in Section 5), and of the soundness of the CBS w.r.t. the ISS (proved in Section 4), we can state soundness of the inductive type system in terms of the ISS as a simple corollary.

The following lemmas are instrumental to the proof of the theorem 6 that follows; in the claims of all lemmas we implicitly assume that judgments refer to a well-typed program. All omitted proofs can be found in Appendix B.

Lemma 6. $\tau_1 \leq \vee(\tau_1, \tau_2)$ and $\tau_2 \leq \vee(\tau_1, \tau_2)$.

Lemma 7. If $fields(c) = \overline{\tau}^n \overline{f}^n$, and $c \leq c'$, then $fields(c') = \overline{\tau}^m \overline{f}^m$ with $m \leq n$.

Lemma 8. The subtyping relation is transitive: if $\tau_1 \leq \tau_2$ and $\tau_2 \leq \tau_3$, then $\tau_1 \leq \tau_3$.

Lemma 9 (Soundness of subtyping). If $v \in \tau$ and $\tau \leq \tau'$, then $v \in \tau'$.

Lemma 10. If $meth(c, m) = \overline{\tau}^n \ \overline{x}^n.e:\tau \ and \ c' \leq c$, then $meth(c', m) = \overline{\tau'}^n \ \overline{x'}^n.e':\tau'$ where for all $i = 1..n \ \tau_i \leq \tau'_i \ and \ \tau' \leq \tau$.

To prove that the coinductive type system is sound w.r.t. the CBS, we coinductively define a concretization relation \mathcal{R}_{γ} between valid proof trees $\nabla \in VPT$ for $\Gamma \Vdash e:\tau$ and (possibly non valid) proof trees $\nabla \in PT \Rightarrow$ for $\Pi \Vdash e \Rightarrow v$, and show that for any valid proof tree $\nabla \in T \Vdash e:\tau$ and any $\Pi \in \Gamma$, there exists a value v and a valid proof tree $\nabla \in T \Vdash e:\tau$ and $\nabla \in T$ and $\nabla \in T$.

Definition 9. A relation $\mathcal{R} \subseteq VPT_: \times PT_{\Rightarrow}$ is a concretization iff the following constraints are satisfied:

$$-\frac{1}{\Gamma \Vdash x : \tau} \mathcal{R} \frac{1}{\Pi \Vdash x \Rightarrow v} \text{ iff } \Pi \in \Gamma, \text{ and } ok(var) \left(\frac{1}{\Pi \Vdash x \Rightarrow v} \right)$$

$$-\frac{1}{\Gamma \Vdash \text{false} : bool} \mathcal{R} \frac{1}{\Pi \Vdash \text{false} \Rightarrow false} \text{ iff } \Pi \in \Gamma$$

$$-\frac{1}{\Gamma \Vdash \text{true} : bool} \mathcal{R} \frac{1}{\Pi \Vdash \text{true} \Rightarrow true} \text{ iff } \Pi \in \Gamma$$

$$-\frac{1}{\Gamma \Vdash \text{true} : bool} \mathcal{R} \frac{1}{\Pi \Vdash \text{true} \Rightarrow true} \text{ iff } \Pi \in \Gamma$$

$$-\frac{1}{\Gamma \Vdash \text{new } c(\overline{e}^n) : c} \mathcal{R} \frac{1}{\Pi \Vdash \text{new } c(\overline{e}^n) \Rightarrow v} \text{ iff for all } i = 1..n \text{ } _{\parallel} \nabla_i \mathcal{R} \text{ } _{\parallel} \nabla_i, \Pi \in \Gamma, \text{ and } ok(\text{NEW}) \left(\frac{1}{\Pi \vdash \text{new } c(\overline{e}^n) \Rightarrow v} \right)$$

$$-\frac{1}{\Gamma \vdash \text{new } c(\overline{e}^n) : c} \mathcal{R} \frac{1}{\Pi \vdash \text{new } c(\overline{e}^n) \Rightarrow v} \text{ iff } _{\parallel} \nabla \mathcal{R} \text{ } _{\parallel} \nabla, v \in \tau, \Pi \in \Gamma, \text{ and } ok(\text{FLD}) \left(\frac{1}{\Pi \vdash \text{ne}, f \Rightarrow v} \right)$$

$$-\frac{1}{\Gamma \vdash \text{if } (e) e_1 \text{ else } e_2 : \tau} \mathcal{R} \frac{1}{\Pi \vdash \text{if } (e) e_1 \text{ else } e_2 \Rightarrow v} \text{ iff } _{\parallel} \nabla \mathcal{R} \text{ } _{\parallel} \nabla, \Pi \text{ } _{\parallel} \nabla, root(\text{ } _{\parallel} \nabla) = \Pi \text{ } _{\parallel} \nabla \text{ } _{\parallel} \nabla, root(\text{ } _{\parallel} \nabla) = \Pi \text{ } _{\parallel} \nabla, root(\text{ } root(\text{ } _{\parallel} \nabla, root(\text{ } _{\parallel} \nabla, root(\text{ } _{\parallel} \nabla, root(\text{ } root(\text{ } _{\parallel} \nabla, root(\text{ } _{\parallel} \nabla, root(\text{ } _{\parallel} \nabla, root(\text{ } root(\text{ }$$

$$\begin{split} &-\frac{\mathbf{p} \nabla_0 \ \mathbf{p} \overline{\nabla}^n \ \mathbf{p} \nabla}{\Gamma \Vdash e_0.m(\overline{e}^n):\tau} \ \mathcal{R} \ \frac{\mathbf{p} \nabla_0 \ \mathbf{p} \overline{\nabla}^n \ \mathbf{p} \nabla}{\Pi \Vdash e_0.m(\overline{e}^n) \Rightarrow \mathbf{p}} \ iff \ for \ all \ i = 0..n \ \mathbf{p} \nabla_i \mathcal{R} \mathbf{p} \nabla_i, \ \mathbf{p} \mathcal{R} \mathbf{p} \nabla_i, \ \mathbf{p} \nabla \mathcal{R}$$

The function \mathcal{F} corresponding to the recursive definition of concretization relation is trivially monotone on the complete lattice defined by the power set of $VPT \times PT \Rightarrow$, therefore by the Tarski-Knaster theorem there exists the greatest concretization relation, denoted by \mathcal{R}_{γ} . However, the Tarski-Knaster theorem does not provide any guarantee that for any valid proof tree \mathbb{P} for $\Gamma \Vdash e:\tau$ and any $\Pi \in \Gamma$, there exists a value \mathbb{P} and a valid proof tree \mathbb{P} for $\Pi \Vdash e \Rightarrow \mathbb{P}$ s.t. $\mathbb{P} \mathcal{R}_{\gamma} \mathbb{P}$, and $\mathbb{P} \in \Gamma$. To prove such a property we need to apply the Kleen theorem; indeed, \mathcal{F} also preserves infima of descending chains in the same complete lattice, hence, the concretization relation \mathcal{R}_{γ} is defined by $\mathbb{P} \in \mathbb{P}$, where Γ denotes the top element of the lattice defined by the power set of $\mathbb{P} \in \mathbb{P}$, that is, the relation associating any valid proof tree for the judgment $\mathbb{P} : \mathbb{P} \to \mathbb{P}$, with any proof tree for the judgment $\mathbb{P} \to \mathbb{P}$. We abbreviate $\mathcal{F}^n(\Gamma)$ with \mathcal{R}^n_{γ} , hence $\mathcal{R}^0 = \Gamma$.

As an example, we have that $\nabla^e \mathcal{R}_{\gamma} = \nabla^e$, where ∇^e and ∇^e are the proof trees defined in Figure 9 and 6, respectively. The easiest way to prove this fact is to show that there exists a concretization relation \mathcal{R} s.t. $\nabla^e \mathcal{R} = \nabla^e$; this can be achieved by considering the finite relation that associates each subtree of ∇^e (including ∇^e itself), with the corresponding subtree³ of ∇^e (including ∇^e itself); it is immediate to verify that such a relation is a concretization.

