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Overview

Visualib is a comprehensive state-of-the-art graphics library for the Microsoft Windows environment. It contains powerful and efficient functions to transform and display both 2D and 3D graphic objects. Visualib can be used with either Microsoft Windows Software Development Kit version 3.0 or Borland C++ version 2.0 and up.

Main features of Visualib includes:

2D and 3D viewing systems

Transformations and _stack

Drawing functions

Viewing systems for 2D and 3D graphics

User can establish virtually unlimited number of independent 2D and 3D viewers. In each viewer, user can select various parameters such as the viewport, eye position, perspective or orthogonal projections, view volume, etc.

Transformation functions and stack

Visualib provides a sophisticated transformation mechanism to support virtually all types of graphics transformations. Visualib maintains a transformation stack which can be used in conjunction with the transformation functions to achieve flexible and efficient graphic effects.

Graphic object drawing functions

Visualib supports a full set of common 2D and 3D drawing functions such as lines, polygons, ellipses, spheres, polyhedra, etc. Backface culling is implemented for 3D viewers. User may also select double buffer mode to achieve smooth animation effects.

Visualib also provides the powerful curve and surface drawing functions such as Bezier, Hermit curves, B-Spline, NURBS curves and surfaces.

Visualib greatly extends the capabilities of windows' GDI functions. Visualib uses float type for specifying coordinates and avoids the common integer overflow problem associated with the GDI functions. However, all GDI functions are still available and the function calls from both systems can be used at the same time. Visualib can be used with any types of device context - screens, printers, or memory. Consequently, the same routine for display can also be used for printing or storing. Visualib uses the attributes such as colors, line width of the device context set by the GDI functions.

Visualib is the only graphics package for the Windows that delivers the power of high-end graphics work stations. For everyone interested in using graphics in the Windows, Visualib is an indispensable tool.

Whether you are developing a CAD application or simply want to draw a nice business chart, you will find that Visualib can save your time and money. Visualib will free the user from writing highly sophisticated and tedious graphics routines and obtain beautiful 2-D and 3-D graphics quickly.

About This Manual

Chapter II. GET STARTED provides a brief introduction on how to use Visualib in your windows programming.

Chapter III. INSIDE Visualib is a detailed explanation of all features of Visualib.

Chapter IV. Visualib FUNCTION REFERENCE is the alphabetical reference of all Visualib functions.

Appendix A. BIBLIOGRAPHY lists graphics books and research papers related to the features of Visualib.

Appendix B. COMMON QUESTIONS contains answers to some most commonly asked questions about Visualib.

Getting Started

Visualib disk contains the following files:

README.1ST - read me first
REGISTER.TXT - ASCII registration form
VISUALIB.LIB - the main library file
VISUALIB.H - the header file
VISUALIB.HLP - on-line Windows help of Visualib
VLIBDEMO.C - Visualib demo program source code
VLIBDEMO.EXE - Visualib demo program executable

The best place to start your Visualib programming is the demo program VLIBDEMO included in the distribution disk. The executable file is ready to run in Windows. Try it and enjoy the show!

The source code VLIBDEMO.C illustrated the application of Visualib library to create beautiful graphics applications. It uses many features on Visualib and may serve as a template on using Visualib.

Visualib functions are contained in the library file VISUALIB.LIB. Place it in a directory so that your linker can find it. In order to use the library functions in your Windows program, the header file VISUALIB.H needs to be included in your C source code after WINDOWS.H.

To use the Visualib system, first you need to initialize the graphics system by calling either `initialGraphics2D` or `InitialGraphics3D`. After the graphics system is initialized, you may create 2D or 3D viewers by calling `CreateViewer2D` or `CreateViewer3D`. Then call the viewing transformation functions and projection transformation functions to setup the viewers.

Now you can start to draw graphics through the viewers. Using the rich set of drawing functions provided by Visualib together with the modeling transformation functions and the matrix stacks, you will be able to achieve most sophisticated visual effects with ease.

Call the `ExitGraphics` function to exit the Visualib system.

Refer to 3.4 for a complete description of drawing functions.

The following is a very simple program segment that illustrates the general procedure of using Visualib library.

```
#include "windows.h"  
#include "Visualib.h"
```

```
/* in the function initInstance */  
    InitialGraphics3D(3, 100, 100);
```

```
/* in the function WindProc */  
    case WM_CREAT:  
        hVIEW = CreatViewer3D("sample viewer",100,20,100,100);  
  
    case WM_PAINT:
```

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Visualib Initialization and Termination

The 2D and 3D systems contained in Visualib are completely independent. You may use one of them or both of them at any time. Depending on your choice of graphics systems, one or both of the following initialization functions should be called before using the Visualib systems.

InitialGraphics2D
InitialGraphics3D

The initialization function allocates and initializes necessary system variables. When calling InitialGraphics2D or InitialGraphics3D, you specify the maximum number of viewers, the maximum number of points for each object, and the maximum depth of the matrix stack. The initialization function allocates the internal memory based on the given information. If an parameter is set to 0, the default maximum value for that parameter will be used.

The following functions set the default maximum values.

Max2DViewer
Max3DViewer
Max2DMStack
Max3DMStack

If a parameter in the initialization function is not 0, then the given value overrides the default value.

To exit a Visualib graphics system, use the function

ExitGraphics

ExitGraphics will free the memory used by the Visualib system.

Coordinate Systems

Visualib has three different coordinate systems that concern users.

The world coordinate system is the one that users deal with most often. A world coordinate system is a logical 2D or 3D coordinate in which most Visualib functions use to specify the geometric objects. You may define the world coordinates in any way to suit your application. It does not need to be correlated to the display configuration. Because of the powerful viewing transformations of Visualib, you can set up arbitrary viewing configurations in any world coordinates. The axes of a 3D world coordinate system may be displayed by calling the function:

[MarkPosition3D](#)

The screen coordinate system is the coordinate system used in MS Windows GDI functions. Several Visualib functions use this system to specify certain parameters related to the display devices. Because Visualib is compatible with the GDI functions, user may also call some GDI functions with this kind of coordinates while using Visualib.

The viewing coordinate system is an intermediate coordinate system used by Visualib. The following viewing transformations may be best thought of as operations in the viewing coordinate system.

[MoveViewer3D](#)

[RotateViewer3D](#)

[ZoomViewer3D](#)

[MoveViewer2D](#)

[RotateViewer2D](#)

The coordinates used in the world coordinate system are the 2D and 3D homogenous coordinates. Visualib defines the following types.

```
typedef struct {float x,y,w} POINT2D;  
typedef struct {float x,y,z,w} POINT3D;
```

Therefore, three floating point numbers (x,y,w) are used to define a 2D point and four floating point numbers (x,y,z,w) are used for a 3D point. A point in the 2D space with homogeneous coordinate (x,y,w) corresponds to the Euclidean coordinate (x/w,y/w) and a 3D point with homogeneous coordinate (x,y,z,w) corresponds the Euclidean coordinate (x/w, y/w, z/w). Although this representation will take a little more memory. There are many advantages associated with the homogeneous coordinates:

All affine transformations (including translation) can be handled in a uniform manner by linear transformations.

Perspective projections can be applied naturally and with the clipping in the homogeneous coordinates, the overflow problem associated with the perspective projections is avoided.

For the NURBS curves and surfaces, it is necessary to specify the homogenous coordinates.

To help users convert the regular nonhomogeneous coordinates to the format used by Visualib, Visualib provides the following functions:

[AssignPoint2D](#)

[AssignPoint3D](#)

Viewer

A viewer is a logical structure which specifies precisely how the graphics objects in a world coordinate system (2D or 3D) is displayed in a two dimensional screen viewport.

Viewport

The viewport of a viewer is a rectangular region in a window client area which is used for the actual display of the content of the viewer.

Viewing Transformation

The viewing transformation of a viewer defines the position of the eye related to the world coordinate system.

Projection Transformation

Projection transformation of a viewer defines the view volume and the way it is mapped to the viewport. A 3D projection can be either perspective or orthogonal.

