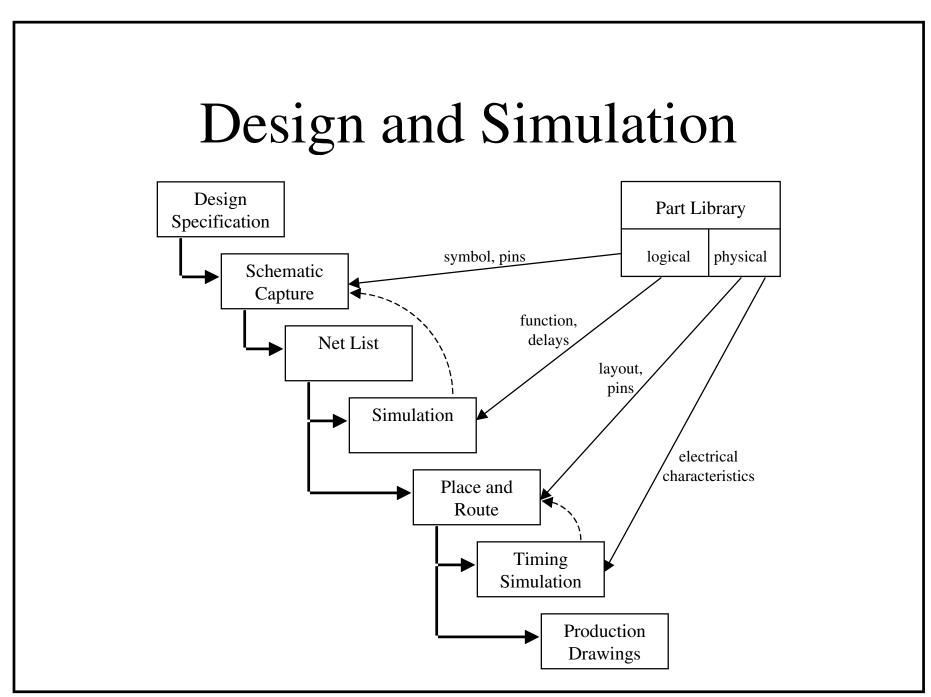
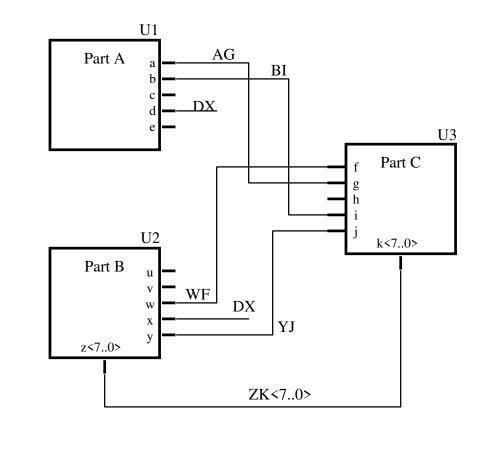


CAD Tools

- Schematic Capture
 - Graphical design entry
 - Examples: Cadence, Mentor Graphics
- HDL
 - Textual description of logic
 - Permits behavioral description of logic
 - Examples: VHDL, Verilog



Schematic Capture



- Parts are generic objects with:
 - symbol
 - pins
 - part name (Part A)
 - instance name (U1)
- •Wires connect pins
 - may be 1 or more bits (bus)
 - have a signal name
 - may be implicit (DX)

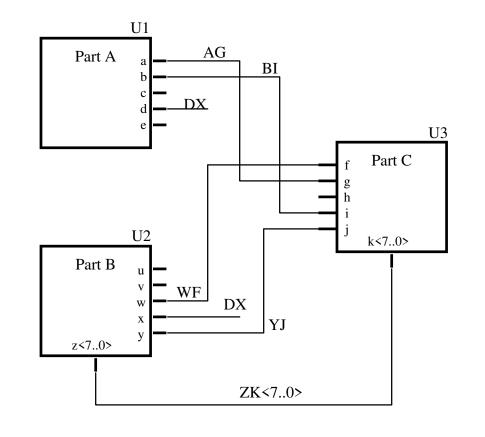
•Netlist

- connected signal names
 - •U1.a, AG, U3.g
 - •U2.w, WF, U3.f

•etc.