However, when proving soundness the proof tree for the CBS is unknown, and therefore its existence is proved by showing that it can be obtained as the limit of a Cauchy sequence in a complete metric space. Therefore, to better understand the proof that will follow, it is instructive to show how the proof tree ∇^e can actually be built from ∇^e by using the Kleen construction. We assume that the expression is evaluated in a program where the only available classes are M and L as declared for case 2 (b) in Section 4, and we use ellipses ... as a wildcard.

$$- \nabla^{e} \mathcal{R}_{\gamma}^{0} \Rightarrow \text{ for any } \Rightarrow \mathcal{P} \in PT_{\Rightarrow}.$$

$$- \nabla^{e} \mathcal{R}_{\gamma}^{1} \Rightarrow \text{ for any } \Rightarrow \mathcal{P} \in PT_{\Rightarrow} \text{ s.t. } \Rightarrow \mathcal{P} = \dots$$

$$\dots$$

$$\boxed{\Pi | \text{hew M()} \Rightarrow \text{ whis } \mapsto \text{ where } \text{L(this.m())} \Rightarrow \text{ w}_{0}}$$

$$\boxed{\Pi | \text{hew M()} \cdot \text{m()} \Rightarrow \text{ w}_{0}}$$

where $\Pi \in \emptyset$ (hence, Π can be any value environment), \mathbf{v} can be any value, and $\mathbf{v}_0 \in \mathbf{L}$, hence for all $i \in \mathbb{N}$, $\mathbf{v}_i = obj(\mathbf{L}, [\mathbf{n} \mapsto \mathbf{v}_{i+1}])$, therefore \mathbf{v}_0 is the unique value s.t. $\mathbf{v}_0 = obj(\mathbf{L}, [\mathbf{n} \mapsto \mathbf{v}_0])$ and $\mathbf{v}_i = \mathbf{v}_{i+1}$, for all $i \in \mathbb{N}$. Note that, since we have assumed that \mathbf{M} and \mathbf{L} are the only available classes of the

³ We recall that the two trees are isomorphic; furthermore, they have a finite number of subtrees, since they are regular.

program, there exists only one possible subtype of L, namely L itself, and the equations above can be directly derived by applying membership rule OBJ. Therefore, for this particular case we get the returned value (in this particular case it is unique) just at the first iteration; however, for getting the corresponding valid proof tree all iterations have to be considered.

We proceed with the next iteration, to show how at each step the obtained proof trees are better approximations of a valid proof tree.

$$-\nabla^e \mathcal{R}^2 \nabla$$
 for any $\nabla \in PT \Rightarrow \text{s.t. } \nabla =$

$$\frac{}{ \text{this} \mapsto obj(\mathtt{M},[\]) \Vdash_{\mathtt{this}.\mathtt{m}()} \Rightarrow \mathtt{V}_0 } \\ \overline{\Pi \Vdash_{\mathbf{new}\ \mathtt{M}()} \Rightarrow obj(\mathtt{M},[\])} \xrightarrow{\mathtt{this} \mapsto obj(\mathtt{M},[\]) \Vdash_{\mathbf{new}\ \mathtt{L}(\mathtt{this}.\mathtt{m}())} \Rightarrow \mathtt{V}_0 } \\ \overline{\Pi \Vdash_{\mathbf{new}\ \mathtt{M}().\mathtt{m}()} \Rightarrow \mathtt{V}_0 }$$

where $\Pi \in \emptyset$ (hence, Π can be any value environment). Note that, by virtue of the equation $v_0 = obj(L, [n \mapsto v_0])$, the evaluation of **new L(this.m())** and of this.m() returns the same vale v_0 .

It can be easily proved by standard induction over n that $\nabla^e \mathcal{R}^n_{\gamma} \supset \nabla^e$, for all $n \in \mathbb{N}$, where ∇^e is the valid proof tree defined in Figure 6; since \mathcal{R}_{γ} is the greatest lower bound of $\{\mathcal{R}^n_{\gamma} | n \in \mathbb{N}\}$, we obtain that $\nabla^e \mathcal{R}_{\gamma} \supset \nabla^e$.

To prove the main claim from which soundness of the coinductive type system w.r.t. the CBS can be derived, we need to define a complete metric space of proof trees for the CBS.

We first define the metric of value environment. We recall that a value environment is a finite partial function mapping variables to values, and that values are finitely branching trees with infinite paths (hence, they form a complete metric space with the distance d_T of Definition 1).

Proposition 2. The set of value environments forms a complete metric space when equipped with the distance d_{Π} defined as follows:

$$d_{\Pi}(\Pi_{1},\Pi_{2}) = \begin{cases} 1 & \text{if } dom(\Pi_{1}) \neq dom(\Pi_{2}) \\ \max(\{0\} \cup \{d_{T}(\Pi_{1}(x),\Pi_{2}(x)) \mid x \in D\}) & \text{if } D = dom(\Pi_{1}) = dom(\Pi_{2}) \end{cases}$$

Proof. We first note that $\{0\} \subseteq \{0\} \cup \{d_T(\Pi_1(x), \Pi_2(x)) \mid x \in D\} \subseteq \{0\} \cup \{2^{-c} \mid c \in \mathbb{N}\}$ (see Proposition 1), therefore there always exists $\max(\{0\} \cup \{d_T(\Pi_1(x), \Pi_2(x)) \mid x \in D\})$, and for all pairs of environments Π_1 and Π_2 , $d_{\Pi}(\Pi_1, \Pi_2) \in \{0\} \cup \{2^{-c} \mid c \in \mathbb{N}\}$, hence $0 \leq d_{\Pi}(\Pi_1, \Pi_2) \leq 1$.

- (identity): let $D = dom(\Pi_1)$, then $\Pi_1 = \Pi_2$ iff $dom(\Pi_1) = dom(\Pi_2)$ and for all $x \in D$ $\Pi_1(x) = \Pi_2(x)$ iff $dom(\Pi_1) = dom(\Pi_2)$ and for all $x \in D$ $d_T(\Pi_1(x), \Pi_2(x)) = 0$ (since d_T is a metric) iff $dom(\Pi_1) = dom(\Pi_2)$ and $max(\{0\} \cup \{d_T(\Pi_1(x), \Pi_2(x)) \mid x \in D\}) = 0$ iff $d_{\Pi}(\Pi_1, \Pi_2) = 0$.
- (symmetry) immediate (since d_T is a metric).
- (triangle inequality): Let $dom(\Pi_1) = dom(\Pi_3) = D$; if $D = \emptyset$, then trivially $d_{\Pi}(\Pi_1, \Pi_3) = 0 \le d_{\Pi}(\Pi_1, \Pi_2) + d_{\Pi}(\Pi_2, \Pi_3)$. Otherwise, if $D \ne \emptyset$,

then $d_{\Pi}(\Pi_1, \Pi_3) = d_T(\Pi_1(x_0), \Pi_3(x_0))$ for some $x_0 \in D$; if $dom(\Pi_2) = D$, then $d_T(\Pi_1(x_0), \Pi_3(x_0)) \leq d_T(\Pi_1(x_0), \Pi_2(x_0)) + d_T(\Pi_2(x_0), \Pi_3(x_0)) \leq d_{\Pi}(\Pi_1, \Pi_2) + d_{\Pi}(\Pi_2, \Pi_3) \ (d_T \text{ is a metric, and definition of } d_{\Pi})$; if $dom(\Pi_2) \neq D$, then $d_T(\Pi_1(x_0), \Pi_3(x_0)) \leq 2 = d_{\Pi}(\Pi_1, \Pi_2) + d_{\Pi}(\Pi_2, \Pi_3)$ (definition of d_T and d_{Π}).

If $dom(\Pi_1) \neq dom(\Pi_3)$, then $d_{\Pi}(\Pi_1, \Pi_3) = 1$, and $dom(\Pi_2) \neq dom(\Pi_1)$ or $dom(\Pi_2) \neq dom(\Pi_3)$, therefore $1 \leq d_{\Pi}(\Pi_1, \Pi_2) + d_{\Pi}(\Pi_2, \Pi_3)$ (definition of d_{Π}).