Setup Viewer

A 2D or 3D viewer contains three major components:

Viewport
Viewing Transformation
Projection Transformation

The following functions create a 2D or 3D viewer and set its viewport and name:

CreateViewer2D
CreateViewer3D

The viewport of a viewer can be changed by the following function.

SetViewport2D
SetViewport3D

The name of a viewer is changed by the functions:

SetViewerName2D
SetViewerName3D

The frame of a viewer can be displayed by the functions:

DisplayViewerFrame2D
DisplayViewerFrame3D

The name of a viewer is displayed by the functions:

DisplayViewerName2D
DisplayViewerName3D

The viewing transformation of a 2D viewer is set by

SetView2D

The projection of a 2D viewer are set by the following functions:

SetProjection2D

The following function combines the actions of SetView2D and SetProjection

SetWindow2D

The viewing transformation of a 3D viewer is set by the functions:

SetView3D
SetPolarView3D

The projection of a 3D viewer is set by the following functions:

SetPerspective3D
SetOrthogonal3D

To select a viewer for drawing, use the functions:

SelectViewer3D

SelectViewer2D

The content of a viewer is cleared by the functions:

ClearViewer2D

ClearViewer3D

The viewing transformations may be modified by the following functions

MoveViewer3D

MoveWorld3D

RotateViewer3D

RotateWorld3D

ZoomViewer3D

ZoomWorld3D

MoveViewer2D

RotateViewer2D

Note that the viewing transformations are different from the modeling transformations. The modeling transformations affect the current transformation matrix on the stack top only, while the viewing transformations change the setting of a viewer.

To get information on a viewer, use the following functions:

Num2DViewer

Num3DViewer

ViewerPosition3D

ViewerOrientation3D

ViewerDirection3D

ViewerPosition2D

ViewerField3D

ViewerField2D

SetView3D defines the VRP, VPN, and VUP of the viewer. VRP is specified by the world coordinates VX, VY, VZ; VPN is specified by VRP and another point (RX, RY, RZ); VUP is determined by the twist angle, which is the angle of rotation about the VPN.

SetPolarView3D sets the viewer's VRP, VPN and VUP. (CX,CY,CZ) defines a reference center (not necessarily the origin) in the world coordinates. VRP is given by the polar coordinates (dist, Azim, Inc). Dist is the distance from VRP to the center. Azim is a rotation about y-axis and Inc is the angle of rotation about z-axis. VUP is again defined by the twist angle.

SetPerspective3D defines a perspective projection according to the field of view angle of Fovy, Aspect ratio, Front and Back clipping panes.

SetOrthogonal3D defines an orthogonal projection according to the viewing box defined by the Left, Right, Bottom, Top, Front, and Back.

Visualib provides a rich set of viewing transformations to help users achieve various viewing effects.

View reference point (VRP) - A reference point in the view plane that defines the camera position.

View plane normal (VPN) - the direction normal to the view plane. Together with VRP, it defines the view plane and the direction of the projection.

View up vector (VUP) - the vector in the view plane that points to the up direction.

Field of view angle (Fovy) - the angle of the viewing pyramid in the y-direction. Together with the Aspect ratio, it defines the projection point.

Aspect ratio - the ratio the y size over the x size of the view pyramid.

Clip depth - the minimum and maximum clipping values in z direction. It defines the top and bottom of the viewing pyramid.

Modeling Transformations and Matrix Stack

Transformations are important part of the graphics system. Visualib provides full support of all types of affine geometric transformations. Users may arbitrarily translate, scale, or rotate any object in any sequence.

[Rotate3D](#)
[Translate3D](#)
[Scale3D](#)
[Rotate2D](#)
[Translate2D](#)
[Scale2D](#)

Note that the modeling transformations are different from the viewing transformations. The modeling transformations affect the current transformation matrix on the stack top only, while the viewing transformations change the setting of a viewer.

To systematically manage the transformation processes, Visualib provides transformation stacks for 2D and 3D modeling transformations. The stack top determines the final effect of transformation process. All the transformation functions discussed above changes some aspects of the stack top. To save the current transformation configurations, use the following functions

[PushMatrix2D](#)
[PushMatrix3D](#)

These functions will push the current stack top and leave the stack top unchanged. You may get back to this particular state later by using the following function.

[PopMatrix2D](#)
[PopMatrix3D](#)

Drawing Functions

Visualib provides a full set of common 2D and 3D drawing functions.

[MoveTo2D](#)
[LineTo2D](#)
[DrawLine2D](#)
[Polyline2D](#)
[Polygon2D](#)
[Rectangle2D](#)
[Circle2D](#)
[Ellipse2D](#)
[Ngon2D](#)
[NsideStar2D](#)
[NsideFlower2D](#)
[MoveTo3D](#)
[LineTo3D](#)
[DrawLine3D](#)
[Polyline3D](#)
[Polygon3D](#)
[Rectangle3D](#)
[Prism3D](#)
[NsideStar3D](#)
[NsideFlower3D](#)
[Cube3D](#)
[Sphere3D](#)
[NsidePyramid3D](#)
[Cone3D](#)
[NsidePrism3D](#)
[Cylinder3D](#)

Visualib also provides advanced curve and surface functions. Visualib supports cubic Bezier, Hermit, B-Spline, and NURBS curves and surfaces.

[BezierCurve2D](#)
[HermitCurve2D](#)
[BSplineCurve2D](#)
[NURBSCurve2D](#)
[BezierCurve3D](#)
[HermitCurve3D](#)
[BSplineCurve3D](#)
[NURBSCurve3D](#)
[BezierSurface3D](#)
[HermitSurface3D](#)
[BSplineSurface3D](#)
[NURBSSurface3D](#)

NURBS (NonUniform Rational B-Spline) curves and surfaces have gained popularities in CAD/CAM because of their power and flexibility. NURBS has some distinctive advantages:

NURBS is invariant under perspective projections.

The continuity and smoothness of NURBS curve or surfaces can be controlled by the knots.

All conic sections and quadric surfaces can be represented by NURBS exactly.

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HermitSurface3D

short SetWindow3D (HVIEW hview, float left, float right,
float top, float bottom, float front, float back);

void Revolution3D (HDC hDC, float x1, float y1, float z1,
float x2, float y2, float z2,
float start, float angle, LPPOINT3D vertex, short count);

void Ball3D (HDC hDC, float x, float y, float z, float r);

void Mark3D (HDC hDC, float x, float y, float z, LPSTR mark);

AssignPoint2D

Function

Assigns 2D homogeneous coordinate.

Syntax

```
void AssignPoint2D(POINT2D *point, float x, float y);
```

Remarks

AssignPoint2D sets the homogeneous coordinate in point by the x, y coordinate.

Return Value

None.

See also

[AssignPoint3D](#)

AssignPoint3D

Function

Assigns 3D homogeneous coordinate.

Syntax

```
void AssignPoint3D (POINT3D *point, float x, float y, float z);
```

Remarks

AssignPoint3D sets the homogeneous coordinate in point by the x, y, z coordinate.

Return Value

None.

See also

[AssignPoint2D](#)

BackfaceCulling

Function

Sets backface culling flag.

Syntax

short BackfaceCulling (short flag);

Remarks

BackfaceCulling sets the backface culling flag. If the flag is set to a nonzero value, the drawing functions will implement backface culling.

Return Value

BackfaceCulling returns the previous value of backface culling flag.

See also

[CountClockwise](#)

CountClockwise

Function

Sets the counter-clockwise flag.

Syntax

short CountClockwise (short flag);

Remarks

CountClockwise sets the counter-clockwise flag. The flag is used for backface culling to determine the direction of a polygon normal. If the flag is set to a nonzero value, the drawing functions will assume that a polygon is specified by the vertices in counter-clockwise order, i.e., the direction of the polygon normal is determined by the right-hand system.

Return Value

CountClockwise returns the previous value of the counter-clockwise flag.

See also

[BackfaceCulling](#)

BeginDoubleBuffer3D

Function

Starts double buffer mode.