- each part instance
 - •U1 is a Part A
 - •U2 is a Part B
 - •U3 is a Part C

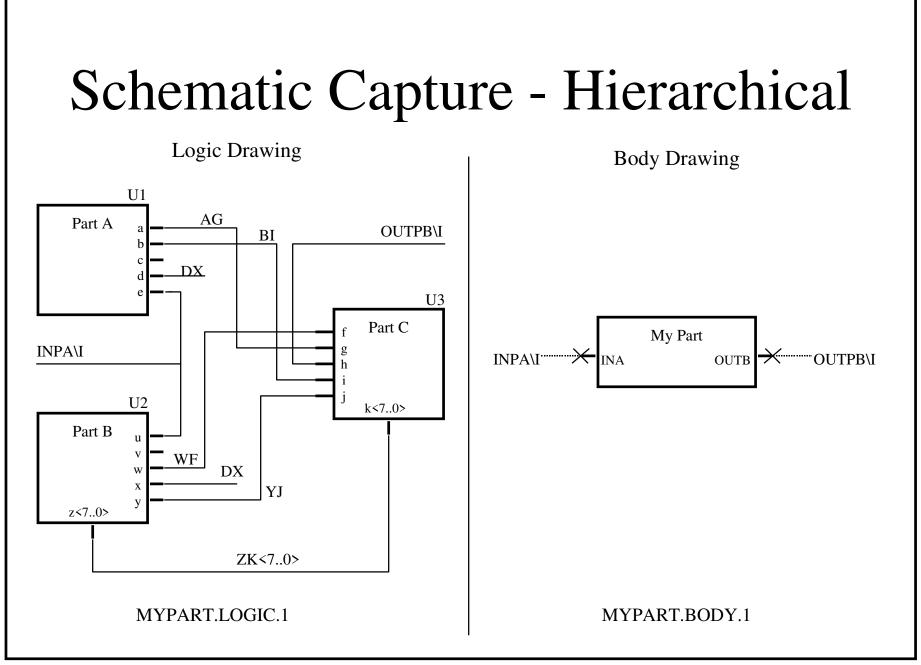
Schematic Capture



- Part library provides
 - Part symbol
 - Location of pins
 - Part name
 - Pin names
- •Hierarchical tools
 - Allow user to define parts
 - Allow design to be subdivided
 - Support reuse of designs
 - User must define above info
 - Later user provides part netlist

•Hierarchical netlists

- Look like subroutines
- Instance names differentiate multiple instances of a subcircuit



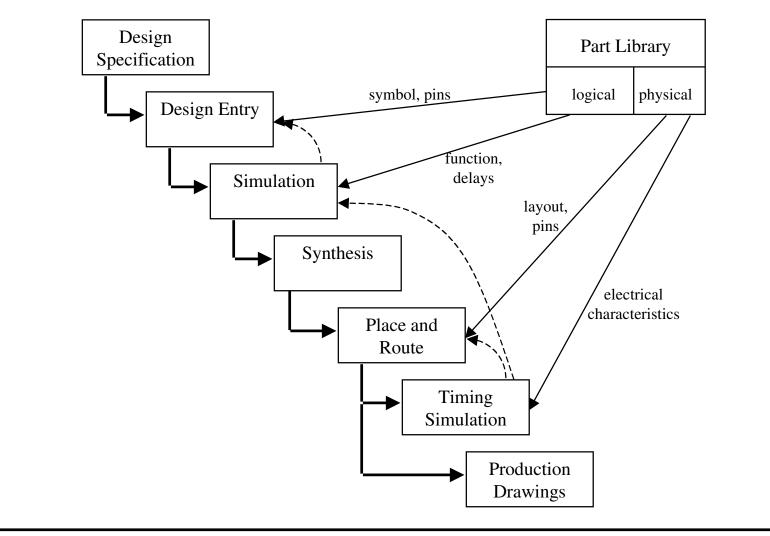
Netlist Output

- Each tool's unique format
 - complex set of translators
- EDIF
 - early attempt at a standard format
 - various versions
- HDLs (structural)
 - Verilog
 - VHDL (gov't approved)