We now prove the completeness of the metric space. Let $(\Pi_i)_{i\in\mathbb{N}}$ be a Cauchy sequence. Since $dom(\Pi_n) \neq dom(\Pi_m)$ implies $d_\Pi(\Pi_n,\Pi_m) = 1$, there exists $k_0 \in \mathbb{N}$ s.t. for all $n, m > k_0$, $dom(\Pi_n) = dom(\Pi_m) = D$, hence, $d_\Pi(\Pi_n,\Pi_m) = \max(\{0\} \cup \{d_T(\Pi_n(x),\Pi_m(x)) \mid x \in D\})$. If $D = \emptyset$, then for all $n, m > k_0$ $d_\Pi(\Pi_n,\Pi_m) = 0$, hence $\Pi_n = \Pi_m$ and the limit of the sequence is trivially the empty value environment \emptyset . If $D \neq \emptyset$, then we have that for all $x \in D$ and $n, m > k_0$, $d_T(\Pi_n(x),\Pi_m(x)) \leq d_\Pi(\Pi_n,\Pi_m)$, and therefore, for all $x \in D$, $(\Pi_i(x))_{i\in\mathbb{N}\setminus[0,k_0]}$ is a Cauchy sequence. By completeness of the metric space of trees we deduce that for all $x \in D$, $(\Pi_i(x))_{i\in\mathbb{N}\setminus[0,k_0]}$ has limit v_x , therefore the limit of $(\Pi_i)_{i\in\mathbb{N}}$ is the value environment Π with domain D s.t. $\Pi(x) = v_x$ for all $x \in D$. This can be proved thanks to the finiteness of D. Indeed, given an arbitrary $\epsilon > 0$, for any $x \in D$ one can find $h_x \in \mathbb{N}$, $h_x > k_0$ s.t. for all $n > h_x$, $d_T(\Pi_n(x), v_x) < \epsilon$. Since D is finite, $h_0 = \max\{h_x | x \in D, h_x \in \mathbb{N}\}$ is always defined, therefore for any $\epsilon > 0$ there exists h_0 s.t. for all $n > h_0$, $d_\Pi(\Pi_n, \Pi) < \epsilon$.

Proposition 3. The set of pairs of value environments and values forms a complete metric space when equipped with the distance $d_{\Pi, \mathbf{v}}$ defined as follows:

$$d_{\Pi, \mathbb{V}}((\Pi_1, \mathbb{V}_1), (\Pi_2, \mathbb{V}_2)) = \max\{d_{\Pi}(\Pi_1, \Pi_2), d_{\Pi, \mathbb{V}}(\mathbb{V}_1, \mathbb{V}_2)\}$$

Proof. A well known property of product metric spaces that can be easily checked. From Property 2 one can easily deduce that $0 \leq d_{\Pi,\mathbf{v}}((\Pi_1,\mathbf{v}_1),(\Pi_2,\mathbf{v}_2)) \leq 1$, since $d_{\Pi,\mathbf{v}}((\Pi_1,\mathbf{v}_1),(\Pi_2,\mathbf{v}_2)) \in \{0\} \cup \{2^{-c} \mid c \in \mathbb{N}\}.$

Let j be the judgment $\Pi \Vdash e \Rightarrow v$, then ev(j) and exp(j) denote (Π, v) and e, respectively; furthermore, $exp(\mathfrak{D})$ denotes the tree t over expressions s.t. $dom(t) = dom(\mathfrak{D})$, and for all $p \in dom(t)$ $t(p) = exp(\mathfrak{D}(p))$.

Proposition 4. The set PT_{\Rightarrow} of proof trees for $\Pi \Vdash e \Rightarrow \forall$ forms a complete metric space when equipped with the distance d_{∇} defined as follows:

$$d_{\nabla}(\nabla_1, \nabla_2) = \max(\{2^{-c}\} \cup S)$$
 where

 $S = \{2^{-k} \cdot d_{\Pi,\mathbf{v}}(ev(\mathbf{v}_1(p)), ev(\mathbf{v}_2(p))) \mid p \in \mathbb{N}^k \cap dom(\mathbf{v}_1), 0 \leq k < c\}$ $c = shtp(exp(\mathbf{v}_1), exp(\mathbf{v}_2)), \ that \ is, \ c = \min\{n \in \mathbb{N} \mid p \in \mathbb{N}^n, exp(\mathbf{v}_1(p)) \neq_{\perp} exp(\mathbf{v}_2(p))\} \ (see \ Proposition \ 1 \ for \ the \ definition \ of \ shtp \ and \ the \ related \ notation).$

Proof. Before proving that d_{∇} is a metric, we note that if $0 \leq k < c$, then $\mathbb{N}^k \cap dom(\mathbb{T}_1) = \mathbb{N}^k \cap dom(\mathbb{T}_2)$, because $exp(\mathbb{T}_1(p)) =_{\perp} exp(\mathbb{T}_2(p))$, hence $d_{\Pi,\mathbb{V}}(ev(\mathbb{T}_1(p)), ev(\mathbb{T}_2(p)))$ is always well-defined in S; furthermore, trivially $\{2^{-c}\} \cup S \neq \emptyset$, and, by the property of $d_{\Pi,\mathbb{V}}$ (Proposition 3), $\{2^{-c}\} \cup S \subseteq \{0\} \cup \{2^{-k} \mid k \in \mathbb{N}\}$, therefore $\max(\{2^{-c}\} \cup S)$ is always defined, and $0 \leq d_{\nabla}(\mathbb{T}_1,\mathbb{T}_2) \leq 1$.

- (identity) if $\[\[\] \] = \[\] \] \bigvee_1 = \[\] \] \bigvee_2$, then $shtp(exp(\[\] \] \bigvee_1), exp(\[\] \] \bigvee_2) = \min \emptyset = \infty$, therefore $d_{\nabla}(\[\] \] \bigvee_1, \[\] \] \bigvee_2 = \max(\{2^{-\infty}\} \cup S) = 0$, since $ev(\[\] \] \bigvee_1(p)) = ev(\[\] \] \bigvee_2(p)$ for all $p \in dom(\[\] \] \bigvee_1$, and $d_{\Pi, \mathbb{V}}$ is a metric.
- (symmetry) a direct consequence of the fact that $d_{\Pi,\mathbf{v}}$ is a metric (Proposition 3), \neq_{\perp} is a symmetric relation and the following property holds (as already remarked above): if $p \in \mathbb{N}^k$ with $0 \leq k < c$, then $p \in dom(\ \nabla_1)$ iff $p \in dom(\ \nabla_2)$.
- (triangle inequality) If $c_i = shtp(exp(\supdetengred{\belowdisplayskip}\xspace_i), exp(\supdetengred{\belowdisplayskip}\xspace_i), exp(\supdetengred{\belowdisplayskip}\x$
 - 1. $2^{-c} \le 2^{-c_0}$ (since $c_0 \le c$), $2^{-c_0} \le 2^{-c_1} + 2^{-c_2}$ (since $c_0 = \min\{c_1, c_2\}$ and 2^n is always non negative), and $2^{-c_1} + 2^{-c_2} \le d_2 + d_3$ (by definition of d_{∇}), therefore $2^{-c} \le d_2 + d_3$.
 - 2. for all $k \in \mathbb{N}$, $k < c_0$, and for all paths $p \in \mathbb{N}^k \cap dom(\mathbb{T}_1)$, we have that $2^{-k} \cdot d_{\Pi,\mathbf{v}}(ev(\mathbb{T}_1(p)), ev(\mathbb{T}_3(p))) \leq 2^{-k} \cdot (d_{\Pi,\mathbf{v}}(ev(\mathbb{T}_1(p)), ev(\mathbb{T}_2(p))) + d_{\Pi,\mathbf{v}}(ev(\mathbb{T}_2(p)), ev(\mathbb{T}_3(p))) = 2^{-k} \cdot d_{\Pi,\mathbf{v}}(ev(\mathbb{T}_1(p)), ev(\mathbb{T}_2(p))) + 2^{-k} \cdot d_{\Pi,\mathbf{v}}(ev(\mathbb{T}_2(p)), ev(\mathbb{T}_3(p))) \leq d_2 + d_3$, since $d_{\Pi,\mathbf{v}}$ is a metric, and by definition of $d_{\mathbb{T}}$.
 - 3. for all $k \in \mathbb{N}$, $k \geq c_0$, we have that $2^{-k} \cdot d_{\Pi, \mathbf{v}}(ev(\mathbf{v}_1(p)), ev(\mathbf{v}_3(p))) \leq 2^{-c_0}$ (recall that $d_{\Pi, \mathbf{v}}$ always returns values between 0 and 1), hence by fact $1, 2^{-k} \cdot d_{\Pi, \mathbf{v}}(ev(\mathbf{v}_1(p)), ev(\mathbf{v}_3(p))) \leq d_2 + d_3$.