Syntax

short BeginDoubleBuffer3D (HDC *hpdc, HVIEW hview);

Remarks

BeginDoubleBuffer3D starts the double buffer mode for the 3D viewer hview. hpdc is a pointer to the handle of the device context used by the viewer. After calling this function, all drawing function calls to the viewer will be redirected to a buffer. The buffer can be displayed by calling UpdateBuffer3D.

Return Value

On success, BeginDoubleBuffer3D returns 0. On error, it returns a nonzero value.

See also

[EndDoubleBuffer3D](#), [UpdateBuffer3D](#)

BeginDoubleBuffer2D

Function

Starts double buffer mode.

Syntax

```
short BeginDoubleBuffer2D (HDC *hdc, HVIEW hview);
```

Remarks

BeginDoubleBuffer2D starts the double buffer mode for the 2D viewer hview. hpdc is a pointer to the handle of the device context used by the viewer. After calling this function, all drawing function calls to the viewer will be redirected to a buffer. The buffer can be displayed by calling UpdateBuffer2D.

Return Value

On success, BeginDoubleBuffer2D returns 0. On error, it returns a nonzero value.

See also

[EndDoubleBuffer2D](#), [UpdateBuffer2D](#)

EndDoubleBuffer3D

Function

Ends double buffer mode.

Syntax

short EndDoubleBuffer3D (HDC *hdc, HVIEW hview);

Remarks

EndDoubelBuffer3D ends the double buffer mode and releases the memory allocated for the buffer.

Return Value

On success, EndDoubleBuffer3D returns 0. On error, it returns a nonzero value.

See also

[BeginDoubleBuffer3D](#), [UpdateBuffer3D](#)

EndDoubleBuffer2D

Function

Ends double buffer mode.

Syntax

short EndDoubleBuffer2D (HDC *hdc, HVIEW hview);

Remarks

EndDoubelBuffer2D ends the double buffer mode and releases the memory allocated for the buffer.

Return Value

On success, EndDoubleBuffer2D returns 0. On error, it returns a nonzero value.

See also

[BeginDoubleBuffer2D](#), [UpdateBuffer2D](#)

UpdateBuffer3D

Function

Displays the buffered image in the double buffer mode.

Syntax

short UpdateBuffer3D (HDC hdc, HVIEW hview);

Remarks

UpdateBuffer3D displays the buffered image in the double buffer mode. The content of the buffer is copied to the actual device context.

Return Value

On success, UpdateBuffer3D returns 0. On error, it returns a nonzero value.

See also

[BeginDoubleBuffer3D](#), [EndDoubleBuffer3D](#)

UpdateBuffer2D

Function

Displays the buffered image in the double buffer mode.

Syntax

short UpdateBuffer2D (HDC hdc, HVIEW hview);

Remarks

UpdateBuffer3D displays the buffered image in the double buffer mode. The content of the buffer is copied to the actual device context.

Return Value

On success, UpdateBuffer2D returns 0. On error, it returns a nonzero value.

See also

[BeginDoubleBuffer2D](#), [EndDoubleBuffer2D](#)

Tetrahedron

Function

Draws a tetrahedron.

Syntax

```
void Tetrahedron (HDC hdc, float r);
```

Remarks

Tetrahedron draws a tetrahedron in the current 3D viewer with current pen color the edges and current brush color for the interior. *r* specifies the radius of the circumscribing sphere.

Return Value

None.

See also

[Octahedron](#), [Dodecahedron](#), [Icosahedron](#)

Octahedron

Function

Draws a octahedron.

Syntax

```
void Octahedron (HDC hdc, float r);
```

Remarks

Octahedron draws a octahedron in the current 3D viewer with current pen color the edges and current brush color for the interior. r specifies the radius of the circumscribing sphere.

Return Value

None.

See also

[Tetrahedron](#), [Dodecahedron](#), [Icosahedron](#)

Dodecahedron

Function

Draws a dodecahedron.

Syntax

void Dodecahedron (HDC hdc, float r);

Remarks

Dodecahedron draws a dodecahedron in the current 3D viewer with current pen color the edges and current brush color for the interior. r specifies the radius of the circumscribing sphere.

Return Value

None.

See also

[Tetrahedron](#), [Octahedron](#), [Icosahedron](#)

Icosahedron

Function

Draws a icosahedron.

Syntax

```
void Icosahedron (HDC hdc, float r);
```

Remarks

Icosahedron draws a icosahedron in the current 3D viewer with current pen color the edges and current brush color for the interior. r specifies the radius of the circumscribing sphere.

Return Value

None.

See also

[Tetrahedron](#), [Octahedron](#), [Dodecahedron](#)

CreateViewer2D

Function

Creates a 2D viewer

Syntax

HVIEW CreateViewer2D (NPSTR Name, int X, int Y, int Width, int Height);

Remarks

CreateViewer2D creates a 2D viewer. The viewport dimension is Width by Height with Upper-left corner at (X,Y). The name of the viewer is given by Name.

Return Value

The viewer handle will be returned if it is created successfully. Otherwise, NULL will be returned. The function returns a handle to the viewer. The handle is used for all other Visualib functions to reference the viewer.

See also

[InitialGraphics2D](#), [SetViewport2D](#)

CreateViewer3D

Function

Creates a 3D viewer.

Syntax

HVIEW CreateViewer3D (NPSTR Name, int X, int Y, int Width, int Height);

Remarks

CreateViewer3D creates a 3-D viewer. The viewport dimension is Width by Height with upper-left corner at (X , Y). The name of the viewer is given by Name.

Return Value

The viewer handle will be returned if it is created successfully. Otherwise, NULL will be returned.

See also

[InitialGraphics3D](#), [SetViewport3D](#)

Max2DViewer

Function

Sets the default maximum number of 2D viewers.

Syntax

```
void Max2DViewer (short N);
```

Remarks

Max2DViewer sets the default maximum number of 2D viewers to N.

Return value

None.

See also

[CreatViewer2D](#), [InitialGraphics2D](#)

Max3DViewer

Function

Sets the default maximum number of 3D viewers.

Syntax

```
void Max3DViewer (short N);
```

Remarks

Max3DViewer sets the default maximum number of 3D viewers as N.

Return vlaue

None.

See also

[CreatViewer3D](#), [InitialGraphics3Df_initialgraphics3d](#)

Max2DMStack

Function

Sets the default maximum depth of the 2D transformation matrix stack.

Syntax

```
void Max2DMStack (short N);
```

Remarks

Max2DMStack sets the default maximum depth of the 2D transformation matrix stack as N.

Return value

None.

See also

[InitialGraphics2D](#)

Max3DMStack

Function

Sets the default maximum depth of the 3D transformation matrix stack.

Syntax

```
void Max3DMStack (short N);
```

Remarks

Max3DMStack sets the default maximum depth of the 3D transformation matrix stack as N.

Return value

None.

See also

[InitialGraphics3D](#)

InitialGraphics2D

Function

Initializes the 2D graphic system.

Syntax

short InitialGraphics2D (short nview, short npoint, short ndepth);

Remarks

InitialGraphics2D initializes the 2D graphic system with the specified maximum number of viewers, points, and depth of matrix stack. If any of the numbers is set to zero, the default maximum number will be used.

Return value

On successful completion, InitialGraphics2D returns 0. It returns a nonzero number on error.

See also

[ExitGraphics](#), [Max2DViewer](#), [Max2DMStack](#)

InitialGraphics3D

Function

Initializes the 3D graphic system.

Syntax

short InitialGraphics3D (short nview, short npoint, short ndepth);

Remarks

InitialGraphics3D initializes the 3D graphic system with specifying the maximum number of viewers, points, and depth of matrix stack. If any number is set to zero, the default maximum number will be used.

See also

[ExitGraphics](#), [Max2DViewer](#), [Max2DMStack](#)

ExitGraphics

Function

Exits the graphic system and free the memory used.

Syntax

```
void ExitGraphics (void);
```

Remarks

ExitGraphics exits the graphics systems. The memory allocated by Visualib is released.

Return value

None.

See Also

[InitialGraphics2D](#), [InitialGraphics3D](#)

PenColor

Function

Selects pen color.

Syntax

HPEN PenColor (HDC hDC, short Color);

Remarks

PenColor selects a system pen with color index for the current device context.