Hardware Definition Languages

- Provide
 - textual definition of netlists
 - user-defined primitive models
 - high level functionality models
 - mixed-level simulation
- Major examples
 - VHDL
 - Verilog HDL

Design and Simulation



HDL Coding Styles

- Structural
 - Design in terms of components
 - Connect components with language
- Behavioral
 - Textual description of behavior
 - Includes many high level language constructs
- Register Transfer Level (RTL)

HDLs

- Support hierarchical design methology
- Behavioral models
 - describe behavior, not implementation
 - supports top-down design
 - supports mixed-mode simulation
 - means for user-defined primitives
- Structural models
 - textual netlists
 - support synthesis

Top-Down Design: Requirements Analysis

Behavioral Model

of

Complete System

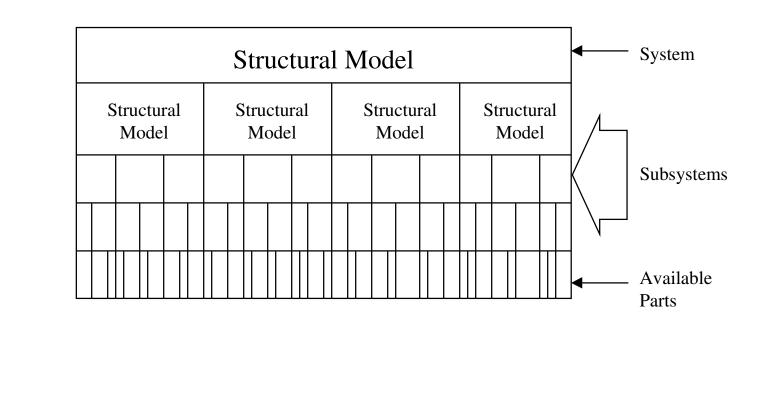
Top-Down Design: Problem Decomposition

Structural Model									
Behavioral	Behavioral	Behavioral	Behavioral						
Model	Model	Model	Model						
of	of	of	of						
Component	Component	Component	Component						

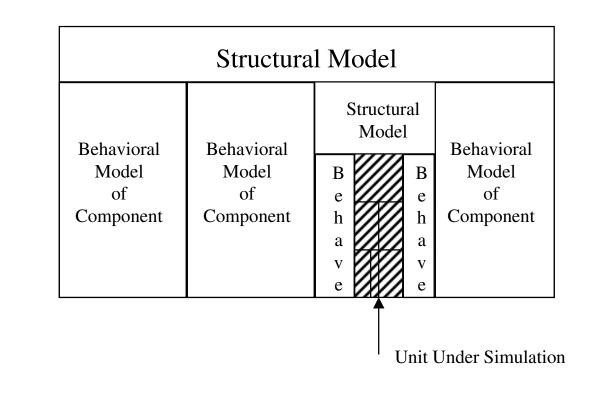
Top-Down Design: Problem Decomposition

Structural Model											
Structural Model		Structural Model		Structural Model		Structural Model					
В	В	В	В	В	В	В	В	В	В	В	В
e	e	e	e	e	e	e	e	e	e	e	e
h	h	h	h	h	h	h	h	h	h	h	h
a	а	a	a	a	a	a	а	a	а	а	a
v	V	v	v	v	v	v	V	v	v	V	v
e	e	e	e	e	e	e	e	e	e	e	e