Since $d_1 = \max(\{2^{-c}\} \cup \{2^{-k} \cdot d_{\Pi, \mathbf{v}}(ev(\mathbf{v}_1(p)), ev(\mathbf{v}_2(p))) \mid p \in \mathbb{N}^k \cap dom(\mathbf{v}_1), 0 \leq k < c\})$ and all elements of such a set are less or equal than $d_2 + d_3$, we can deduce that $d_1 \leq d_2 + d_3$.

The limit ∇ of our Cauchy sequence is defined as follows: let $p \in \mathbb{N}^c$, then we consider the element of the sequence ∇_h with $h = h_c + 1$. Two cases can occur.

- if $p \notin dom(\nabla_h)$, then $p \notin dom(\nabla)$;
- otherwise, $p \in dom(\ \ \ \ \ \ \ \ \ \ \)$, therefore we have to define the judgment $\Pi_p \Vdash e_p \Rightarrow$ \mathbb{V}_p corresponding to $\mathbb{T}(p)$. Clearly, $e_p = exp(\mathbb{T}_h)$, since $exp(\mathbb{T}_h) = exp(\mathbb{T}_n)$ for all n > h. By definition of the metric d_{∇} and by the fact that $(\mathbb{P}_i)_{i \in \mathbb{N}}$ is a Cauchy sequence, we have that for all $\epsilon > 0$ there exist n, m > h s.t. 2^{-c} . $d_{\Pi,\mathbf{v}}(ev(\mathbf{v}(\mathbf{v}_n(p)), ev(\mathbf{v}_m(p))) < 2^{-c} \cdot \epsilon, \text{ hence } d_{\Pi,\mathbf{v}}(ev(\mathbf{v}_n(p)), ev(\mathbf{v}_m(p))) < 2^{-c} \cdot \epsilon, \mathbf{v}_m(p)$ ϵ , therefore $(ev(\nabla_i \nabla_i(p)))_{i \in \mathbb{N} \setminus [0,h]}$ is a Cauchy sequence. By proposition 3, the set of pairs of value environments and values forms a complete metric space, therefore the sequence $(ev(_{\Rightarrow}\nabla_i(p)))_{i\in\mathbb{N}\setminus[0,h]}$ has limit, and we define Π_p and \mathbf{v}_p to be the components of such a limit.

Finally, we have to show that ∇ as defined above is actually the limit of our Cauchy sequence $(\nabla_i)_{i\in\mathbb{N}}$. For any $\epsilon>0$, let $c\in\mathbb{N}$ be s.t. $2^{-c}<\epsilon$; by construction, for all paths $p \in \mathbb{N}^k \cap dom(\nabla)$ with $0 \leq k \leq c$, there exists a Cauchy sequence $(ev(\nabla_i(p)))_{i\in\mathbb{N}\setminus[0,h]}$ with $h=h_k+1$ whose limit is $ev(\nabla(p))$. Since the set of such paths is finite, there exists $l \in \mathbb{N}$ s.t. for all i > l $d_{\Pi,\mathbf{v}}(ev(\mathbf{v}(\mathbf{v}_i(p)), ev(\mathbf{v}(p))) < 2^{-c} \text{ and } shtp(exp(\mathbf{v}_i), exp(\mathbf{v})) > c.$

Our final claim is that $d_{\nabla}(\nabla_i \nabla_i, \nabla) < 2^{-c} < \epsilon$ for all i > l. Indeed, (1) $shtp(exp(\ \ \ \ \ \ \), exp(\ \ \ \ \ \)) > c$ by construction; (2) for all paths $p \in \mathbb{N}^k \cap dom(\ \ \ \ \ \ \)$ 2^{-c} by construction; (3) for all paths $p \in \mathbb{N}^k \cap dom(\nabla)$ with $k > c, 2^{-k}$. $d_{\Pi,\mathbb{V}}(ev(\nabla_i(p)), ev(\nabla_i(p))) \leq 2^{-k} < 2^{-c}.$

Let us consider the Kleene approximations \mathcal{R}^{i}_{γ} $(i \in \mathbb{N})$ of the concretization relation \mathcal{R}_{γ} . Then the following lemma holds, where we assume that judgments are indexed over a class table corresponding to a sequence of well-typed classes \overline{cd}^n .

Lemma 11 (Substitution). Let ∇ be a valid proof tree for $\Gamma \vdash e:\tau$, and ∇ a (not necessarily valid) proof tree for $\Pi \Vdash e \Rightarrow \forall$. For all $n \in \mathbb{N}$, if the following facts hold:

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1. \nabla \mathcal{R}_{\gamma}^n \nabla
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- 2. $\Pi, \Pi' \in \Gamma$, $d_{\Pi}(\Pi, \Pi') \leq 2^{-n}$ 3. there exists ∇' s.t. $\nabla \mathcal{R}_{\gamma}^{n+1} \nabla'$ and $d_{\nabla}(\nabla, \nabla') \leq 2^{-n}$

then there exists a proof tree ∇'' for $\Pi' \Vdash e \Rightarrow \forall'$ s.t. $\nabla \mathcal{R}_{\gamma}^{n+1} \nabla''$ and $d_{\nabla}(\nabla, \nabla'') \leq \nabla \mathcal{R}_{\gamma}^{n+1} \nabla''$ 2^{-n} .

Proof. The proof is by induction on n, and by case analysis on the expression e.

Lemma 12. For all $n \in \mathbb{N}$, $\nabla \in VPT_{:}$, and $\nabla \in PT_{\Rightarrow}$, if $\nabla \mathcal{R}_{\gamma}^{n} \nabla$, then there

Proof. The proof is by induction on n, and by case analysis on the expression e.

Basis: If n=0, then by definition $\mathcal{R}^0_{\gamma}=\top$, and, hence, $\nabla \mathcal{R}^0_{\gamma}$ for all $\nabla \in VPT$:, and $\nabla \in PT$; therefore we have to show that there exists ∇' s.t. $\nabla \mathcal{R}^1_{\gamma}$. Let us consider the case where $e=e_0.m(\overline{e}^n)$ (for all other cases the proof is analogous). If ∇ is a proof tree for $\Gamma \vdash e_0.m(\overline{e}^n)$: τ , then by rule (co-inv) we have that $\Gamma \vdash e_0:\tau_0$ and $meth(\tau_0,m)=\overline{\tau'}^n$ $\overline{x}^n.e:\tau$. By definition of membership, there always exist Π and ∇ s.t. $\Pi \in \Gamma$, and $\nabla \in \tau$, hence we can pick any Π and ∇ s.t. $\Pi \in \Gamma$, and ∇ build the following (not necessarily valid) proof tree:

$$\mathbf{V}' = \frac{\forall \, i = 0..n \, \frac{}{\prod | \vdash e_i \Rightarrow \mathbf{v}_i } \quad \frac{}{\text{this} \mapsto \mathbf{v}_0, \overline{x}^n \mapsto \overline{\mathbf{v}}^n | \vdash e \Rightarrow \mathbf{v}_0, \overline{x}^n \mapsto \overline{\mathbf{v}}^n | \vdash e \Rightarrow \mathbf{v}_0, \overline{x}^n \mapsto \overline{\mathbf{v}}^n | \vdash e \Rightarrow \overline{\mathbf{v}}_0, \overline{x}^n \mapsto \overline{\mathbf{v}}^n | \vdash e \mapsto \mapsto \overline{\mathbf{v}^n | \vdash e \mapsto \overline{\mathbf{v}}^n | \vdash e \mapsto \overline{\mathbf{v}^n | \vdash e \mapsto \overline{\mathbf{v}}^n |$$

with $\mathbf{v}_0 = obj(\tau_0, [\ldots])$ and $meth(\tau_0, m) = \overline{\tau'}^n \overline{x}^n.e:\tau$. Clearly, $\nabla \mathcal{R}^1_{\gamma} \nabla'$, since by definition 9, and by definition of \mathcal{R}^1_{γ} ,

$$\frac{\mathbb{Z}_{0} \mathbb{Z}^{n} \mathbb{Z}^{n}}{\Gamma \Vdash e_{0}.m(\overline{e}^{n}):\tau} \mathcal{R}_{\gamma}^{1} \frac{\mathbb{Z}_{0} \mathbb{Z}^{n} \mathbb{Z}^{n}}{\Pi \Vdash e_{0}.m(\overline{e}^{n}) \Rightarrow \mathbf{v}} \text{ iff for all } i = 0..n \mathbb{Z}_{i} \mathcal{R}_{\gamma}^{0} \mathbb{Z}_{i}, \mathbb{Z} \mathcal{R}_{\gamma}^{0} \mathbb{Z}_{i}, \mathbb{Z}_{\gamma}^{0} \mathbb{Z}_{i}, \mathbb{Z}_{i}, \mathbb{Z}_{\gamma}^{0} \mathbb{Z}_{i}, \mathbb{Z}_{\gamma}^{0} \mathbb{Z}_{i}, \mathbb{Z}_{i}^{0} \mathbb{Z}_{i}, \mathbb{Z}_{i}^{0} \mathbb{Z}_{i}, \mathbb{Z}_{i}^{0} \mathbb{Z}_{i}, \mathbb{Z$$

$$\mathbf{v} \in \tau, \ \Pi \in \Gamma, \ \mathrm{and} \ ok(\mathbf{n}\mathbf{v}) \left(\frac{\mathbf{v} \cdot \mathbf{v}}{\Pi \vdash e_0.m(\overline{e}^n) \Rightarrow \mathbf{v}} \right).$$