Return value

PenColor returns a handle to the previously selected pen.

See also

[BrushColor](#)

BrushColor

Function

Selects a brush color.

Syntax

HBRUSH BrushColor (HDC hDC, short Color);

Remarks

BrushColor selects a system brush with color index for the current device context.

Return value

BrushColor returns a handle to the previously selected brush.

See also

[PenColor](#)

PushMatrix2D

Function

Pushes the 2D transformation matrix stack.

Syntax

short PushMatrix2D (void);

Remarks

PushMatrix2D pushes the 2D transformation matrix stack. A copy of the stack top is pushed to the stack.

Return value

PushMatrix2D returns 0 upon successful completion. A nonzero value is returned if the stack is full.

See also

[PopMatrix2D](#)

PushMatrix3D

Function

Pushes the 3D transformation matrix stack.

Syntax

short PushMatrix3D (void);

Remarks

PushMatrix3D pushes the 3D transformation matrix stack. A copy of the stack top is pushed to the stack.

Return value

On success, PopMatrix3D returns 0. A nonzero value is returned if the stack is full.

See also

[PopMatrix3D](#)

PopMatrix2D

Function

Pops the 2D transformation matrix stack.

Syntax

short PopMatrix2D (void);

Remarks

PopMatrix2D pops the 2D transformation matrix stack. The stack top is discarded.

Return value

On success, PopMatrix2D returns 0. A nonzero value is returned if the stack is empty.

See also

[PushMatrix2D](#)

PopMatrix3D

Function

Pops the 3D transformation matrix stack.

Syntax

short PopMatrix3D (void);

Remarks

PopMatrix3D pops the 3D transformation matrix stack. The stack top is discarded.

Return value

On success, PopMatrix3D returns 0. A nonzero value is returned if the stack is empty.

See also

[PushMatrix3D](#)

SetView3D

Function

Sets 3D viewer's view transformation matrix.

Syntax

short SetView3D (HVIEW Hview, float VX, float VY, float VZ, float RX, float RY, float RZ, float Twist);

Remarks

SetView3D sets 3D viewer Hview's viewing transformation matrix according to the viewer position VX, VY, and VZ; the view reference RX, RY, and RZ; and the viewer Twist angle.

Return value

On success, SetView3D returns 0. On error, it returns a nonzero value.

See also

[SetPolarView3D](#)

SetPolarView3D

Function

Sets 3D viewer based on polar coordinates.

Syntax

short SetPolarView3D (HVIEW Hview, float CX, float CY, float CZ, float Dist, float Azim, float Inc, float Twist);

Remarks

SetPolarView3D sets viewer Hview's viewing transformation matrix according to the reference center CX, CY, and CZ; the Dist form the reference center to the viewer; and the three orientation angles Azim, Inc, and Twist.

Return value

On success, SetPolarView3D returns 0. On error, it returns a nonzero value.

See also

[SetView3D](#)

SetPerspective3D

Function

Sets perspective projection of a 3D viewer.

Syntax

short SetPerspective3D (HVIEW Hview, float Fovy, float Aspect, float Front, float Back);

Remarks

SetPerspective sets 3D viewer Hview's perspective projection matrix according to the field of view angle of Fovy, Aspect ratio, Front and Back clipping panes.

Return value

On success, SetPerspective3D returns 0. On error, it returns a nonzero value.

See also

[SetOrthogonal3D](#)

SetOrthogonal3D

Function

Sets orthogonal projection of a 3D viewer.

Syntax

short SetOrthogonal3D (HVIEW Hview, float Left, float Right, float Bottom, float Top, float Front, float Back);

Remarks

SetOrthogonal3D sets 3D viewer Hview's orthogonal projection matrix according to the viewing box defined by the Left, Right, Bottom, Top, Front, and Back .

Return value

On success, SetOrthogonal3D returns 0. On error, it returns a nonzero value.

See also

[SetPerspective3D](#)

SetViewport2D

Function

Sets a 2D viewer's viewport.

Syntax

short SetViewport2D (HVIEW Hview, short X, short Y, short Width, short Height);

Remarks

SetViewport2D sets 2D viewer Hview's viewport according to the upper left point (X,Y) and the Width and Height in display coordinates.

Return value

On success, SetViewport2D returns 0. On error, it returns a nonzero value.

See also

[GetViewport2D](#)

SetViewport3D

Function

Sets 3D viewer's viewport .

Syntax

short SetViewport3D (HVIEW Hview, short X, short Y, short Width, short Height);

Remarks

SetViewport3D sets 3D viewer Hview's viewport according to the upper left point (X,Y) and the Width and Height in display coordinates.

Return value

On success, SetViewport3D returns 0. On error, it returns a nonzero value.

See also

[GetViewport3D](#)

SetView2D

Function

Sets a 2D viewer's viewing transformation matrix .

Syntax

short SetView2D (HVIEW Hview, float X, float Y, float Angle);

Remarks

SetView2D sets 2D viewer's view transformation according to the center coordinates X, Y, and the rotation Angle.

Return value

On success, SetView2D returns 0. On error, it returns a nonzero value.

See also

[SetWindow2D](#)

SetProjection2D

Function

Sets 2D viewer's projection transformation.

Syntax

short SetProjection2D (HVIEW Hview, float Left, float Right, float Bottom, float Top);

Remarks

SetProjection2D sets 2D viewer Hview's projection transformation according to the two corner points of the projection rectangle defined by Left, Right, Bottom, and Top.

Return value

On success, SetProjection2D returns 0. On error, it returns a nonzero value.

See also

[SetWindow2D](#)

SetWindow2D

Function

Sets 2D viewer's viewing and projection transformations.

Syntax

short SetWindow2D (HVIEW Hview, float X1, float Y1, float X2, float Y2);

Remarks

Set 2D viewer's viewing transformation and projection transformation according to the two corner points in the world coordinates defined by X1, Y1, X2, and Y2.

Return value

On success, SetWindow2D returns 0. On error, it returns a nonzero value.

See also

[SetView2D](#), [SetProjection2D](#)

SelectViewer3D

Function

Selects a 3D viewer.

Syntax

short SelectViewer3D (HVIEW hview);

Remarks

SelectViewer3D selects viewer Hview as the current 3D viewer. The subsequent 3D drawing function calls will use this viewer. hview must be a valid viewer handle returned by CreateViewer3D.

Return value

On success, SelectViewer3D returns 0. On error, it returns a nonzero value.

See also

[CreateViewer3D](#)

SelectViewer2D

Function

Selects 2D viewer.

Syntax

short SelectViewer2D (HVIEW hview);

Remarks

SelectViewer2D selects viewer Hview as the current 2D viewer. The subsequent 2D drawing function calls will use this viewer. hview must be a valid viewer handle returned by CreateViewer2D.

Return value

On success, SelectViewer2D returns 0. On error, it returns a nonzero value.

See also

[CreateViewer2D](#)

DisplayViewerFrame2D

Function

Displays the frame of a 2D viewer.

Syntax

short DisplayViewerFrame2D (HDC hdc, HVIEW hview, short color);

Remarks

DisplayViewerFrame2D draws the 2D viewer Hview's rectangle border with Color. The frame is defined by the viewport set in the function CreateViewer2D or SetViewport2D.

Return value

On success, DisplayViewerFrame2D returns 0. On error, it returns a nonzero value.

See also

[CreateViewer2D](#), [SetViewport2D](#)

DisplayViewerFrame3D

Function

Displays the frame of a 3D viewer.

Syntax

short DisplayViewerFrame3D (HDC hdc, HVIEW hview, short color);

Remarks

DisplayViewerFrame3D draws the 3D viewer Hview's rectangle border with Color. The frame is defined by the viewport set in the function CreateViewer3D or SetViewport3D.

Return value

On success, DisplayViewerFrame3D returns 0. On error, it returns a nonzero value.

See also

[CreateViewer3D](#), [SetViewport3D](#)

DisplayViewerName2D

Function

Display 2D viewer's name.

Syntax

short DisplayViewerName2D (HDC hdc, HVIEW hview, short color, short top);

Remarks

DisplayViewerName2D displays the viewer Hview's name with Color.