Top-Down Design: Problem Decomposition



Top-Down Design: Hybrid Simulation



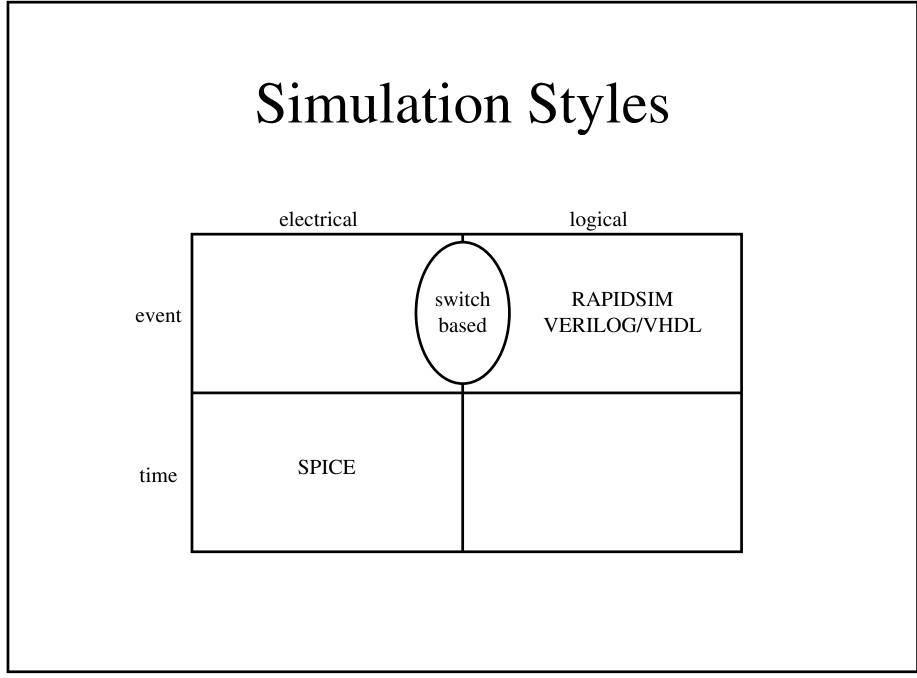
Simulation

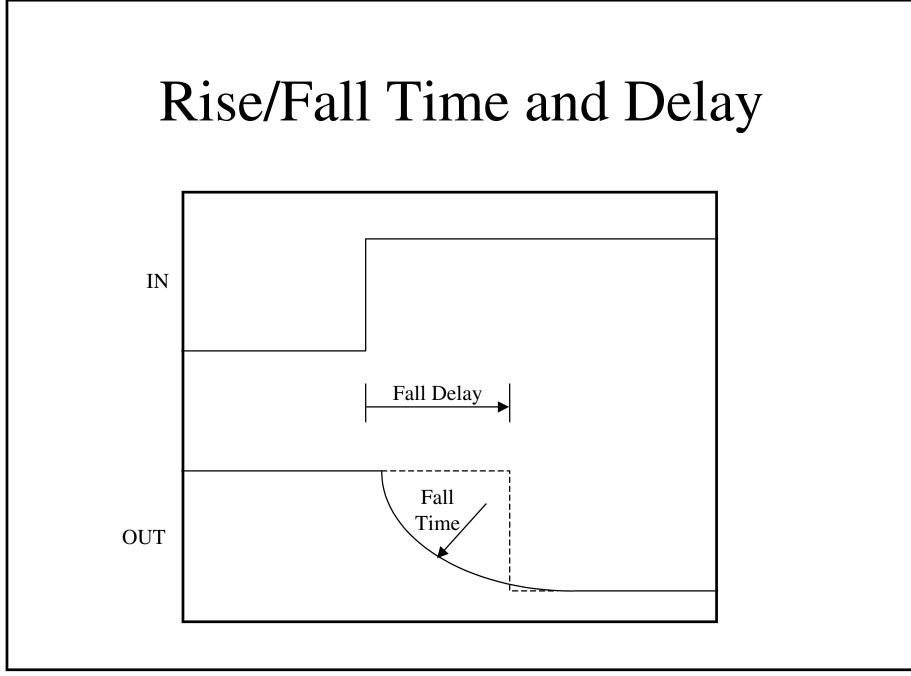
- Part library defines part as netlist based on a set of *primitive* parts
- Simulator provides computer model of primitives, and simulation engine to compute their interactions
- Simulator computes node voltages (simulator outputs) given input voltages

Time-Driven Simulation

- Primitives are resistors, capacitors, transistors, etc.
- Node voltages can be computed at any moment in the simulation
- Simulator computes node voltages every Δt
- Adjusts Δt as needed to control error
- Approach used by *SPICE*
- Can be **VERY** expensive (time-wise)

- Only recompute node voltages at *interesting* times when something changes
- Estimate logic levels (0 and 1)
- Estimate rise and fall delay
- Ignore rise and fall time
- Use basic logic operations (AND, OR, NOT) as primitives