Inductive step: we have to prove that for all $n \geq 1$, $\nabla \mathcal{R}_{\gamma}^{n-1} \Rightarrow \exists \nabla'$ s.t. $\nabla \mathcal{R}_{\gamma}^{n} \Rightarrow \exists \nabla'$ s.t. $\nabla \mathcal{R}_{\gamma}^{n} \Rightarrow \exists \nabla'$ s.t. $\nabla \mathcal{R}_{\gamma}^{n+1} \Rightarrow \forall'$, and $d_{\nabla}(\nabla, \nabla') \leq 2^{-n+1}$ implies $\nabla \mathcal{R}_{\gamma}^{n} \Rightarrow \exists \nabla'$ s.t. $\nabla \mathcal{R}_{\gamma}^{n+1} \Rightarrow \forall'$, and $d_{\nabla}(\nabla, \nabla') \leq 2^{-n}$.

As for the basis, we consider the case where $e = e_0.m(\overline{e}^n)$ (for all other cases the proof is analogous). Therefore let us assume that $\nabla \mathcal{R}^n_{\gamma} \nabla$, where ∇ is a valid proof tree for $\Gamma \vdash e_0.m(\overline{e}^n)$: τ . By rule (co-inv) we have

$$\mathbf{p} = \frac{\mathbf{p}_0 \mathbf{p}^n \mathbf{p}'}{\Gamma \mathbf{p}_0 . m(\overline{e}^n) : \tau}$$

with $meth(\tau_0, m) = \overline{\tau'}^n \overline{x}^n.e:\tau, \forall i = 1..n \ \tau_i \leq \tau'_i, \ \tau' \leq \tau, \text{ and where } \forall i = 1..n \ \tau_i \leq \tau'_i, \ \tau' \leq \tau$

$$1..n\ root(\mathbf{p}_i) = \frac{\vdots}{\Gamma \Vdash e_i : \tau_i}, root(\mathbf{p}') = \frac{\vdots}{\mathtt{this} : \tau_0, \overline{x}^n : \overline{\tau}^n \Vdash e : \tau'}.$$

Since $\nabla \mathcal{R}_{\gamma}^n \nabla$, by Definition 9 and by definition of \mathcal{R}_{γ}^n we have

$$\mathbf{v} = \frac{\mathbf{v}_0 \ \mathbf{v}^n \ \mathbf{v}'}{\Pi \Vdash e_0.m(\overline{e}^n) \Rightarrow \mathbf{v}}$$

and for all i=0..n $\nabla_i \mathcal{R}_{\gamma}^{n-1} \mathcal{T}_i$, $\nabla' \mathcal{R}_{\gamma}^{n-1} \mathcal{T}'$, $\mathbf{v} \in \tau$, $\Pi \in \Gamma$, and $ok(\mathbf{n}\mathbf{v})(\mathcal{T})$. Then by inductive hypothesis we have that there exist $\mathcal{T}_0', \ldots, \mathcal{T}_n'$ and \mathcal{T}'' s.t.

for all i=0..n $\nabla_i \mathcal{R}^n_{\gamma} \mathcal{D}'_i$, $d_{\nabla}(\mathcal{D}_i, \mathcal{D}'_i) \leq 2^{-n+1}$, $\nabla' \mathcal{R}^n_{\gamma} \mathcal{D}''$, $d_{\nabla}(\mathcal{D}', \mathcal{D}'') \leq 2^{-n+1}$. Therefore we have that for all i=0..n $root(\mathcal{D}'_i) = \Pi_i \Vdash e_i \Rightarrow \mathsf{v}_i$, $root(\mathcal{D}'') = \Pi' \Vdash e \Rightarrow \mathsf{v}'$, with $\Pi_i \in \Gamma$, $\Pi' \in (\mathsf{this}:\tau_0, \overline{x}^n:\overline{\tau}^n)$, $\mathsf{v}_i \in \tau_i$ (hence, $\mathsf{v}_0 = obj(\tau_0, [\ldots])$) and $\mathsf{v}' \in \tau$. By lemma 11 we can derive from \mathcal{D}'_i (i=0..n) and from \mathcal{D}'' the proof trees \mathcal{D}''_i (i=0..n) and \mathcal{D}''' s.t. for all i=0..n $\nabla_i \mathcal{R}^n_{\gamma} \mathcal{D}''_i$, $d_{\nabla}(\mathcal{D}_i, \mathcal{D}'_i, \mathcal{D}''_i) \leq 2^{-n+1}$, $\mathcal{D}'\mathcal{R}^n_{\gamma} \mathcal{D}'''$, $d_{\nabla}(\mathcal{D}', \mathcal{D}'') \leq 2^{-n+1}$, and $root(\mathcal{D}''_i) = \Pi \Vdash e_i \Rightarrow \mathsf{v}'_i$, $root(\mathcal{D}''') = \mathsf{this} \mapsto \mathsf{v}'_0, \overline{x}^n \mapsto \overline{\mathsf{v}'}^n \Vdash e \Rightarrow \mathsf{v}''$

Finally, the proof tree

$$\mathbf{\bar{p}} = \frac{\mathbf{\bar{p}}_0'' \mathbf{\bar{p}}''^n \mathbf{\bar{p}}''^n}{\Gamma \vdash e_0.m(\overline{e}^n):\tau}$$

is s.t. $\nabla \mathcal{R}_{\gamma}^{n+1} \bar{\nabla}$, and $d_{\nabla}(\bar{\nabla}, \bar{\nabla}) \leq 2^{-n}$, by definition of $\mathcal{R}_{\gamma}^{n+1}$ and d_{∇} .

We can now state the main result.

Theorem 6. Let \overline{cd}^n be well-typed class declarations. If $\Gamma \Vdash e:\tau$ and $\Pi \in \Gamma$ in \overline{cd}^n , then there exists \forall s.t. $\Pi \Vdash e \Rightarrow \forall$ and $\forall \in \tau$ in \overline{cd}^n .

Soundness of the inductive type system in terms of the CBS and of the ISS can be derived as two simple corollaries.

Corollary 2. Let \overline{cd}^n be well-typed class declarations. If $\Gamma \vdash e:\tau$, and $\Pi \in \Gamma$ in \overline{cd}^n , then there exists v s.t. $\Pi \Vdash e \Rightarrow v$ and $v \in \tau$ in \overline{cd}^n .

Proof. The theorem is a straightforward corollary of Theorems 5 and 6.

Corollary 3. If $\emptyset \vdash e:\tau$, $e \stackrel{*}{\to} e'$, and e' is a normal form, then e' is a value.

Proof. Direct from corollaries 2 and 1.

Such a corollary is sufficient for guaranteeing the soundness of the type system in terms of the ISS: a well-typed expression can never get stuck in the ISS. However, by adding the following property (that can be proved easily), we can also deduce that the value e' is s.t. $\emptyset \vdash e'$: τ' with $\tau' < \tau$.

Proposition 5. If $\emptyset \Vdash v \Rightarrow v$, and $v \in \tau$, then $\emptyset \vdash v : \tau'$, with $\tau' \leq \tau$.

We can now prove the generalization of Corollary 3.

Corollary 4. If $\emptyset \vdash e:\tau$, $e \stackrel{*}{\rightarrow} e'$, and e' is a normal form, then e' is a value and $\emptyset \vdash e':\tau'$ with $\tau' < \tau$.

Proof. By Corollary 2 we know also that $v \in \tau$, and by Corollary 1 we know that $\emptyset \Vdash e' \Rightarrow v$, hence we can conclude by Proposition 5.