Return value

On success, DisplayViewerName2D returns 0. On error, it returns a nonzero value.

See also

[GetViewerName2D](#), [SetViewerName2D](#)

DisplayViewerName3D

Function

Displays a 3D viewer's name.

Syntax

short DisplayViewerName3D (HDC hDC, HVIEW hview, short color, short top);

Remarks

Display 3D viewer Hview's name with Color.

Return value

On success, DisplayViewerName3D returns 0. On error, it returns a nonzero value.

See also

[GetViewerName3D](#), [SetViewerName3D](#)

ClearViewer2D

Function

Clears a 2D viewer.

Syntax

short ClearViewer2D (HDC hDc, HVIEW hview, short color);

Remarks

ClearViewer2D clears a 2D viewer Hview's client area with Color.

Return value

On success, ClearViewer2D returns 0. On error, it returns a nonzero value.

See also

[CreateViewer2D](#)

ClearViewer3D

Function

Clears a 3D viewer.

Syntax

short ClearViewer3D (HDC hDc, HVIEW hview, short color);

Remarks

ClearViewer3D clears a 3D viewer's client area with Color.

Return value

On success, ClearViewer3D returns 0. On error, it returns a nonzero value.

See also

[CreateViewer3D](#)

MoveViewer3D

Function

Moves a 3D viewer.

Syntax

short MoveViewer3D (HVIEW Hview, float LeftRight, float UpDow, float BackForth);

Remarks

MoveViewer3D moves the 3D viewer Hview in the view coordinate system according to LeftRight, UpDown, and BackForth.

Return value

On success, MoveViewer3D returns 0. On error, it returns a nonzero value.

See also

[MoveWorld3D](#)

MoveWorld3D

Function

Moves a 3D viewer.

Syntax

short MoveWorld3D (HVIEW Hview, float X, float Y, float Z);

Remarks

Moves 3D viewer Hview in the world coordinate system along X, Y, and Z.

Return value

On success, MoveWorld3D returns 0. On error, it returns a nonzero value.

See also

[MoveViewer3D](#)

RotateViewer3D

Function

Rotate a 3D viewer.

Syntax

short RotateViewer3D (HVIEW Hview, float Yaw, float Pitch, float Twist);

Remarks

RotateViewer3D rotates the 3D viewer Hview in the view coordinate system according to angles of Yaw, Pitch, and Twist with unit of degrees.

Return value

On success, RotateViewer3D returns 0. On error, it returns a nonzero value.

See also

[RotateWorld3D](#)

RotateWorld3D

Function

Rotates a 3D viewer.

Syntax

short RotateWorld3D (HVIEW Hview, float X, float Y, float Z);

Remarks

RotateWorld3D rotates the 3D viewer Hview in the world coordinate system around X, Y, and Z Axes with unit of degrees.

Return value

On success, RotateWorld3D returns 0. On error, it returns a nonzero value.

See also

[RotateViewer3D](#)

ZoomViewer3D

Function

Zooms a 3D viewer.

Syntax

short ZoomViewer3D (HVIEW Hview, float Zoom);

Remarks

ZoomViewer3D zooms the 3D viewer Hview by factor Zoom.

Return value

On success, ZoomViewer3D returns 0. On error, it returns a nonzero value.

See also

[ZoomWorld3D](#)

ZoomWorld3D

Function

Zooms a 3D viewer.

Syntax

short ZoomViewer3D (HVIEW Hview, float Zoom);

Remarks

ZoomViewer3D zooms the 3D viewer Hview by factor Zoom.

Return value

On success, ZoomViewer3D returns 0. On error, it returns a nonzero value.

See also

[ZoomViewer3D](#)

MoveViewer2D

Function

Moves a 2D viewer.

Syntax

short MoveViewer2D (HVIEW hview, float LeftRight, float UpDown);

Remarks

MoveViewer2D changes the viewing transformation of a 2D viewer Hview by moving it in the view coordinate system according to LeftRight and UpDown.

Return value

On success, MoveViewer2D returns 0. On error, it returns a nonzero value.

See also

[RotateViewer2D](#)

RotateViewer2D

Function

Rotates a 2D viewer.

Syntax

short RotateViewer2D (HVIEW hview, float Angle);

Remarks

RotateViewer2D rotates the 2D viewer Hview by Angle degrees.

Return value

On success, RotateViewer2D returns 0. On error, it returns a nonzero value.

See also

[MoveViewer2D](#)

Num2DViewer

Function

Gets the number of 2D viewers created in the current system.

Syntax

short Num2DViewer (void);

Remarks

Num2DViewer gets the number of 2D viewers created in the current system.

Return value

Num2DViewer returns the number of 2D viewers.

See also

[CreateViewer2D](#)

Num3DViewer

Function

Gets the number of 3D viewers created in the current system.

Syntax

short Num3DViewer (void);

Remarks

Num3DViewer gets the number of 3D viewers created in the current system.

Return value

Num3DViewer returns the number of 3D viewers.

See also

[CreatViewer3D](#)

ViewerPosition3D

Function

Gets a 3D viewer's position.

Syntax

short ViewerPosition3D (HVIEW Hview, float *VX, float *VY, float *VZ);

Remarks

ViewerPosition3D gets the 3D viewer Hview's position in the world coordinate system VX, VY, and VZ .

Return value

On success, ViewerPosition3D returns 0. On error, it returns a nonzero value.

See also

[SetView3D](#)

ViewerOrientation3D

Function

Gets a 3D viewer's orientation.

Syntax

short ViewerOrientation3D (HVIEW Hview, float *Azim, float *Inc, float *Twist);

Remarks

ViewOrientation3D gets 3D viewer Hview's orientation in the world coordinate system Azim, Inc, and Twist.

Return value

On success, ViewerOrientation3D returns 0. On error, it returns a nonzero value.

See also

[SetPolarView3D](#)

ViewerDirection3D

Function

Gets a 3D viewer's direction.

Syntax

short ViewerDirection3D (HVIEW Hview, float *X, float *Y, float *Z);

Remarks

ViewerDirection3D gets the 3D viewer Hview's direction vector's three components X, Y, and Z on the three axes of the world coordinate system .

Return value

On success, ViewerDirection3D returns 0. On error, it returns a nonzero value.

See also

[SetView3D](#)

ViewProjectionMode3D

Function

Get 3D viewer Hview's projection mode.

Syntax

short ViewProjectionMode3D (HVIEW Hview);

Remarks

Return value

See also

ViewerPosition2D

Function

Gets a 2D viewer's center position.

Syntax

short ViewerPosition2D (HVIEW Hview, float *CX, float *CY, float *Angle);

Remarks

ViewerPosition2D gets the 2D viewer Hview's center position CX, CY and the rotation Angle in the world coordinate system.

Return value

On success, ViewerPosition2D returns 0. On error, it returns a nonzero value.

See also

[SetView2D](#)

ViewerField3D

Function

Gets a 3D viewer's viewing field.

Syntax

short ViewerField3D (HVIEW Hview, float *Left, float *Right, float *Bottom, float *Top, float *Width, float *Height);

Remarks

ViewerField3D gets the 3D viewer Hview's viewing field defined by Left, Right, Bottom, Top, Front, and Back in the view coordinate system.

Return value

On success, ViewerField3D returns 0. On error, it returns a nonzero value.

See also

[SetPerspective3D](#), [SetOrthogonal3D](#)

ViewerField2D

Function

Gets a 2D viewer's viewing field.

Syntax

short ViewerField2D (HVIEW Hviwe, float *Left, float *Right, float *Bottom, float *Top);

Remarks

ViewerField2D gets the 2D viewer Hview's viewing field defined by Left, Right, Bottom, and Top in the view coordinate system.

Return value

On success, ViewerField2D returns 0. On error, it returns a nonzero value.

See also

[SetProjection2D](#)

Rotate3D

Function

Rotates on the current transformation matrix.

Syntax

```
void Rotate3D (float Angle, char Axis);
```

Remarks

Rotate3D rotates on the current 3D transformation matrix (the stack top) by the amount specified. Axis can be 'x', 'y', or 'z'. Angle is measured in degrees.