- Simulator keeps sorted list of future events
- Simulator execution
 - remove next event from list
 - set sim time to time of the event
 - simulate the event (primitives)
 - insert new events (caused by the current event)
 into the event list
 - run until no more events

- Example an inverter

 Primitive model
 PRIMITIVE inverter BEGIN
 when input goes high to low
 schedule output high in RDELAY cycles
 when input goes low to high
 schedule output low in FDELAY cycles
 - Use netlist to locate all other gates that are connected to output

- Simulation output
 - list of changes to signals (high-low, low-high)
 - usually used to create a timing diagram
 - also may be used as input to another simulation
- Simulation cost
 - reduced to time needed to schedule and cause events - computation is minimal
 - nolonger sensitive to circuit density, speed, or technology

Basic Logic Values

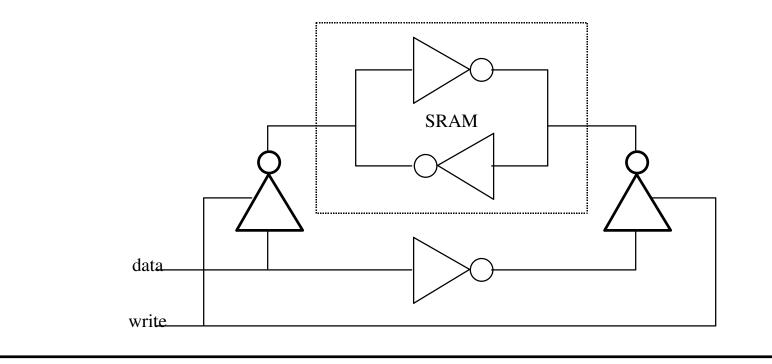
- Each node in one state
 - 0
 - 1
 - U (unknown or undefined)
 - Z (high impedance)
 - X (don't care)