7 Conclusion

We have shown that it is possible to prove soundness of a conventional inductive and nominal type system for a Java-like language in terms of a coinductive big-step operational semantics obtained by interpreting coinductively the rules of a standard big-step semantics. The key point of the result is that infinite (including non regular) values have to be considered, otherwise the claim fails. Infinite values allows the definition of a complete metric space of proof trees for the CBS, which ensures that every well-typed expression evaluates into a value in the CBS, even in case of non termination.

We have also shown that the CBS can be regarded as the concretization of a coinductive type system that can be directly derived from the standard inductive type system. Before making the proof of soundness clearer, this fact also reveals how coinduction is related to the inductive type system.

The pioneer work of Milner and Tofte [16] is one of the first where coinduction is used for proving consistency of the type system and the big-step semantics of a simple functional language; however rules are interpreted inductively, and the semantics does not capture diverging evaluations.

In their work Leroy and Grall [15] analyze two kinds of coinductive big-step operational semantics for the call-by-value λ -calculus, study their relationships with the small-step and denotational semantics, and their suitability for compiler correctness proofs. Besides the fact that here we consider a Java-like language, the main contribution of this paper w.r.t. Leroy and Grall's work is showing that by interpreting coinductively a standard big-step operational semantics, soundness of a standard nominal type system can be proved. We could prove such a result because (1) in our semantics not only evaluation rules are interpreted coinductively, but also the definition of values, and (2) the absence of first-class functions in our language makes the treatment simpler. Leroy and Grall show that a similar soundness claim does not hold in their setting; we conjecture that the only reason for that consists in the fact that in their coinductive semantics values are defined inductively (hence are finite), rather than coinductively (that is, infinite). It would be interesting to investigate whether soundness holds for the λ -calculus when values are defined coinductively.

Kusmierek and Bono propose a different approach and prove type soundness w.r.t. an inductive big-step operational semantics; their proposal is centered on the idea of tracing the intermediate steps of a program execution with a partial derivation-search algorithm which deterministically computes the value and the proof tree of evaluation judgments. Similar approaches, although their corresponding semantics are not deterministic, are those of Ager [1] and Stoughton [20].

Nakata and Uustalu [18,17] define a coinductive trace-based semantics, whose main aim, however, is formal verification of not terminating programs.

Finally we would like to mention the work by Ernst et al. [12] where a soundness result w.r.t. a big-step operational semantics is proved thanks to a coverage lemma ensuring that errors do not prevent expressions from evaluating to a result. Such a result is achieved by introducing a finite evaluation relation indexed over natural numbers. A terminating expression is one for which there exists a natural number n such that the finite evaluation indexed by n returns a value (which may include also the usual runtime errors). However, in our approach type soundness can be proved without introducing extra rules for dealing with runtime errors generation and propagation, and finite evaluations.

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A Auxiliary definitions

Auxiliary functions *fields* and *meth* are defined in Figure 10. Figure 11 contains the rules defining subtyping, overriding and the join operator \vee .

$$\begin{split} &\frac{fields(c') = \overline{\tau}^m \ \overline{f}^m}{fields(0\texttt{bject}) = \epsilon} \quad \frac{fields(c') = \overline{\tau}^m \ \overline{f}^m}{fields(c) = \overline{\tau}^m \overline{f}^m, \overline{\pi}^n \ \overline{g}^n} \quad \frac{\textbf{class} \ c \ \textbf{extends} \ c' \ \{ \ \overline{\pi}^n \ \overline{g}^n; \overline{md}^k \} \\ &\frac{meth(c,m) = \overline{\tau}^n \ \overline{x}^n.e:\tau}{meth(c',m) = \overline{\tau}^n \ \overline{x}^n.e:\tau} \quad \textbf{class} \ c \ \textbf{extends} \ c' \ \{ \ \overline{fd}^n \ \overline{md}^k \ \tau \ m(\overline{\tau} \ \overline{x}^n) \ \{e\} \ \overline{md'}^{k'} \} \\ &\frac{meth(c',m) = \overline{\tau}^n \ \overline{x}^n.e:\tau}{meth(c,m) = \overline{\tau}^n \ \overline{x}^n.e:\tau} \quad \textbf{class} \ c \ \textbf{extends} \ c' \ \{ \ \overline{fd}^n \ \overline{md}^k \}, m \ \text{not declared in} \ \overline{md}^k \} \end{split}$$

Fig. 10. Definition of auxiliary functions fields and meth

$$(\operatorname{Box}) \frac{c \operatorname{lass} \ c \ \operatorname{extends} \ c'}{bool \leq \operatorname{Object}} \qquad (\operatorname{inh}) \frac{c' \leq c''}{c \leq c''} \ \operatorname{class} \ c \ \operatorname{extends} \ c' \ \{ \ \dots \ \}$$

$$\frac{\operatorname{class} \ c \ \operatorname{extends} \ c' \ \{ \ \dots \ \}}{override(c,m,\overline{\tau}^n,\tau)} \qquad \frac{\operatorname{class} \ c \ \operatorname{extends} \ c' \ \{ \ \dots \ \}}{meth(c',m) \ \operatorname{undefined}} \qquad \frac{\operatorname{class} \ c \ \operatorname{extends} \ c' \ \{ \ \dots \ \}}{v(\tau_1,\tau_2) = \tau_1} \qquad \frac{\operatorname{class} \ c \ \operatorname{extends} \ c' \ \{ \ \dots \ \}}{v(\tau_1,\tau_2) = \tau_2} \qquad \frac{\operatorname{class} \ c \ \operatorname{extends} \ c' \ \{ \ \dots \ \}}{v(\tau_1,\tau_2) = \operatorname{Object}} \qquad \frac{\tau_1 = bool, \tau_2 \neq bool \ \operatorname{or}}{v_1 \neq bool, \tau_2 = bool}$$

$$\frac{\operatorname{class} \ c_1 \ \operatorname{extends} \ c'_1 \ \{ \ \dots \ \}}{\operatorname{class} \ c_2 \ \operatorname{extends} \ c'_2 \ \{ \ \dots \ \}}$$

$$\frac{\operatorname{class} \ c_2 \ \operatorname{extends} \ c'_2 \ \{ \ \dots \ \}}{c_1 \not\leq c_2, c_2 \not\leq c_1}$$

Fig. 11. Definition of subtyping, override, and \vee

B Proofs

Theorem 3

Proof. The proof is by case analysis on the first applied rule of the coinductive big-step semantics, and by induction on the structure of e.

Rule (VAR) This case is vacuous, since \emptyset is undefined on every variable.

Rules (FAL) and (TRU) By definition false, and true are values.

Rule (NEW) By definition of the rule, $e = \mathbf{new} \ c(\overline{e}^n)$ and $\forall i = 1..n \ \emptyset | \vdash e_i \Rightarrow v_i$. Then, by inductive hypothesis, for all i = 1..n one between the following two facts must hold:

- 1. e_i is a value;
- 2. there exists e'_i s.t. $e_i \rightarrow e'_i$.

If for all $i=1..n, e_i$ is a value, then by definition $\mathbf{new}\ c(\overline{e}^n)$ is a value as well. Otherwise, let j be the least index in the range 1..n such that 2 holds; then we can apply rule (ctx) with context $\mathbf{new}\ c(\overline{e}^{j-1}, \square, e_{j+1}, \dots, e_n)$, and redex e_j , and deduce $\mathbf{new}\ c(\overline{e}^n) \to \mathbf{new}\ c(\overline{e}^{j-1}, e'_j, e_{j+1}, \dots, e_n)$.

Rule (FLD) By definition of the rule, $e=e'.f_i, \emptyset \Vdash e' \Rightarrow v$, where $v=obj(c, [\overline{f}^n \mapsto \overline{v}^n])$, and $1 \leq i \leq n$. Then, by inductive hypothesis, either e' is a value, or there exists e'' s.t. $e' \to e''$; if the latter fact holds, then we can apply rule (ctx) with context $\Box .f_i$ and redex e', and deduce $e'.f_i \to e''.f_i$. Otherwise, if e' is a value, then, since $\emptyset \Vdash e' \Rightarrow obj(c, [\overline{f}^n \mapsto \overline{v}^n])$, by the definition of values and by the rules for the coinductive semantics, we deduce that (NEW) must be the first applied rule in the proof tree for $\emptyset \Vdash e' \Rightarrow obj(c, [\overline{f}^n \mapsto \overline{v}^n])$, therefore $e' = \mathbf{new} \ c(\overline{v}^n)$ and $fields(c) = \overline{f}^n$. Since $1 \leq i \leq n$, we can apply rule (fld), and deduce $e = \mathbf{new} \ c(\overline{v}^n).f_i \to v_i$.