Return value

None

See also

[Translate3D](#), [Scale3D](#)

Translate3D

Function

Translates on the current 3D transformation matrix.

Syntax

```
void Translate3D (float X, float Y, float Z);
```

Remarks

Translate3D performs a 3D modeling transformation on the current 3D transformation matrix by a translation of (X,Y,Z).

Return value

None.

See also

[Rotate3D](#), [Scale3D](#)

Scale3D

Function

Scales on the current 3D transformation matrix .

Syntax

```
void Scale3D (float X, float Y, float Z);
```

Remarks

Scale3D scales on the current 3D transformation matrix (the stack top) in the x , y, and z directions by the amounts specified.

Return value

None.

See also

[Translate3D](#), [Rotate3D](#)

Translate2D

Function

Translates on the current 2D transformation matrix.

Syntax

```
void Translate2D (float X, float Y);
```

Remarks

Translate2D translates on the current 2D transformation matrix (the stack top) in the x and y directions by the amounts specified.

Return value

None.

See also

[Rotate2D](#), [Scale2D](#)

Rotate2D

Function

Rotates on the current 2D transformation matrix.

Syntax

```
void Rotate2D (float Angle);
```

Remarks

Rotate2D rotates on the current 2D transformation matrix (the stack top) by the amounts specified.

Return value

None.

See also

[Translate2D](#), [Scale2D](#)

Scale2D

Function

Scales on the current 2D transformation matrix.

Syntax

```
void Scale2D (float x, float y);
```

Remarks

Scale2D scales on the current 2D transformation matrix (the stack top) in the x and y directions by the amounts specified.

Return value

None.

See also

[Translate2D](#), [Rotate2D](#)

GetViewerName2D

Function

Gets the name of a 2D viewer.

Syntax

short GetViewerName2D (HVIEW hview, NPSTR name);

Remarks

GetViewerName2D gets the name string of the 2D viewer hview.

Return value

On success, GetViewerName2D returns 0. On error, it returns a nonzero value.

See also

[DisplayViewerName2D](#), [SetViewerName2D](#)

SetViewerName2D

Function

Sets the name of a 2D viewer.

Syntax

short SetViewerName2D (HVIEW hview, NPSTR name);

Remarks

SetViewerName2D sets the name string of the 2D viewer hview.

Return value

On success, SetViewerName2D returns 0. On error, it returns a nonzero value.

See also

[DisplayViewerName2D](#), [GetViewerName2D](#)

GetViewerName3D

Function

Gets the name of a 3D viewer.

Syntax

short GetViewerName3D (HVIEW hview, NPSTR name);

Remarks

GetViewerName3D gets the name string of the 3D viewer hview.

Return value

On success, GetViewerName3D returns 0. On error, it returns a nonzero value.

See also

[DisplayViewerName3D](#), [SetViewerName3D](#)

SetViewerName3D

Function

Sets the name of a 3D viewer.

Syntax

short SetViewerName3D (HVIEW hview, NPSTR name);

Remarks

SetViewerName3D sets the name string of the 3D viewer hview.

Return value

On success, SetViewerName3D returns 0. On error, it returns a nonzero value.

See also

[DisplayViewerName3D](#), [GetViewerName3D](#)

GetViewport2D

Function

Gets the position of a 2D viewport.

Syntax

short GetViewport2D (HVIEW Hview, short *X, short *Y, short *Width, short *Height);

Remarks

GetViewport2D gets the 2D viewer Hview's viewport position in display coordinates as the upper-left corner X and Y, and the Width and Height.

Return value

On success, GetViewport2D returns 0. On error, it returns a nonzero value.

See also

[SetViewport2D](#)

GetViewport3D

Function

Gets the position of a 3D viewport.

Syntax

short GetViewport3D (HVIEW Hview, short *X, short *Y, short *Width, short *Height);

Remarks

GetViewport3D gets 3D viewer Hview's viewport position in display coordinates as the upper-left corner X and Y, and the Width and Height.

Return value

On success, GetViewport3D returns 0. On error, it returns a nonzero value.

See also

[SetViewport3D](#)

MoveTo2D

Function

Moves to a new position.

Syntax

```
void MoveTo2D (HDC hDC, float X, float Y);
```

Remarks

MoveTo2D moves the current 2D display position to X and Y in the current viewer.

Return value

None.

See also

[LineTo2D](#)

LineTo2D

Function

Draws a 2D line to a new position.

Syntax

```
void LineTo2D (HDC hDC, float X, float Y);
```

Remarks

LineTo2D draws a 2D line from the current 2D display position to X and Y in the current viewer with the current pen.

Return value

None.

See also

[MoveTo2D](#)

DrawLine2D

Function

Draws a 2D line segment.

Syntax

```
void DrawLine2D (HDC hDC, float X1, float Y1, float X2, float Y2);
```

Remarks

DrawLine2D draws a 2D line from X1 and Y1 to X2 and Y2 in the current 2D viewer with the current pen.

Return value

None.

See also

[LineTo2D](#), [MoveTo2D](#)

Polyline2D

Function

Draws a 2D polyline.

Syntax

void Polyline2D (HDC hdc, LPPOINT2D Point, short N);

Remarks

Polyline2D draws a 2D polyline defined by N 2D Points in the current 2D viewer with current pen for edges and current brush for interior.

Return value

None.

See also

[Polygon2D](#)

Polygon2D

Function

Draws a 2D polygon.

Syntax

void Polygon2D (HDC hdc, LPPOINT2D point, short count);

Remarks

Polygon2D draws a 2D polygon defined by N 2D Points in the current 2D viewer with current pen for edges and current brush for interior.

Return value

None.

See also

[Polyline2D](#)

ResetVertex2D

Function

Reset temporary 2D point buffer Point2D to empty.

Syntax

```
void ResetVertex2D (void);
```

Remarks

Return value

None.

See also

SetVertex2D

Function

Set one 2D point X and Y into the 2D point buffer Point2D

Syntax

```
void SetVertex2D (float X, float Y);
```

Remarks

Return value

None.

See also

Rectangle2D

Function

Draws a 2D rectangle.

Syntax

```
void Rectangle2D (HDC hDC, float X1, float Y1, float X2, float Y2);
```

Remarks

Rectangle2D draws a 2D rectangle defined by X1, Y1, X2, and Y2 in the current 2D viewer with current pen for edge and current brush for interior.

Return value

None.

See also

[Polygon2D](#)

Circle2D

Function

Draws a 2D circle..

Syntax

```
void Circle2D (HDC hDC, float X, float Y, float Radius);
```

Remarks

Circle2D draws a 2D circle defined by center X, Y and Radius in the current 2D viewer with current pen for edge and current brush for interior.

Return value

None.

See also

[Arc2D](#)

Arc2D

Function

Draws a 2D circular arc.

Syntax

```
void Arc2D (HDC hDC, float x, float y, float r, float start, float angle);
```

Remarks

Arc2D draws a 2D circular arc in the current 2D viewer with the current pen color. (x,y) is the center of the circle and r is the radius of the circle. The starting angle and the span of the arc are specified by the parameter start and angle measured in degrees.

Return Value

None.

See also

[Circle2D](#)

EllipseArc2D

Function

Draws a 2D elliptic arc.

Syntax

void EllipseArc2D (HDC hDC, float x, float y, float r1, float r2, float start, float angle);

Remarks

EllipseArc2D draws a 2D elliptic arc in the current 2D viewer with the current pen color. (x,y) is the center of the ellipse and r1, r2 are the half-axes of the ellipse. The starting angle and the span of the arc are specified by the parameter start and angle measured in degrees.

Return Value

None.

See also

[Ellipse2D](#)

Wedge2D

Function

Draws a 2D circular wedge.

Syntax

```
void Wedge2D (HDC hDC, float x, float y, float r1, float r2, float start, float angle);
```

Remarks

Wedge2D draws a 2D circular wedge in the current 2D viewer with the current pen color. (x,y) is the center of the circle and r is the radius of the circle. The starting angle and the span of the arc are specified by the parameter start and angle measured in degrees.

Return Value

None.