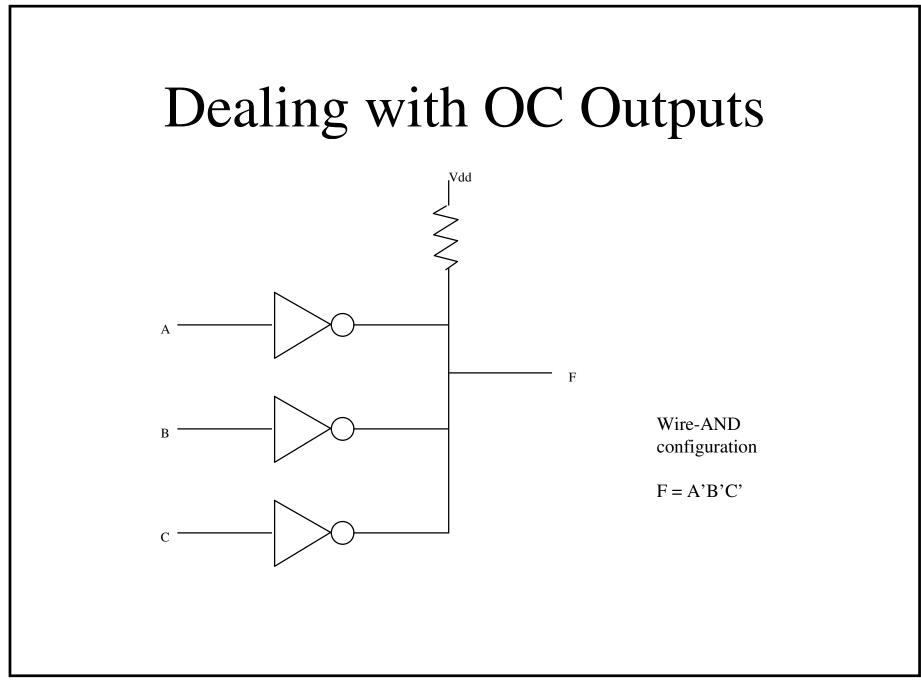
TSB and TG Problems

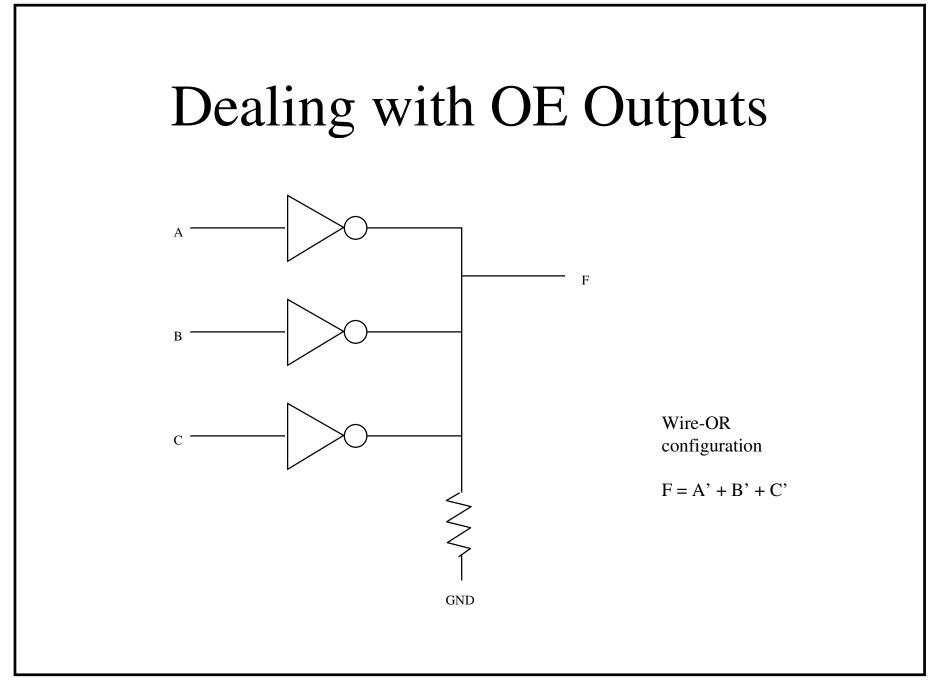
- TSBs and TGs can charge a node and then stop driving it
 - Add Z+
 - Add Z-
 - Add charge decay
- TGs are bi-directional, and can exhibit charge-sharing
 - VERY hard to simulate