Rule (INV) By definition of the rule, $e = e_0.m(\overline{e}^n)$, $\emptyset \Vdash e_0 \Rightarrow v$, where $v = obj(c, [\overline{f}^k \mapsto \overline{\mathbf{u}}^k])$, $\forall i = 1..n \ \emptyset \Vdash e_i \Rightarrow v_i$, and $meth(c, m) = \overline{\tau}^n \ \overline{x}^n.e':\tau$. Then, by inductive hypothesis, for all i = 0..n one between the following two facts must hold:

- 1. e_i is a value;
- 2. there exists e'_i s.t. $e_i \rightarrow e'_i$.

If for all i = 0..n, e_i is a value, then, since $\emptyset \vdash e_0 \Rightarrow obj(c, [\overline{f}^k \mapsto \overline{u}^k])$, by the definition of values and by the rules for the coinductive semantics, we deduce that (NEW) must be the first applied rule in the proof tree for $\emptyset \vdash e_0 \Rightarrow obj(c, [\overline{f}^k \mapsto \overline{u}^k])$, therefore $e_0 = \mathbf{new} \ c(\overline{v}^k)$. Hence, we can apply rule (inv), and deduce

$$e_0.m(\overline{e}^n) \to e'[\mathtt{this} \mapsto \mathbf{new} \ c(\overline{v}^k), \overline{x}^n \mapsto \overline{e}^n].$$

Otherwise, let j be the least index in the range 0..n such that 2 holds; then, if j=0, we can apply rule (ctx) with context $\Box.m(\overline{e}^n)$ and redex e_0 , and deduce $e_0.m(\overline{e}^n) \to e'_0.m(\overline{e}^n)$; if j>0, then we can apply rule (ctx) with context $v.m(\overline{v}^{j-1}, \Box, \overline{e}^{n-j})$ and redex e_j , and deduce

$$v.m(\overline{v}^{j-1}, e_j, \overline{e}^{n-j}) \to v.m(\overline{v}^{j-1}, e'_j, \overline{e}^{n-j}).$$

Rule (IFT) By definition of the rule, $e = \mathbf{if}$ (e') e_1 else e_2 , and $\emptyset \Vdash e' \Rightarrow true$. Then, by inductive hypothesis, either e' is a value, or there exists e'' s.t. $e' \to e''$. If the latter fact holds, then we can apply rule (ctx) with context \mathbf{if} (\square) e_1 else e_2 and redex e', and deduce

if
$$(e')$$
 e_1 else $e_2 \rightarrow$ if (e'') e_1 else e_2 .

Otherwise, if e' is a value, then, since $\emptyset \Vdash e' \Rightarrow true$, by the definition of values and by the rules for the coinductive semantics, we deduce that (TRU) must be the first (and unique) applied rule in the proof tree for $\emptyset \Vdash e' \Rightarrow true$, therefore $e' = \mathbf{true}$ and by rule (ift) we can deduce **if** (**true**) e_1 **else** $e_2 \rightarrow e_1$.

Rule (IFF) The proof is symmetric to the one shown above for rule (IFF).

Lemma 1

Proof. The proof is by case analysis on the first applied rule in the proof tree of $\overline{x}^n \mapsto \overline{v}^n | \vdash e \Rightarrow v$, and by coinduction on the rules defining the big-step semantics.

Rule (VAR) By definition of the rule, $e = x_i$, $v = v_i$ for i s.t. $1 \le i \le n$, therefore $e[\overline{x}^n \mapsto \overline{v}^n] = v_i$. Furthermore, by hypothesis $\emptyset \Vdash v_i \Rightarrow v_i$, therefore $\emptyset \Vdash e[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow v$.

Rules (FAL) and (TRU) The proof is immediate by virtue of the fact that $\emptyset \Vdash \mathbf{false} \Rightarrow false \text{ and } \emptyset \Vdash \mathbf{true} \Rightarrow true$, and $\mathbf{false}[\overline{x}^n \mapsto \overline{v}^n] = \mathbf{false} \text{ and } \mathbf{true}[\overline{x}^n \mapsto \overline{v}^n] = \mathbf{true}$.

Rule (NEW) By definition of the rule, $e = \mathbf{new} \ c(\overline{e}^k)$, $\mathbf{v} = obj(c, [\overline{f}^k \mapsto \overline{\mathbf{v}}^k])$, $\forall i = 1..k \ \overline{x}^n \mapsto \overline{\mathbf{v}}^n \Vdash e_i \Rightarrow \mathbf{u}_i$, and $fields(c) = \overline{f}^k$. By coinductive hypothesis $\forall i = 1..k \ \emptyset \Vdash e_i[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow \mathbf{u}_i$, therefore by rule (NEW) $\emptyset \Vdash \mathbf{new} \ c(e_1[\overline{x}^n \mapsto \overline{v}^n], \dots, e_k[\overline{x}^n \mapsto \overline{v}^n]) \Rightarrow obj(c, [\overline{f}^k \mapsto \overline{\mathbf{v}}^k])$, hence $\emptyset \Vdash \mathbf{new} \ c(\overline{e}^k)[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow \mathbf{v}$.

Rule (FLD) By definition of the rule, $e = e'.f_i$, $v = u_i$, $\overline{x}^n \mapsto \overline{v}^n \Vdash e' \Rightarrow obj(c, [\overline{f}^k \mapsto \overline{u}^k])$, and $1 \leq i \leq k$. By coinductive hypothesis $\emptyset \Vdash e'[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow obj(c, [\overline{f}^k \mapsto \overline{u}^k])$, therefore by rule (FLD) $\emptyset \Vdash e'[\overline{x}^n \mapsto \overline{v}^n].f_i \Rightarrow u_i$, hence $\emptyset \Vdash e'.f_i[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow v$.

 $\begin{aligned} &Rule\ (\text{INV})\ \text{By definition of the rule},\ e = e_0.m(\overline{e}^k), \overline{x}^n \mapsto \overline{\mathbf{v}}^n \Vdash e_0 \Rightarrow obj(c, [\overline{f}^h \mapsto \overline{\mathbf{u}}^h]),\\ \forall\ i = 1..k\ \overline{x}^n \mapsto \overline{\mathbf{v}}^n \Vdash e_i \Rightarrow \mathbf{v}_i',\ meth(c,m) = \overline{\tau}^n\ \overline{x'}^n.e':\tau, \text{ and this } \mapsto obj(c, [\overline{f}^h \mapsto \overline{\mathbf{u}}^h]), \overline{x'}^k \mapsto \overline{\mathbf{v}}^k \Vdash e' \Rightarrow\\ \mathbf{v}.\ \text{By coinductive hypothesis}\ \emptyset \Vdash e_0[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow obj(c, [\overline{f}^h \mapsto \overline{\mathbf{u}}^h])\ \text{ and }\ \forall\ i =\\ 1..k\ \emptyset \Vdash e_i[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow \mathbf{v}_i',\ \text{therefore by rule (INV)}\ \emptyset \Vdash e_0[\overline{x}^n \mapsto \overline{v}^n].m(e_1[\overline{x}^n \mapsto \overline{v}^n],\dots,e_k[\overline{x}^n \mapsto \overline{v}^n]) \Rightarrow\\ \mathbf{v},\ \text{hence}\ \emptyset \Vdash e_0.m(\overline{e}^k)[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow \mathbf{v}.\end{aligned}$

Rule (IFT) By definition of the rule, $e = \mathbf{if} \ (e') \ e_1 \ \mathbf{else} \ e_2, \overline{x}^n \mapsto \overline{v}^n \Vdash e' \Rightarrow true$, and $\overline{x}^n \mapsto \overline{v}^n \Vdash e_1 \Rightarrow v$. By coinductive hypothesis $\emptyset \Vdash e'[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow true$, and $\emptyset \Vdash e_1[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow v$, therefore by rule (IFT)

$$\emptyset \vdash \mathbf{if} \ (e'[\overline{x}^n \mapsto \overline{v}^n]) \ e_1[\overline{x}^n \mapsto \overline{v}^n] \ \mathbf{else} \ e_2[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow \mathbf{v},$$

hence $\emptyset \Vdash \mathbf{if} (e') \ e_1 \ \mathbf{else} \ e_2[\overline{x}^n \mapsto \overline{v}^n] \Rightarrow \mathbf{v}.$

Rule (IFF) The proof is symmetric to the one shown above for rule (IFF).