See also

[Arc2D](#)

Ellipse2D

Function

Draws a 2D ellipse.

Syntax

```
void Ellipse2D (HDC hDC, float x, float y, float r1, float r2);
```

Remarks

Ellipse2D draws a 2D ellipse defined by center X, Y and two radius R1 and R2 in the current 2D viewer with current pen for edge and current brush for interior.

Return value

None.

See also

[EllipseArc2D](#)

Ngon2D

Function

Draws a 2D N-sided regular polygon.

Syntax

void Ngon2D (HDC hDC, float X, float Y, float R1, float R2, short N);

Remarks

Ngon2D draws a 2D N-sided regular polygon define by ceter X, Y and two radius R1 and R2 in the current 2D viewer with current pen for edge and current brush for interior.

Return value

None.

See also

[Polygon2D](#)

NsideStar2D

Function

Draws a 2D N-point star.

Syntax

```
void NsideStar2D (HDC hDC, float X, float Y, float Radius, short N);
```

Remarks

NsideStar2D draws a 2D N-point regular star defined by center X, Y and Radius in the current 2D viewer with current pen for edge and current brush for interior.

Return value

None.

See also

[Polygon2D](#)

NsideFlower2D

Function

Draw a 2D N-point flower.

Syntax

```
void NsideFlower2D (HDC hDC, float X, float Y, float R1, float R2, short N);
```

Remarks

Draw a 2D N-point flower defined by center X, Y, and the inner and outer radius R1 and R2 in the current 2D viewer with current pen for edge and current brush for interior

Return value

None.

See also

[Polygon2D](#)

MoveTo3D

Function

Move current 3D display position.

Syntax

void MoveTo3D (HDC hDC, float X, float Y, float Z);

Remarks

MoveTo3D moves current 3D display position to X, Y, and Z in the current 3D viewer.

Return value

None.

See also

[LineTo3D](#)

LineTo3D

Function

Draws a 3D line to a new position.

Syntax

```
void LineTo3D (HDC hdc, float x, float y, float z);
```

Remarks

LineTo3D draws a 3D line from the current display position to X, Y, and Z in the current viewer with current pen.

Return value

None.

See also

[Moveto3D](#)

DrawLine3D

Function

Draws a 3D line segment.

Syntax

```
void DrawLine3D (HDC hDC, float X1, float Y1, float Z1, float X2, float Y2, float Z2);
```

Remarks

DrawLine3D draws a 3D line from X1, Y1, and Z1 to X2, Y2, and Z2 in the current 3D viewer with current pen.

Return value

None.

See also

[LineTo3D](#), [MovoTo3D](#)

MarkPosition3D

Function

Draws 3D axes.

Syntax

```
void MarkPosition3D (HDC hdc, float x, float y, float z, float scale);
```

Remarks

MarkPosition3D draws a 3D axes in size of Scale at X, Y, and Z in the current 3D viewer with red, green, and blue for the three axes.

Return value

None.

See also

[CreateViewer3D](#)

Polyline3D

Function

Draw a 3D polyline.

Syntax

void Polyline3D (HDC hdc, LPPOINT3D Point, short N);

Remarks

Polyline3D draws a polyline defined by N 3D Point with current pen for the edge and current brush for the interior in the current viewer.

Return value

None.

See also

[Polygon3D](#)

Polygon3D

Function

Draws a 3D polygon.

Syntax

```
void Polygon3D (HDC hDC, LPPOINT3D Point, short N);
```

Remarks

Polygon3D draws a polygon defined by N 3D Point with current pen for the edge and current brush for the interior in the current viewer.

Return value

None.

See also

[Polyline3D](#)

ResetVertex3D

Function

Reset the temporary 3D point buffer Point3D to empty

Syntax

```
void ResetVertex3D (void);
```

Remarks

Return value

See also

SetVertex3D

Function

Set a 3D point X, Y, and Z into the 3D point buffer Point3D

Syntax

```
void SetVertex3D (float X, float Y, float Z);
```

Remarks

Return value

None.

See also

Shape3D

Function

Draw a 2D shape defined by N 2D Point at X, Y, and Z in MS Windows' device context hDC with current pen for the edge and current brush for the interior

Syntax

```
void Shape3D (HDC hDC, float X, float Y, float Z, LPPOINT2D Point, short N);
```

Remarks

Draw a 2D shape defined by N 2D Point at X, Y, and Z in MS Windows' device context hDC with current pen for the edge and current brush for the interior

Return value

None.

See also

Rectangle3D

Function

Draw a Rectangle.

Syntax

void Rectangle3D (HDC hDC, float X1, float Y1, float X2, float Y2, float Z);

Remarks

Rectangle3D draws a Rectangle defined by X1, Y1, X2, and Y2 and elevation Z in the current 3D viewer with current pen for the edge and current brush for the interior.

Return value

None.

See also

[Polygon3D](#)

Prism3D

Function

Draws a 3D prism.

Syntax

```
void Prism3D (HDC hDC, float X, float Y, float Z, float H, LPPOINT2D BaseVertex, LPPOINT2D HeadVertex, short N);
```

Remarks

Prism3D draws a 3D prism defined by the N point base shape BaseVertex and head shape HeadVertex at X, Y, and Z with current pen for the facets edges and the current brush for the facet interior.

Return value

None.

See also

[NsidePrism3D](#)

Pyramid3D

Function

Draws a pyramid.

Syntax

```
void Pyramid3D (HDC hDC, float x, float y, float z, float height, LPPOINT2D basevertex, short count);
```

Remarks

Pyramid3D draws a pyramid in the current 3D viewer. The apex is specified by (x,y,z). The vertices of the based is in the array basevertex and the number of base vertices is given by count.

Return Value

None.

See also

[NsidePyramid3D](#)

NsideStar3D

Function

Draw a 3D N point star.

Syntax

```
void NsideStar3D (HDC hDC, float X, float Y, float Z, float H, float R, short N);
```

Remarks

NsideStar3D draw a 3D N point regular star defined by H and R and X, Y, and Z with current pen for the facet edges and the current brush for the facet interior.

Return value

None.

See also

[NsideFlower3D](#)

NsideFlower3D

Function

Draw a 3D N point flower.

Syntax

```
void NsideFlower3D (HDC hDC, float X, float Y, float Z, float H, float R1, float R2, short N);
```

Remarks

NsideFlower3D draws a 3D N point regular flower defined by R1, R2, and H at X, Y, and Z with current pen for the facet edges and the current brush for the facet interior.

Return value

None.

See also

[NsideStar3D](#)

Cube3D

Function

Draws a 3D rectangular box.

Syntax

```
void Cube3D (HDC hDC, float x1, float y1, float z1, float x2, float y2, float z2);
```

Remarks

Cube3D draws a 3D rectangular box defined by two corner points X1, Y1, Z1 and X2, Y2, Z2 with current pen for the facet edges and the current brush for the facet interior

Return value

None.

See also

[Rectangle3D](#)

Sphere3D

Function

Draws a sphere.

Syntax

```
void Sphere3D (HDC hDC, float X, float Y, float Z, float R, short N1, short N2);
```

Remarks

Sphere3D draws a spherical polyhedron with radius R at X, Y, and Z in the current 3D viewer with current pen for the facet edges and the current brush for the facet interior

Return value

None.

See also

[Cylinder3d](#), [Cone3D](#)

NsidePyramid3D

Function

Draws a regular 3D pyramid.

Syntax

```
void NsidePyramid3D (HDC hDC, float X, float Y, float Z, float R, float H, short N);
```

Remarks

Draw a vertical 3D N sided regular pyramid defined by radius R and height H at position X, Y, and Z in the current viewer with current pen for the facet edges and the current brush for the facet interior

Return value

None.

See also

[Pyramid3D](#)

Cone3D

Function

Draws a cone.

Syntax

```
void Cone3D (HDC hDC, float X, float Y, float Z, float R, float H);
```

Remarks

Cone3D draws a vertical 3D cone define by radius R and height H at position X, Y, and Z in the current viewer with current pen for the facet edges and the current brush for the facet interior

Return value

None.