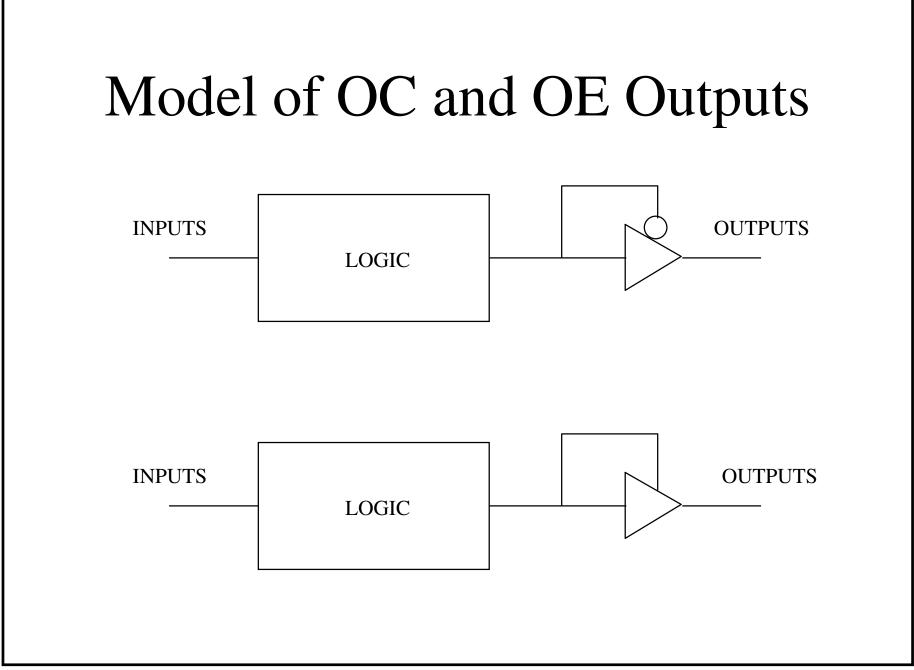
Different Driver Strength

• Might WANT to have one gate override another



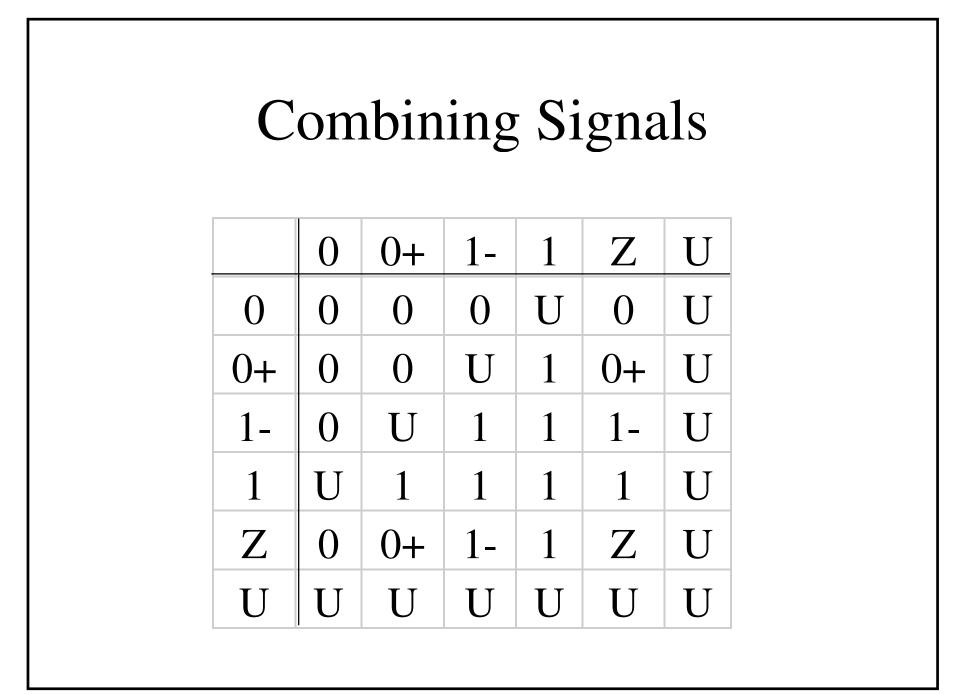






Simulating OC and OE Parts

- Model OC devices to output 0 or Z
- Model OE devices to output 1 or Z
- Model pull-up resistor to output 1-
- Model pull-down resistor to output 0+
- Z and 1- is 1-; Z and 0+ is 0+
- 0 and 1- is 0+; 1 and 0+ is 1-
- Must model node as multi-input device



Advanced Logic Simulators

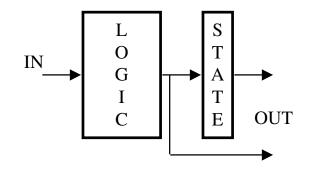
- Can operate at switch or gate level
- Node Model
 - logic level
 - level strength
 - path strength
- Switch simulations model for both 0 and 1
- Table driven engine evalutes node states

Register Transfer Level (RTL) Simulators

- Restricted to synchronous circuits in a standard Mealy model
- Languages specify logic as state diagrams or truth tables

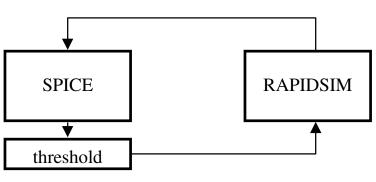
– PIC, SYSPLD, ABEL

• Translate nicely to PALs

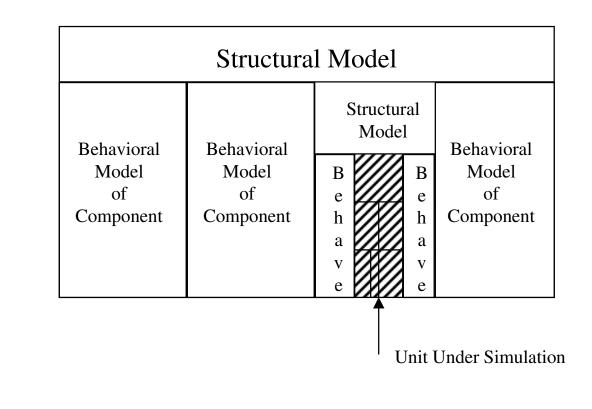


Hybrid (Mixed-Mode) Simulation

- Electrical (spice) and logic simulation together
- Partition problem into those areas needing critical timing analysis, and perform full electrical simulation of only those parts