Theorem 4

Proof. The proof is by case analysis on the first applied rule in the proof tree of $\emptyset \Vdash e \Rightarrow v$, and by induction on the rules defining the small-step semantics.

Rules (VAR), (FAL), (TRU) These cases are vacuous, since the hypothesis $e \to e'$ does not hold.

Rule (NEW) By definition of the rule, $e = \mathbf{new} \ c(\overline{e}^n)$, and $\forall i = 1..n \ \emptyset \vdash e_i \Rightarrow v_i$. In this case the first applicable reduction rule can only be (ctx), therefore $e = \mathcal{C}[e_i], \ e' = \mathcal{C}[e_i']$ with $1 \leq i \leq n$ and a suitable context $\mathcal{C}[\]$, and $e_i \to e_i'$. By inductive hypothesis $\emptyset \Vdash e_i' \Rightarrow v_i$, therefore by rule (NEW) $\emptyset \Vdash \mathcal{C}[e_i'] \Rightarrow v$.

Rule (FLD) By definition of the rule, $e = e_0.f_i$, $\mathbf{v} = \mathbf{v}_i$, $\emptyset \Vdash e_0 \Rightarrow obj(c, [\overline{f}^n \mapsto \overline{\mathbf{v}}^n])$, and $1 \leq i \leq n$. If the first applicable reduction rule is (ctx), then $e' = e'_0.f_i$ and $e_0 \to e'_0$. By inductive hypothesis $\emptyset \Vdash e'_0 \Rightarrow obj(c, [\overline{f}^n \mapsto \overline{\mathbf{v}}^n])$, therefore by rule (FLD) $\emptyset \Vdash e'_0.f_i \Rightarrow \mathbf{v}_i$.

Otherwise the first applicable reduction rule can only be (fld), therefore $e_0 = \mathbf{new} \ c'(\overline{v}^k)$, $fields(c') = \overline{g}^k$, $e' = v_j$ with $g_j = f_i$, $1 \leq j \leq k$; since $\emptyset \Vdash e_0 \Rightarrow obj(c, [\overline{f}^n \mapsto \overline{v}^n])$, by rule (NEW), c' = c, k = n, $\overline{g}^k = \overline{f}^n$ and $\emptyset \Vdash v_l \Rightarrow v_l$ for all l = 1..n, therefore $\emptyset \Vdash e' = v_i \Rightarrow v_i$.

Rule (INV) By definition of the rule, $e = e_0.m(\overline{e}^n)$, $\forall i = 0..n \ \emptyset \vdash e_i \Rightarrow v_i, v_0 = obj(c, [\overline{f}^k \mapsto \overline{u}^k])$, this $\mapsto v_0, \overline{x}^n \mapsto \overline{v}^n \vdash e_b \Rightarrow v$ and $meth(c, m) = \overline{\tau}^n \overline{x}^n.e_b:\tau$. If the first applicable reduction rule is (ctx), then $e = \mathcal{C}[e_i]$, $e' = \mathcal{C}[e'_i]$ with $0 \le i \le n$ and a suitable context $\mathcal{C}[]$, and $e_i \to e'_i$. By inductive hypothesis $\emptyset \vdash e'_i \Rightarrow v_i$, therefore by rule (INV) $\emptyset \vdash \mathcal{C}[e'_i] \Rightarrow v$.

Otherwise the first applicable reduction rule can only be (inv), therefore $e_0 = \mathbf{new} \ c'(\overline{v}^h).m(\overline{v'}^n)$, $meth(c',m) = \overline{x}^n \ \overline{x'}^n.e'_b:\tau$, and $e' = e'_b[\mathtt{this} \mapsto \mathbf{new} \ c'(\overline{v}^h),\overline{x'}^n \mapsto \overline{v'}^n]$; since $\emptyset \Vdash e_0 \Rightarrow obj(c, [\overline{f}^k \mapsto \overline{v}^k])$, by rule (NEW), c' = c, h = k, and $\overline{x'}^n.e'_b = \overline{x}^n.e_b$, therefore

$$e' = e_b[\mathtt{this} \mapsto \mathbf{new} \ c(\overline{v}^k), \overline{x}^n \mapsto \overline{v'}^n],$$

and, by lemma 1, $\emptyset \Vdash e' \Rightarrow v$.

Lemma 4

Proof. By induction on the definition of \leq . If c'=c, then the proof is immediate; otherwise there must exist c'' s.t. c' extends c'' and $c'' \leq c$. If c' does not contain a declaration for m, then we can conclude by inductive hypothesis on c'' and by definition of meth. If c' contains a declaration τ' $m(\overline{\tau'}^n \ \overline{x'}^n)$ $\{e'\}$, then by definition $meth(c',m)=\overline{\tau'}^n \ \overline{x'}^n.e':\tau'$ and $override(c',m,\overline{\tau'}^n,\tau')$ must hold; therefore we can conclude by inductive hypothesis on c'', by definition of override, and by transitivity of \leq .

lemma 7

Proof. The proof is by induction on the definition of subtyping and by case analysis on the first applied subtyping rule. Rule (BOX) cannot be applied, whereas the proof for (REF) is immediate. If (INH) is the first applied rule, then class c extends c'' and $c'' \leq c'$; by definition of fields, we deduce that $fields(c'') = \overline{\tau}^k \overline{f}^k$ with $k \leq n$. Finally, by inductive hypothesis $fields(c') = \overline{\tau}^m \overline{f}^m$ for $m \leq k \leq n$.

Lemma 8

Proof. The proof is by induction on the definition of $\tau_1 \leq \tau_2$ and by case analysis on the first applied subtyping rule. Cases for rules (BOX) and (REF) are trivial. If (INH) is the first applied rule, then class $\tau_1 = c$, c extends c'' and $c' \leq \tau_2$; by inductive hypothesis $c' \leq \tau_3$, hence by rule (INH) we conclude $\tau_1 \leq \tau_3$.

Lemma 9

Proof. The proof is by case analysis on the first applied rule for $v \in \tau$.

The proof for the two rules (TOP) and (BOOL) is immediate since Object can only be subtype of itself, whereas bool can only be subtype of Object and itself.

For rule (OBJ) we observe that the side condition of the rule is verified for τ' as well. This comes from the transitivity of \leq and by lemma 7.

Lemma 10

Proof. By induction on the definition of meth. If c contains the declaration τ $m(\overline{\tau}^n \overline{x}^n)$ $\{e\}$, then by virtue of the fact that m must be well-typed we deduce that this: $c, \overline{x}^n : \overline{\tau}^n \vdash e : \tau'$ with $\tau' \leq \tau$. Otherwise $meth(c', m) = \overline{\tau}^n \overline{x}^n . e : \tau$ where c' is the direct superclass of c, and, by inductive hypothesis, there exists c'' s.t. $c' \leq c''$ (and, by transitivity, $c \leq c''$) and this: $c'', \overline{x}^n : \overline{\tau}^n \vdash e : \tau'$ with $\tau' \leq \tau$.

Proposition 5

Proof. By induction and case analysis on v. For $v = \mathbf{false}$ and $v = \mathbf{true}$ the proof is immediate. If $v = \mathbf{new} \ c(\overline{v}^n)$, then the first applied rule of the proof tree for $\emptyset \Vdash v \Rightarrow v$ is (NEW), therefore $v = obj(c, [\overline{f}^n \mapsto \overline{v}^n]), \emptyset \Vdash v_i \Rightarrow v_i$ for all i = 1..n, and $fields(c) = \overline{\tau}^n \overline{f}^n$. From the shape of v we know that the first applied rule in the proof tree for $v \in \tau$ is (OBJ), therefore $\tau = c', c \leq c'$, and $v_i \in \tau_i$ for all i = 1..n. By induction, we deduce that $\emptyset \vdash v_i : \tau_i'$ with $\tau_i' \leq \tau_i$ for all i = 1..n, hence we conclude by applying typing rule (NEW), that $\Gamma \vdash \mathbf{new} \ c(\overline{v}^n) : c$, where $c \leq c' = \tau$.