See also

[Cylinder3D](#)

NsidePrism3D

Function

Draws an N sided regular prism.

Syntax

```
void NsidePrism3D (HDC hDC, float X, float Y, float Z, float R, float H, short N);
```

Remarks

Draw a vertical 3D N side prism defined by radius R and height H at X, Y, and Z with current pen for the facet edges and the current brush for the facet interior.

Return value

None.

See also

[Prism3D](#)

Cylinder3D

Function

Draw a 3D cylinder.

Syntax

void Cylinder3D (HDC hDC, float X, float Y, float Z, float R, float H);

Remarks

Cylinder3D draws a vertical 3D cylinder defined by radius R and height H at position X, Y, and Z in the current 3D viewer with current pen for the facet edges and the current brush for the facet interior.

Return value

None.

See also

[Cone3D](#)

BezierCurve2D

Function

Draws a 2D Bezier curve.

Syntax

```
void BezierCurve2D(HDC hdc, LPPOINT2D CtrlPolygon);
```

Remarks

BezierCurve2D draws a Bezier curve in the current 2D viewer. The curve is specified by four control points in the CtrlPolygon.

Return value

None.

See also

[BSplineCurve2D](#), [HermitCurve2D](#), [NURBSCurve2D](#)

HermitCurve2D

Function

Draws a 2D Hermit curve.

Syntax

```
void HermitCurve2D(LPPOINT2D CtrlPolygon);
```

Remarks

HermitCurve2D draws a Hermit curve in the current 2D viewer. The curve is specified by four control points in the CtrlPolygon.

Return value

None.

See also

[BezierCurve2D](#), [BSplineCurve2D](#), [NURBSCurve2D](#)

BSplineCurve2D

Function

Draws a 2D uniform non-rational B-Spline curve.

Syntax

```
void BSplineCurve2D(HDC hdc, LPPOINT2D CtrlPolygon, int N);
```

Remarks

BezierCurve2D draws a uniform non-rational B-Spline curve in the current 2D viewer. The curve is specified by N control points in the CtrlPolygon. The first and the last knots are of multiplicity 3 and all other knots are simple and uniformly spaced.

Return value

None.

See also

[BezierCurve2D](#), [HermitCurve2D](#), [NURBSCurve2D](#)

NURBSCurve2D

Function

Draws a 2D NURBS curve.

Syntax

```
void NURBSCurve2D(HDC hdc, LPPOINT2D CtrlPolygon, int N, float Knots[]);
```

Remarks

NURBSCurve2D draws a non-uniform rational B-spline (NURBS) curve in the current 2D viewer. The curve is specified by N control points in the CtrlPolygon and N+2 Knots.

Return value

None.

See also

[BezierCurve2D](#), [BSplineCurve2D](#), [HermitCurve2D](#)

BezierCurve3D

Function

Draws a 3D Bezier curve.

Syntax

```
void BezierCurve3D(HDC hdc, LPPOINT3D CtrlPolygon);
```

Remarks

BezierCurve3D draws a Bezier curve in the current 3D viewer. The curve is specified by four control points in the CtrlPolygon.

Return value

None.

See also

[BSplineCurve3D](#), [HermitCurve3D](#), [NURBSCurve3D](#)

HermitCurve3D

Function

Draws a 3D Hermit curve.

Syntax

```
void HermitCurve3D(LPPOINT3D CtrlPolygon);
```

Remarks

HermitCurve3D draws a Hermit curve in the current 3D viewer. The curve is specified by four control points in the CtrlPolygon.

Return value

None.

See also

[BezierCurve3D](#), [BSplineCurve3D](#), [NURBSCurve3D](#)

BSplineCurve3D

Function

Draws a 3D uniform non-rational B-Spline curve.

Syntax

```
void BSplineCurve3D(HDC hdc, LPPOINT3D CtrlPolygon, int N);
```

Remarks

BezierCurve3D draws a uniform non-rational B-Spline curve in the current 3D viewer. The curve is specified by N control points in the CtrlPolygon. The first and the last knots are of multiplicity 3 and all other knots are simple and uniformly spaced.

Return value

None.

See also

[BezierCurve3D](#), [HermitCurve3D](#), [NURBSCurve3D](#)

NURBSCurve3D

Function

Draws a 3D NURBS curve.

Syntax

```
void NURBSCurve3D(HDC hdc, LPPOINT3D CtrlPolygon, int N, float Knots[]);
```

Remarks

NURBSCurve3D draws a non-uniform rational B-spline (NURBS) curve in the current 3D viewer. The curve is specified by N control points in the CtrlPolygon and N+2 Knots.

Return value

None.

See also

[BezierCurve3D](#), [BSplineCurve2D](#), [HermitCurve3D](#)

BezierSurface3D

Function

Draws a 3D Bezier surface.

Syntax

```
void BezierSurface3D(HDC hdc, LPPOINT3D CtrlNet, int Ns, int Nt);
```

Remarks

BezierSurface3D draws a Bezier surface in the current 3D viewer. The curve is specified by the CtrlNet which is an array of 4 by 4 points. The surface is drawn in wire-frame form with Ns+1 lines in s direction and Nt+1 lines in the t direction.

Return value

None.

See also

[BSplineSurface3D](#), [HermitSurface3D](#), [NURBSSurface3D](#)

HermitSurface3D

Function

Draws a 3D Hermit surface.

Syntax

```
void HermitSurface3D(LPPOINT3D CtrlNet);
```

Remarks

HermitCurve3D draws a Hermit curve in the current 3D viewer. The curve is specified by four control points in the CtrlPolygon. The surface is drawn in wire-frame form with N_s+1 lines in s direction and N_t+1 lines in the t direction.

Return value

None.

See also

[BezierSurface3D](#), [BSplineSurface3D](#), [NURBSSurface3D](#)

BSplineSurface3D

Function

Draws a 3D uniform non-rational B-Spline surface.

Syntax

```
void BSplineSurface3D(HDC hdc, LPPOINT3D CtrlPolygon, int N, int Ns, int Nt);
```

Remarks

BSplineSurface3D draws a uniform non-rational B-Spline surface in the current 3D viewer. The curve is specified by N control points in the CtrlPolygon. The first and the last knots are of multiplicity 3 and all other knots are simple and uniformly spaced. The surface is drawn in wire-frame form with N_s+1 lines in s direction and N_t+1 lines in the t direction for each rectangular patch.

Return value

None.

See also

[BezierCurve3D](#), [HermitCurve3D](#), [NURBSCurve3D](#)

NURBSSurface3D

Function

Draws a 3D NURBS surface.

Syntax

```
void NURBSSurface3D(HDC hdc, LPPOINT3D CtrlPolygon, float SKnots[], float TKnot[], int  
SCount, int TCount, int Ns, int Nt);
```

Remarks

NURBSSurface3D draws a non-uniform rational B-spline (NURBS) surface in the current 3D viewer. The surface is specified by SCount by TCount control points in the CtrlPolygon and with SCount+2 SKnots and TCount+2 TKnots. The surface is drawn in wire-frame form with Ns+1 lines in s direction and Nt+1 lines in the t direction for each bezier patch.

Return value

None.

See also

[BezierSurface3D](#), [BSplineSurface2D](#), [HermitSurface3D](#)

Appendix A. BIBLIOGRAPHY

Gerald Farin,

Alan Watt,

Appendix B. COMMON QUESTIONS

Q. What is the difference between your MoveTo2D, LineTo2D and GDI's MoveTo, LineTo functions?

A. MoveTo2D and LineTo2D performs the transformation from the world coordinates to the viewport of the selected viewer. MoveTo and LineTo uses the screen coordinates. GDI has several screen mapping modes, but they are all simple scaling transformations. Visualib provides much more sophisticated viewing transformations. Another difference is that GDI functions use 16 bit integer type for coordinates which may easily cause overflow, while Visualib functions use float type.

Q. I just want to display some simple 2D graphics. How could Visualib help me?

A. GDI drawing functions have several limitations. For example, GDI Ellipse function can only draw ellipses with horizontal and vertical axes. Visualib lets you draw any kinds of ellipses with its powerful transformation capabilities.