Top-Down Design: Hybrid Simulation



Simulation Models

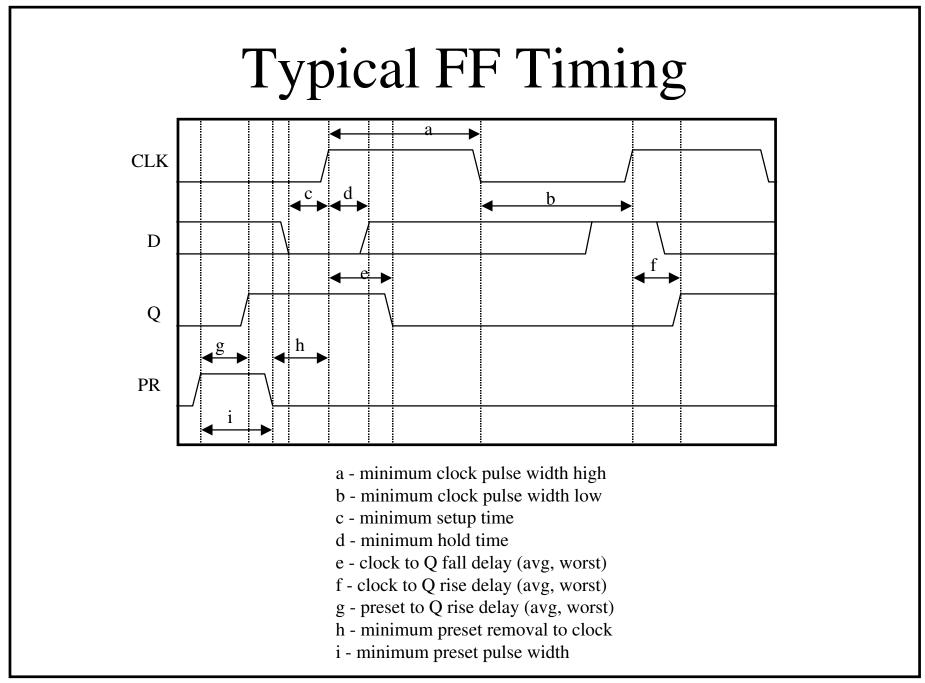
- Inputs to simulator
 - netlist
 - stimulus
 - device models
- Models composed of
 - primitive logic functions
 - timing

Simulation Models

- Primitive logic functions
 - AND, OR, NOT, NAND, NOR, XOR
 - TSB, TG, pull-up, etc.
 - no-delay
- Timing
 - rise time: best, worst, typical
 - fall time: best, worst, typical
 - setup time, hold time, pulse width

Typical FF Model

- Behavior
 - primitive, no-delay gates, or HDL model
- Timing
 - rise/fall delay from clock to Q
 - setup time, hold time
 - clock minimum high/low pulse width
 - preset/reset delay to Q
 - min preset/reset pulse width
 - min preset/reset to clock spacing



Routing

- Router inputs
 - netlist from schematic capture
 - physical part data from part library
 - physical dimension
 - pin data
 - placement, size
 - mount type
 - electrical characteristics
 - technology and user settings

Routing - Inputs

- Netlist
 - table of part numbers and type
 - connection list by part and pin number
- Pin data
 - signal name
 - special flags
 - position, size
 - resistance and capacitance

Routing - Parameters

- Router settings
 - dimensions of layout space
 - placement of connectors, some parts
 - routing layers, spacing, interconnects
 - electrical characteristics (resistance, capacitance)
 - routing goals (trace length, power density, etc.)

Routing - Outputs

- Layout
 - part placement
 - interconnect
 - power distribution
- Information
 - errors
 - routing density
 - routing data by net in netlist feed back to simulator

Back Annotation

- Output data from router added to schematic
- Simulations to estimate timing
 - identify critical paths
 - full logical simulation
 - full electrical simulation
- Leads to re-routing, or re-design